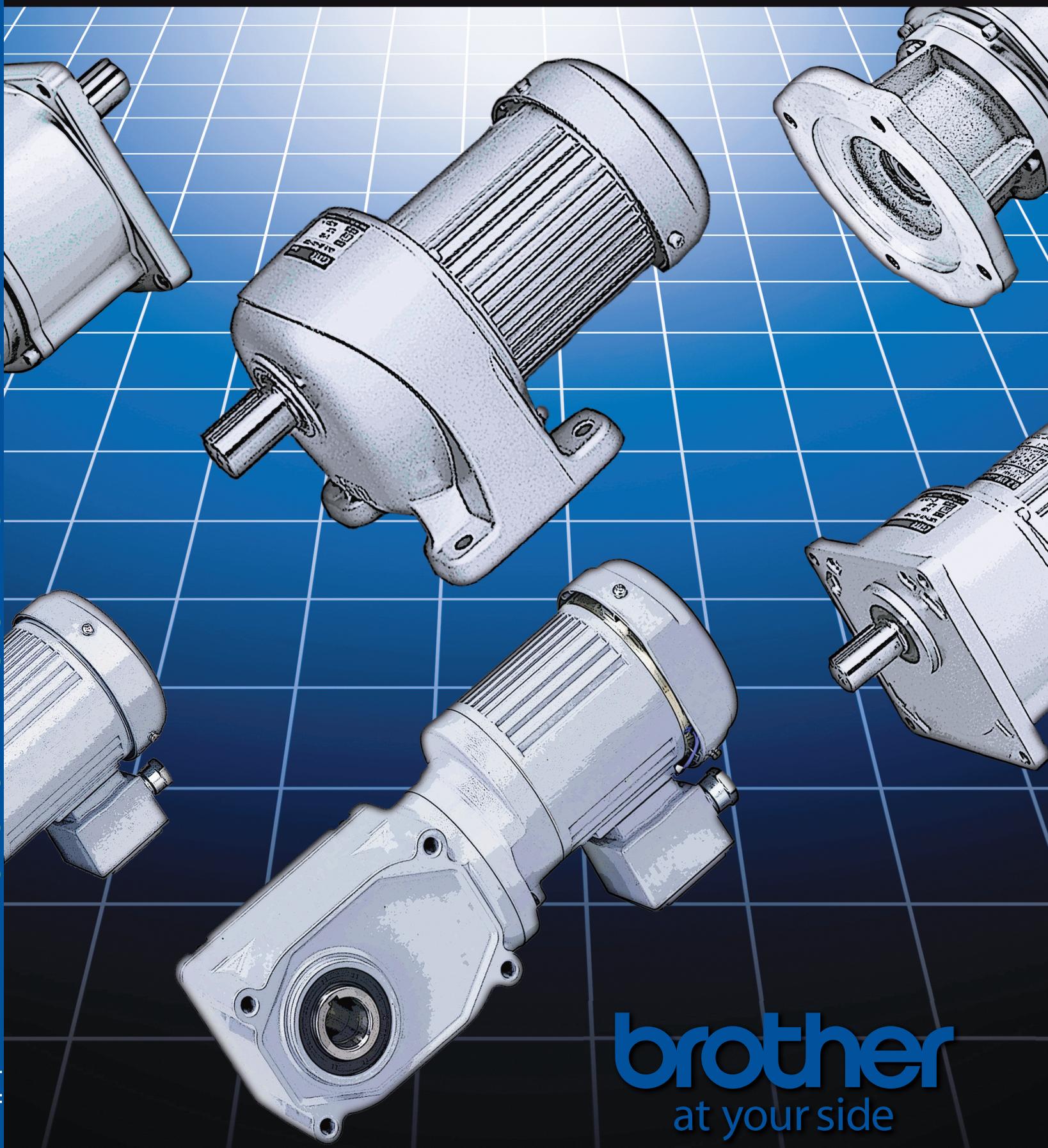


GTR MID SERIES GEARMOTORS

GTR MID SERIES GEARMOTORS

brother
at your side



brother
at your side

HELICAL IN-LINE & HYPOID/HELICAL RIGHT-ANGLE



program for boosting worldwide sales while providing quality products and superior customer service, the company aims to tighten the focus on core competencies and boost global competitiveness.

About Brother Gearmotors

The line of gearmotors and reducers, detailed in this catalog, is an example of advanced technology brought to industry by Brother. The GTR Series of gearmotors was designed in response to industrial demand for smaller, lighter, more reliable, and energy efficient power transmission. Our energy efficient High Ratio Hypoid right-angle gearing, CBN grinding process, and quality aluminum die cast housings are examples of superior technology brought to you by Brother.

Manufactured using the best machinery available in the World, Brother gears are processed on equipment by Gleason Pfauter, Mikron, Reishauer, Kashifiji, Koyo-Lindberg, and Zeiss. The quality equipment, fifty plus years of experience in gear manufacturing, combined with our commitment to advanced technology, make Brother second to none in gear and gearmotor manufacturing technology. We invite you to challenge us with your power transmission needs.

The Brother line of gearmotors offer more voltage choices, a wider range of mounting configurations and greater efficiency (for smaller drive packages).

With Brother Gearmotors, you can design a more efficient machine at a lower overall cost.

Our Helical and Hypoid gearmotors feature:

- Steel carbonitrided and die quenched gears which translates into longer life.
- A selection of 1/50 HP to 3 HP.
- 9 voltage choices in 50hz or 60hz.
- 28 ratio choices.
- Flexibility in mounting styles—with over 10 mounting configurations—helical in-line and hypoid right-angle.
- Hypoid gearing in our right-angle units is the same gearing used in an automobile differential—which allows Brother Gearmotors to boast the most efficient and durable right-angle package commercially available!
- European and other worldwide voltages are available.
- Lubricated for life with high grade synthetic grease and sealed with machine slip fit "O" rings eliminating costly downtime for lubrication changes!
- Two Year Warranty!

Design your machine around your goals, not your gearmotor.

Brother Gearmotors—your options are standard.

About Brother

Brother International Corporation, with its corporate headquarters located in Bridgewater, NJ, was established in the U.S. on April 21, 1954. Brother markets many industrial products, home appliances, and business products manufactured by its parent company, Brother Industries, Ltd. of Nagoya, Japan. Currently, Brother and its subsidiaries employ over 1,100 people in the Americas and recorded consolidated net sales of \$1.5 billion for the fiscal year ending December 2008.

Brother Industries Ltd. began manufacturing sewing machines in 1928 and took its present corporate form in 1934 as a multinational, diversified sales, distribution, engineering and manufacturing company. With an aggressive

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Mid Type G3 In-line Torque Table (in-lb) (Frame / Torque)

Ratio	RPM	1/8 Hp	1/4 Hp	1/2 Hp	1 Hp	2 Hp	3 Hp
5	360	22.5	45	89	167	338	494
10	180	44	89	178	335	668	980
15	120	67	18	134	22	502	1006
20	90	86.7	18	178	268	32	1474
25	72	113	223	233	357	40	1959
30	60	130	268	535	1004	40	2454
40	45	173	346	691	1296	40	2939
50	36	217	432	864	1620	40	3797
60	30	260	519	1037	1944	40	4751
80	22.5	346	691	1383	2593	50	5696
100	18	432	864	1728	3241	50	7595
120	15	519	1037	2074	3889	50	9537
160	11.2	691	1383	2765	5185	50	10317
200	9	864	1728	3457	6481	50	10838
300	6	1155	2311	4621	8665		
375	4.8	1444	2888	40	5777	50	10832
450	4	1733	3466	6770	6770	50	10850
600	3	2311	4621	9243			
750	2.4	2888	5777	40	10850		
900	2	3466	6770	50	10850		
1200	1.5	3819	6770	50	10850		

Foot Mount	Flange Mount	Description
		1/8 ~3 Hp 5:1~200:1 3 Ph Std 3 Ph IP-65 1 Ph Std Optional Brake Pages 18~27
		1/8 ~1 Hp 300:1~1200:1 3 Ph Std 3 Ph IP-65 1 Ph Std Optional Brake Pages 18~25
		1/4 ~1 Hp 5:1~200:1 NEMA 56C Pages 28~29

Mid Type H2 Rt-Angle Torque Table (in-lb) (Frame / Torque)

Ratio	RPM	1/8 Hp	1/4 Hp	1/2 Hp	1 Hp	2 Hp	3 Hp
5	360	21	42	85	159	321	468
10	170	42	85	169	317	633	928
15	120	63	127	254	476	954	1396
20	90	85	169	338	634	1266	1855
25	72	106	211	423	32	40	2324
30	60	127	254	507	951	1899	2783
40	45	169	338	676	1268	2454	3563
50	36	211	423	845	1585	3061	4491
60	30	254	507	1014	1902	3676	5384
80	22.5	328	654	1308	2452	4899	7187
100	18	410	817	1634	3065	6121	9017
120	15	491	981	1961	3677	7343	10751
160	11.2	655	1308	2615	4903	9797	
200	9	819	1634	3269	6129	10838	
240	7.5	983	1961	3819	6770	10838	
300	6	1069	2170	4227	7926		
375	4.8	1336	2712	40	5284	50	9908
450	4	1603	3255	6341	6341	50	10850
600	3	2113	4339	8455			
750	2.4	2642	5424	10568			
900	2	3170	6509	10850			
1200	1.5	3819	6770	10850			
1500	1.2	3818					

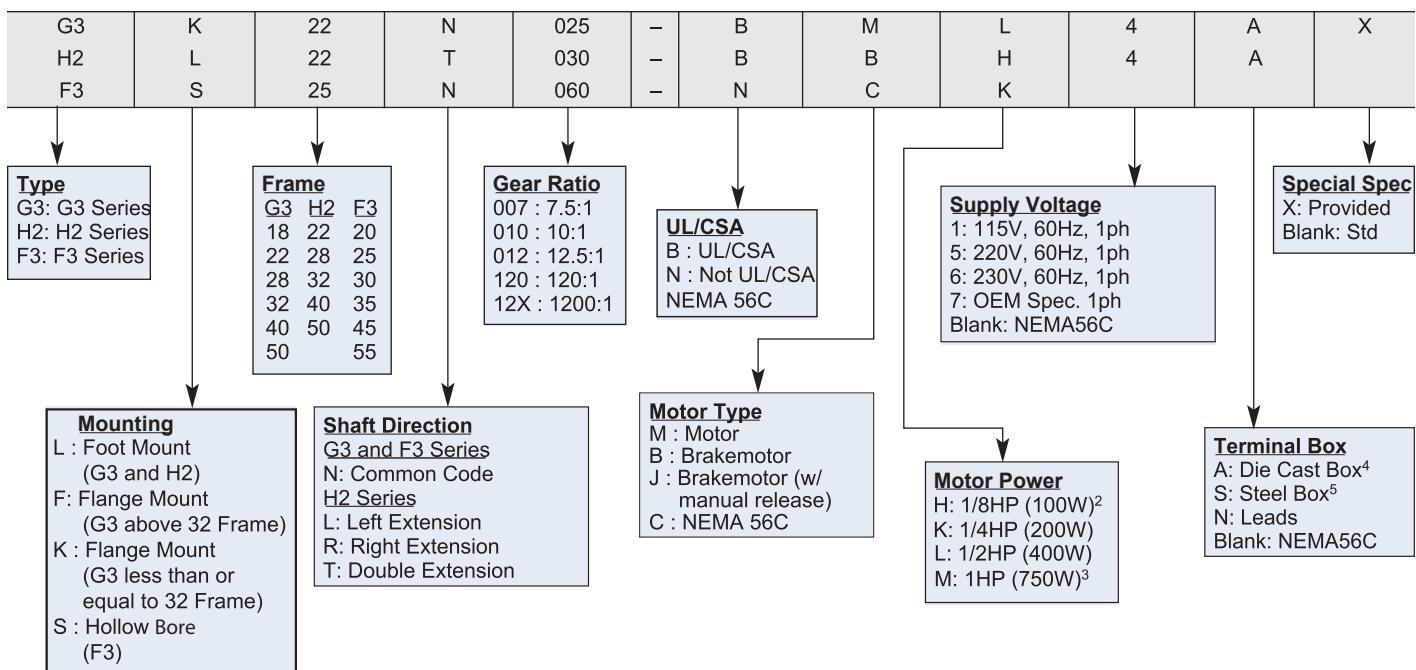
Foot Mount	Description
	1/8 ~3 Hp 5:1~240:1 3 Ph Std 3 Ph IP-65 1 Ph Std Optional Brake Pages 30~39
	1/8 ~1 Hp 300:1~1500:1 3 Ph Std 3 Ph IP-65 1 Ph Std Optional Brake Pages 30~37
	1/4 ~1 Hp 5:1~200:1 NEMA 56C Pages 40~41

Mid Type F3 Rt-Angle Hollow Bore Torque Table (in-lb) (Frame / Torque)

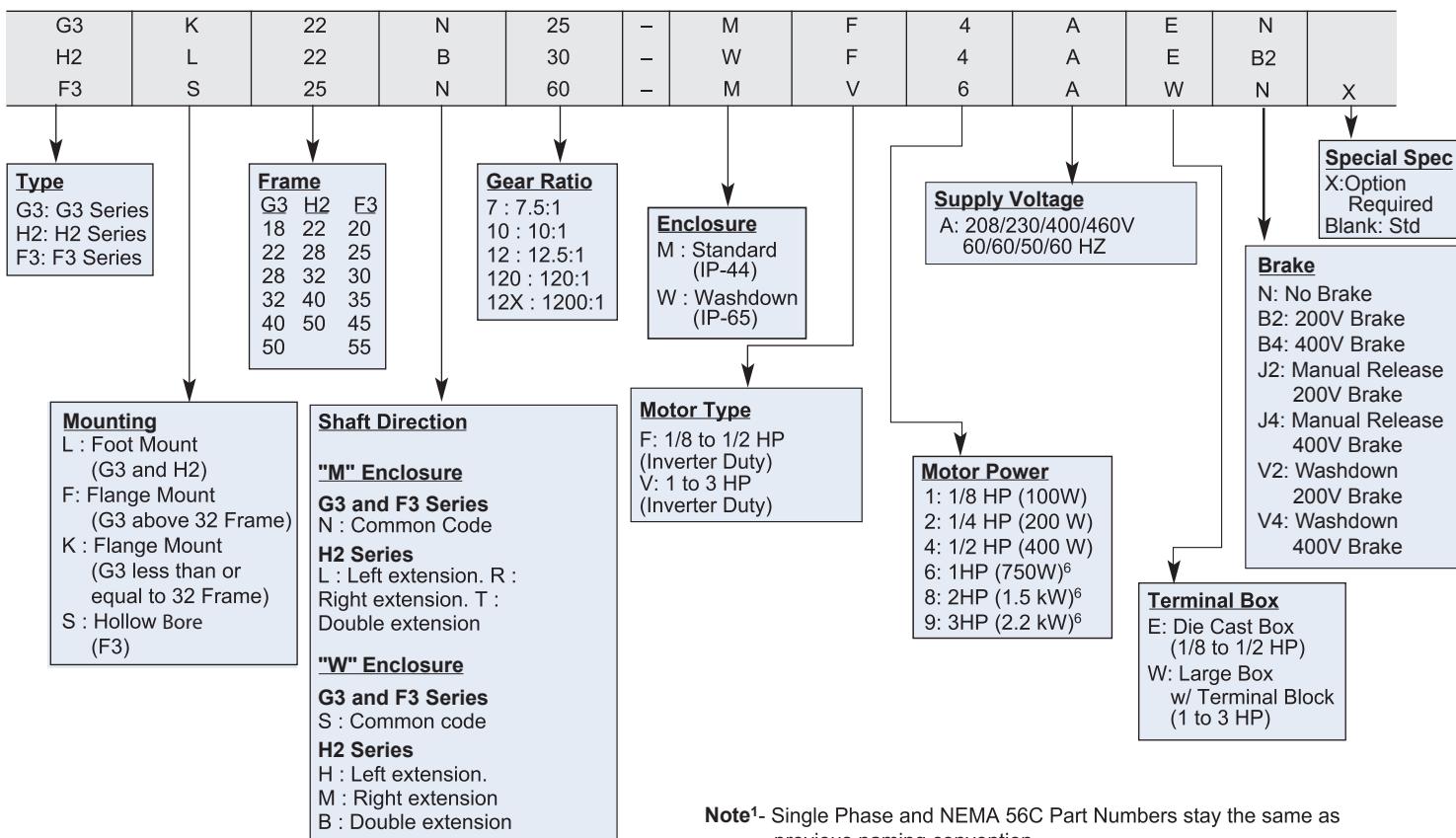
Ratio	RPM	1/8 Hp	1/4 Hp	1/2 Hp	1 Hp	2 Hp	3 Hp
5	360	19	40	81	159	300	451
7.5	240	28	61	123	221	460	672
10	170	38	81	168	300	619	902
12.5	144	47	106	212	380	761	1115
15	120	57	123	238	460	920	1345
20	90	76	168	327	619	1221	1796
25	72	97	212	407	761	1531	2248
30	60	115	238	486	920	1841	2699
40	45	159	327	654	1221	2442	3593
50	36	194	407	814	1531	3053	4496
60	30	221	486	982	1841	3682	5390
80	22.5	283	628	1239	2327	4655	6824
100	18	362	770	1548	2903	5823	8532
120	15	433	929	1867	3496	6983	10231
160	11.2	584	1239	2389	4655	9284	
200	9	716	1548	2389	4903	11187	
240	7.5	867	1628	2389	4903	11187	
300	6	973	2079	4168	55	7824	
375	4.8	1212	2602	5213			
450	4	1460	3124	6257			
600	3	1832	45	3947	8346		
750	2.4	2292	4930				
900	2	2956	6257				
1200	1.5	3938	55	8346			
1500	1.2	55	5213				

Shaft/Flange Mount	Description
	1/8 ~3 Hp 5:1~240:1 3 Ph Std 3 Ph IP-65 1 Ph Std Optional Brake Pages 42~51
	1/8 ~1 Hp 300:1~1500:1 3 Ph Std 3 Ph IP-65 1 Ph Std Optional Brake Pages 42~49
	1/4 ~1 Hp 5:1~240:1 NEMA 56C Pages 52~53

Single Phase Gearmotors & NEMA 56C Reducers



Three Phase-Inverter Duty Gearmotors



Note¹- Single Phase and NEMA 56C Part Numbers stay the same as previous naming convention

Note²- Not available in a 56C Reducer

Note³- Not available in a Single Phase Gearmotor

Note⁴- For 1/8 and 1/4HP Single Phase Models

Note⁵- For 1/2HP Single Phase Models

Note⁶- 1, 2, and 3 HP Motors meet IE3 Efficiency Standards

The New Brother Gearmotor Part Number System

In order to better accommodate third party listing issues (UL/CSA and CCC), as well as USA and International compliance issues, Brother has changed their Gearmotor part numbering system. This new part numbering system will more readily be in compliance with the new international standards, such as CCC.

3 Phase Nomenclature Crossover (Gearhead)

Comment	Same Basic Position	Same Basic Position	Same Basic Position	Same Basic Position with Added Options	Part Numbers no longer need "0's in front for smaller ratios
---------	---------------------	---------------------	---------------------	--	--

Old P/N Description	G3	K	28	N	025
	Type	Mounting	Frame	Shaft Direction	Gear Ratio
G3: G3 Series	L: Foot Motor (G3 and H2)	G3	H2	F3	G3 and F3 Series
H2: H2 Series		18	22	20	N: Common Code
F3: F3 Series	F: Flange Mount (G3 above 32 Frame)	22	28	25	H2 Series
	K: Flange Mount (G3 up to and including 32 Frame)	28	32	30	L: Left extension
		32	40	35	R: Right Extension
	S: Hollow Shaft (F3)	40	50	45	T: Double Extension
		50		50	
				55	

New P/N Description	G3	K	28	N	25
	Type	Mounting	Frame	Shaft Direction	Gear Ratio
G3: G3 Series	L: Foot Motor (G3 and H2)	G3	H2	F3	"M" Enclosure
H2: H2 Series	F: Flange Mount (G3 above 32 Frame)	18	22	20	G3 and F3 Series
F3: F3 Series	K: Flange Mount (G3 less than or equal 32 Frame)	22	28	25	N: Common Code
		28	32	30	H2 Series
	S: Hollow Bore (F3)	32	40	35	L: Left Extension
		40	50	45	R: Right Extension
		50		55	T: Double extension
					"W" Enclosure
					G3 and F3 Series
					S: Common Code
					H2 Series
					H: Left Extension
					R: Right Extension
					B: Double Extension

3 Phase Nomenclature Crossover (Motor)

Removed from the part number since all models will have UL	Motor Type has been split into 3 (Enclosure, Motor, Brake & Options)	Changed HP Codes	Changed Voltage Codes	Only the "E" and "W" Boxes will be available	Same Basic Position
--	--	------------------	-----------------------	--	---------------------

Old P/N Description	B	M	M	4	S	X	
	UL/CSA	Motor Type	Motor Power	Supply Voltage	Terminal Box	Special Spec	
	B: UL/CSA	M: Motor B: Brakemotor J: Brakemotor (w/ manual release) WM: Motor (IP-65) WB: Brakemotor (IP-65)	H: 1/8HP (100W) K: 1/4HP (200W) L: 1/2HP (400W) M: 1HP (750W) P: 2HP (1500W) R: 3HP (2200W)	4: 208/230/460V, 60Hz, 3ph 8: OEM Spec. 3ph	A: Die Cast Box B: Die Cast Box S: Steel Box N: Leads		
						X: Option Required Blank: Standard	
New P/N Description	M	V	6	A	W	N	X
	Enclosure	Motor Type	Motor Power	Supply Voltage	Terminal Box	Brake	Special Spec
	M: Standard (IP-44) W: Washdown (IP-65)	F: 1/8 to 1/2 HP (Inverter Duty) V: 1 to 3HP (Inverter Duty)	1: 1/8HP (100W) 2: 1/4HP (200W) 4: 1/2HP (400W) 6: 1HP (750W) 8: 2HP (1.5kW) 9: 3HP (2.2kW)	A: 208/230/400/460V, 60/60/50/60Hz	E: Die Cast Box (1/8 to 1/2 HP) W: Large Box w/ Terminal Block (1 to 3 HP)	N: No Brake B2: 200V Brake B4: 400V Brake J2: Manual Release 200V Brake J4: Manual Release 400V Brake V2: Washdown 200V Brake V4: Washdown 400V Brake	X: Option Required Blank: Standard

What Changed?

We have separated the gear reducer indicators before the "dash" and the motor indicators after the "dash". To better illustrate, we have shown an example (above) of the how to convert the old part number to the new part number.

In-Line Gearmotors

- Lightweight and Compact
- Longer Life
- Low-Noise Brake
- Maintenance Free
- Mounting in Any Direction
- Brother Helical Gearing

Lightweight and Compact

Die cast aluminum gear housings and motors make Brother gearmotors and reducers light in weight, allowing engineers to design more economical mounting provisions.

Longer Life

Compared to a spur gear of approximately the same pitch diameter, Helical gears can transfer higher loads at greater speeds. This is due to the gradual engagement of the teeth and smooth transfer of the load. Size for size Brother all Helical gearmotors will out perform the competition.

Low-Noise Brake

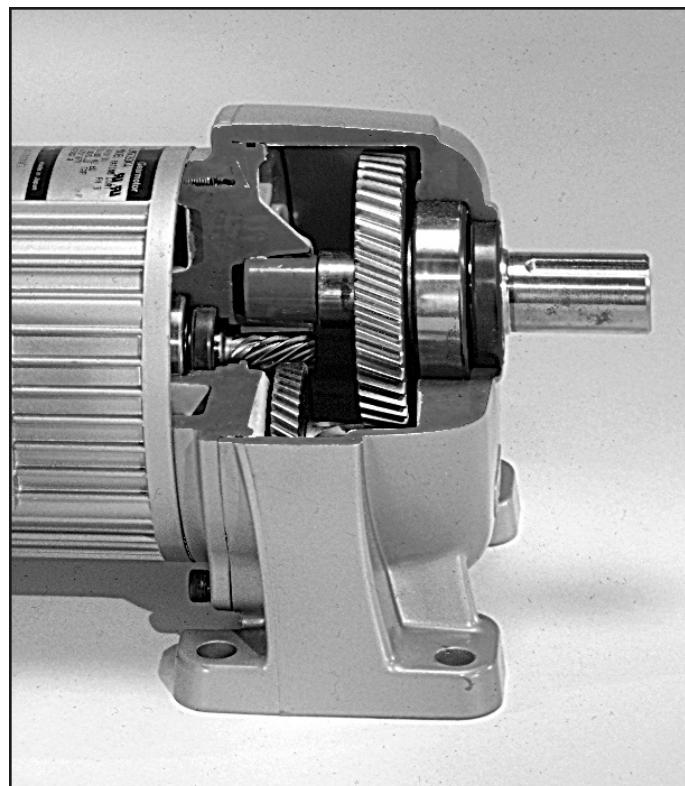
The brake system developed exclusively by Brother uses vibration damping sheet steel for the armature, which dramatically reduces noise associated with the brake.

Maintenance Free

High-quality synthetic grease is used in all Brother gearboxes. They are filled at the factory and do not require maintenance filling or level checks. This saves valuable time at set-up and eliminates concern for costly oil disposal required by the EPA!

Mounting in Any Direction

Brother gearboxes are sealed with machine "slip" fit "O" rings and double lip spring shaft seals on both the motor input shaft and output drive shaft. Thus, they can be mounted in any conceivable direction without concern for the position of a breather plug.



Brother Helical Gearing

As the world's largest fine pitch gear manufacturer, Brother provides all Helical gearing for in-line designs. Gears are made of chromium molybdenum steel that has undergone precision carbonitriding. Brother Helical gears out-perform spur gears by a great margin as shown in the chart below. Most of our competition use a combination of Spur/Helical.

Spur vs. Helical Gear Comparison

Condition	Same Load Rating, 1800 RPM Speed Ratio 1:1 Based on Bending Moment Strength		
Gear Type	Spur Gear	Spur Gear	Helical Gear
Material	S-45C	S45C	SCM415
Hardness/ Heat Treatment	None (typical for Spur type gear)	HRC 50	HRC 60
Helix Angle	0	0	15°
Size Ratios			
Size Comparison	113% Larger	82% Larger	Reference

Diagrams and size comparisons reveal that a Spur type gear must be significantly larger to have the same load capacity as the Helical gear.

Right-Angle Gearmotors

- Longer Life
- High Reductions/Small Size
- Mounting in Any Direction
- Lightweight and Compact
- Low-Noise Brake
- Maintenance Free
- Brother Hypoid Gearing

Longer Life

Brother Hypoid gearmotors and reducers use hardened steel gears throughout. This gives Hypoid gearing far superior wear life compared to worm gears which use softer bronze on the output gear.

High Reductions/Small Size

Brother offers reductions up to 1500:1 in most sizes. Hypoid gearing makes our high reductions significantly more compact and light weight compared to worm/worm and helical/worm designs.

Mounting in Any Direction

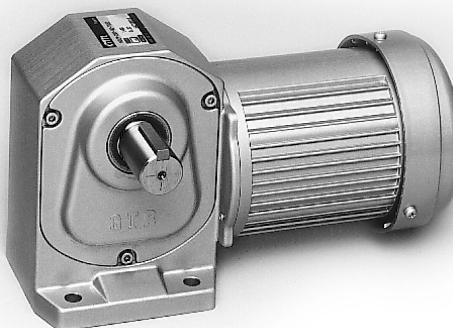
Brother gearboxes are sealed with machine "slip" fit "o" rings and double lip spring shaft seals on both the motor input shaft and output drive shaft. They do not require breather plugs or expansion bladders. They can be mounted in any conceivable direction without concern for lubrication leakage.

Lightweight and Compact

Die cast aluminum gearmotors and reducers are light in weight allowing engineers to design more economical mounting provisions.

Low-Noise Brake

The brake system developed exclusively by Brother, uses vibration damping sheet steel for the armature, which dramatically reduces noise associated with the brake.



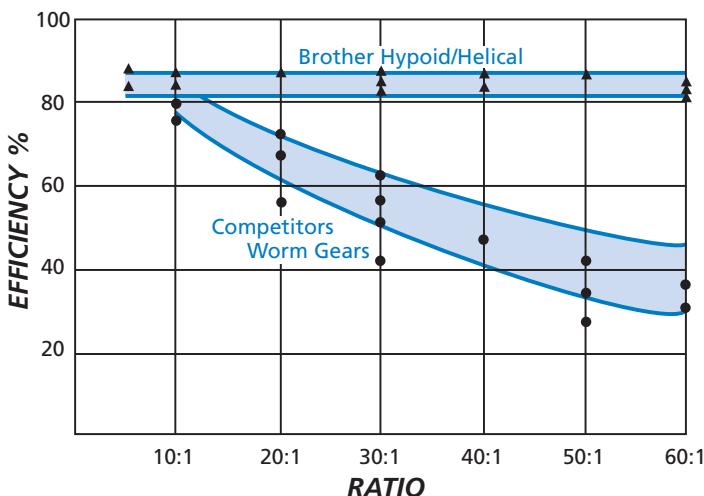
Maintenance Free

High-quality synthetic grease is used in all Brother gearboxes. It is filled at the factory and does not require maintenance filling or level checks. This saves valuable set-up and maintenance time compared to worm gear boxes. With no oil changes required, there is less concern for the costly disposal of oil as required by the EPA.

Brother Hypoid Gearing

As the world's largest fine pitch gear manufacturer, Brother provides highly efficient Hypoid gearing in all right-angle designs. Gears are made of chromium molybdenum steel that has undergone precision carbonitriding. The superior efficiency, gear materials, and heat treatment allows engineers to design-in the most compact gearmotor per output torque.

Gearbox Efficiency Comparison – Right-Angle Hypoid/Helical vs. Worm Gear



Input Speed – 1800 RPM

Hypoid – Grease Lubrication

Worm – Oil Lubrication

The graph at left shows actual measured efficiency, 1/4 Hp to 3 Hp.

Because of the high efficiency of the Hypoid/Helical combination, there is no self-locking in the back drive direction.

Big Energy Savings, Smaller Motor Hp Input

Due to the superior efficiency, it is often possible to replace worm gearbox/motor combination with a smaller Hp input in a Hypoid and actually receive greater torque at the driven shaft. Also, with smaller motor Hp, less electrical current is required, resulting in big savings on electric bills.

Industry Leader

Brother is the pioneer and leading manufacturer of Hypoid Bevel gearmotors. This unique right-angle type gearmotor has much higher power transmission efficiency than conventional worm gears. Growing demand is due to its COMPACTNESS, HIGH EFFICIENCY, and superior wear life, which meet the latest primary requirements for industrial applications.

Mid Series AC Gearmotors & Reducers

Mid G3**Gearing:** 100% Hardened steel helical gearing

Helical gearing runs quieter and provides greater torque and shock load capacity than competitive spur/helical selectively hardened combinations.

Bearings: Ball (Output shaft ball/sleeve comb.)

Premium ball bearings provide quiet efficient torque transfer and high overhung load capacity.

Lubricant: High grade synthetic grease

Synthetic grease provides extended lubrication life over a wide temperature range. The viscosity resists leakage and does not require breather holes.

Shaft seals: NBR Rubber, lip type spring loaded

Provides a good seal over a wide range of operating temperatures.

Housing seals: Machine "slip-fit" O ring.

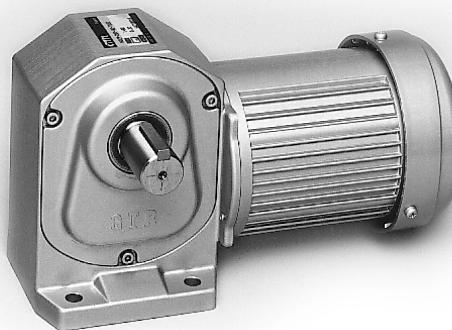
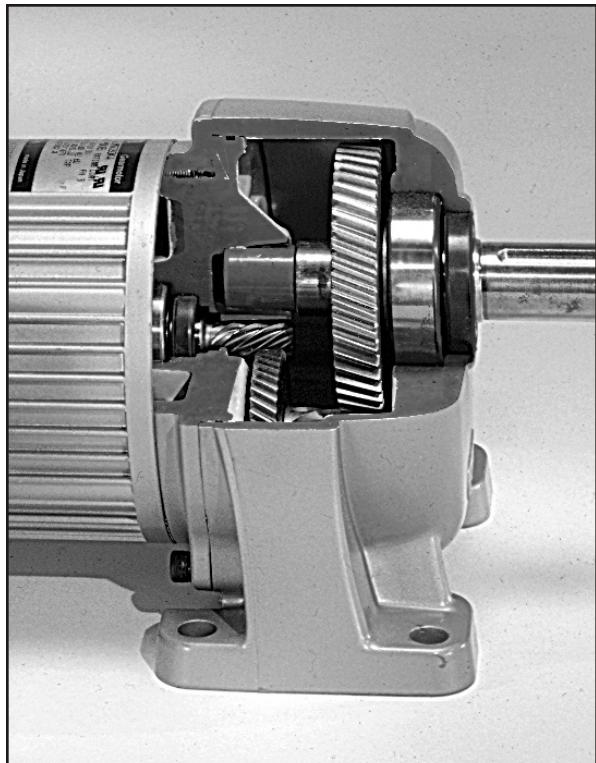
O ring seals provide a longer and more reliable housing seal compared to competitive gasket sealed housings.

Mounting: Universal mounting in any position and at any angle!

The combination of synthetic grease, NBR shaft seals, O ring housing seals, and the lack of breather holes allows for fast, safe mounting in any position.

Housing: Die cast aluminum

Aluminum is light weight, corrosion resistant, and provides good heat dissipation, strength and durability.

**Mid H2** ▲**Gearing:** 100% Hardened steel Hypoid/Helical gearing

Hypoid gearing is up to 80% more efficient than competitive worm gears. The Brother all steel Hypoid/Helical combination has much better wear properties than softer bronze worm gearing. Brother Hypoid gearmotors last longer!

Hypoid gearing runs cooler than worm gears.

Bearings: Premium Ball

Premium ball bearings provide quiet efficient torque transfer and high overhung load capacity.

Lubricant: High grade synthetic grease

Synthetic grease provides extended lubrication life over a wide temperature range. The viscosity resists leakage and does not require breather holes.

Shaft seals: NBR Rubber, lip type spring loaded

Provides a good seal over a wide range of operating temperatures.

Housing seals: Machine "slip-fit" O ring

O ring seals provide a longer and more reliable housing seal compared to competitive gasket sealed housings.

Mounting: Universal mounting in any position and at any angle!

The combination of synthetic grease, NBR shaft seals, O ring housing seals, and the lack of breather holes allows for fast, safe mounting in any position.

Housing: Die cast aluminum

Aluminum is light weight, corrosion resistant, and provides good heat dissipation, strength and durability.

Mid F3

Gearing: 100% Hardened steel Hypoid/Helical gearing

Hypoid gearing is up to 80% more efficient than competitive worm gears. The Brother all steel Hypoid/Helical combination has much better wear properties than softer bronze worm gearing. Brother Hypoid gearmotors last longer!

Hypoid gearing runs cooler than worm gears.

Bearings: Premium Ball

Premium ball bearings provide quiet efficient torque transfer and high overhung load capacity.

Lubricant: High grade synthetic grease

Synthetic grease provides extended lubrication life over a wide temperature range. The viscosity resists leakage and does not require breather holes.

Shaft seals: NBR Rubber, lip type spring loaded

Provides a good seal over a wide range of operating temperatures.

Housing seals: Machine "slip-fit" O ring

O ring seals provide a longer and more reliable housing seal compared to competitive gasket sealed housings.

Mounting: Universal mounting in any position and at any angle!

The combination of synthetic grease, NBR shaft seals, O ring housing seals, and the lack of breather holes allows for fast, safe mounting in any position. The design of the gearmotor flange allows for shaft or flange mounting for simple and clean appearance.

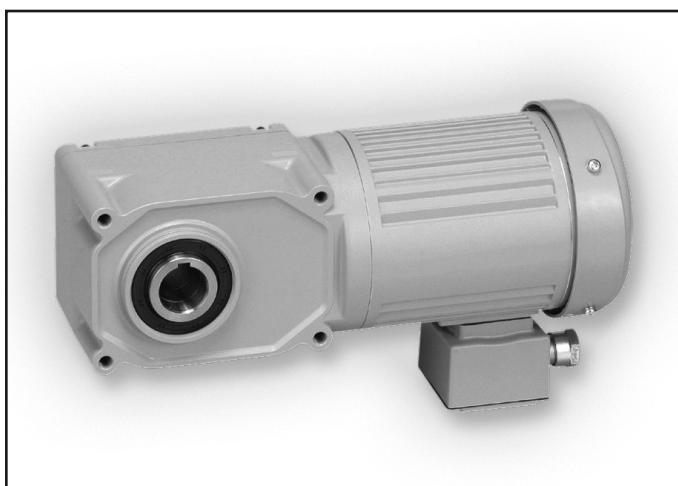
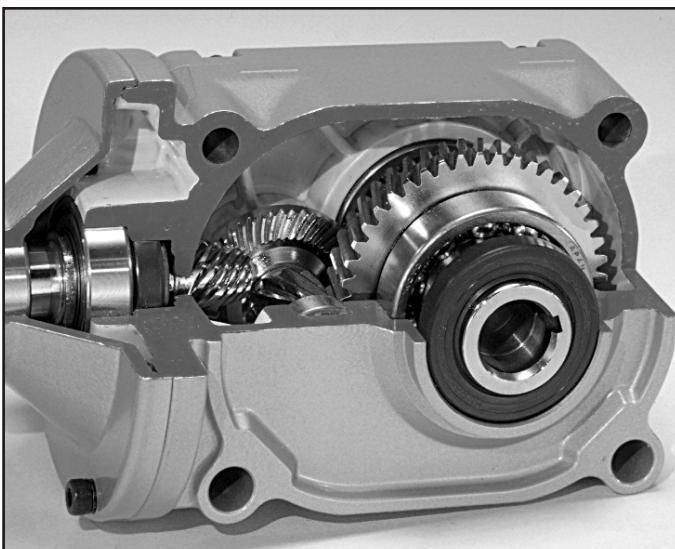
Eliminate Chain/Sprockets

The F3 type gearmotors and reducers are ideal for eliminating chain and sprocket assemblies which are unsafe, cumbersome, and a maintenance hassle. In contrast to traditional worm gears, with the high efficiency Brother Hypoid/Helical combination you can maintain a compact drive package at higher ratios.

By flange mounting the F3 product it can be used as the support bearing for one side of a conveyor pulley. This can save assembly time, material costs, and present a clean modern appearance to the end product.

Housing: Die cast aluminum

Aluminum is light weight, corrosion resistant, and provides good heat dissipation, strength and durability.



IP-65

Brother IP-65 washdown gearmotors offer superior resistance to water ingress and superior resistance to harsh chemicals used in food processing plants.

- Designed to keep water out, they outlast the competition!
- Protected against pressure jets of water
- Totally protected against dust
- Terminal Boxes are specially designed, sealed and gasketed. Complete with stainless steel IP-65 cord grip.

When placing an order be sure to specify a "WM" or "WB" type motor.

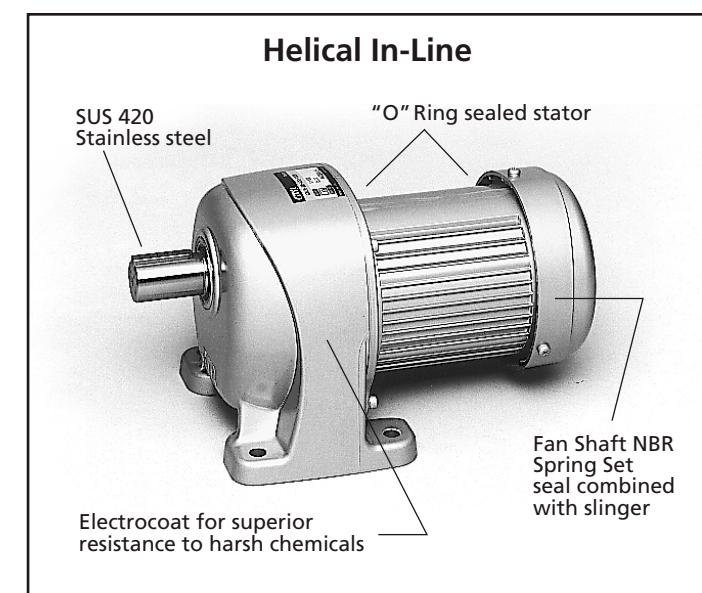
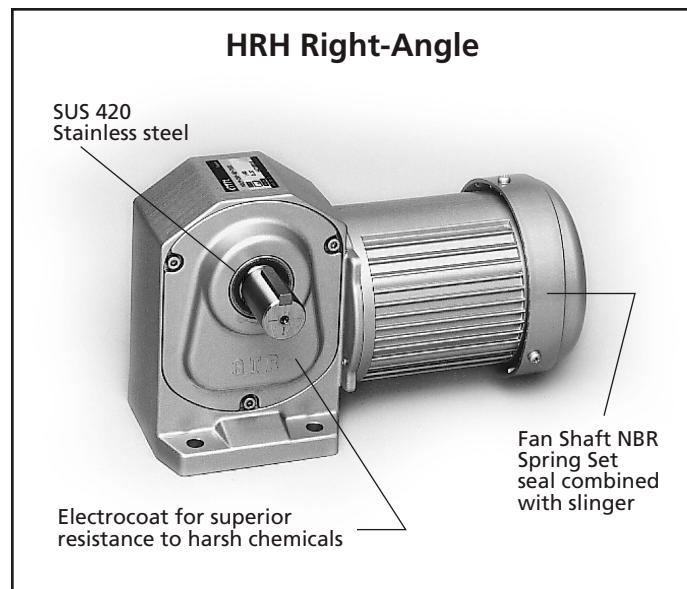
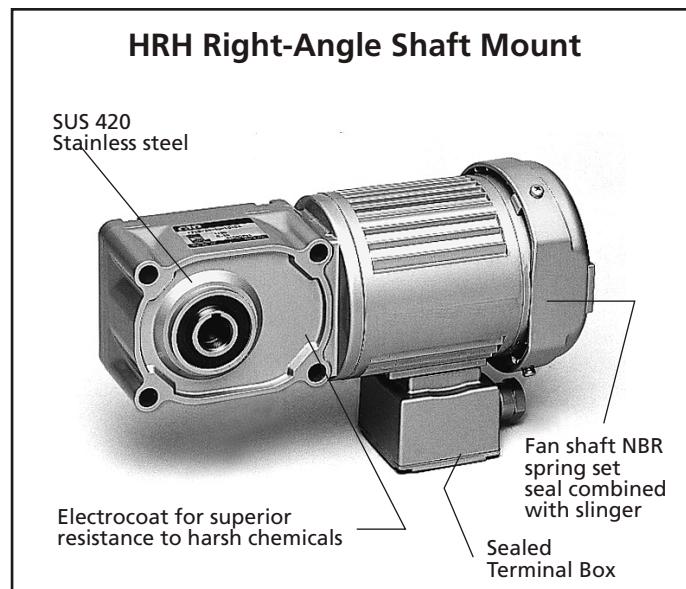
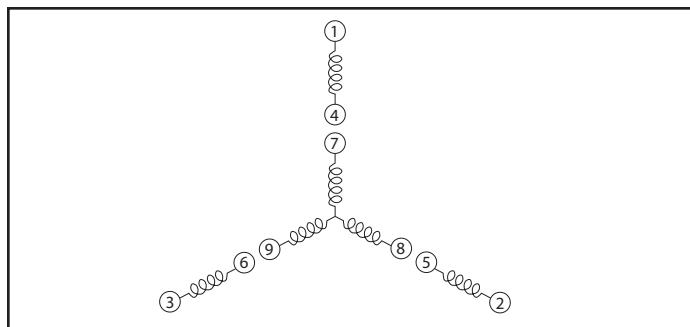
Helical In-Line**HRH Right-Angle****HRH Right-Angle Shaft Mount**

Fig. 1.1: 1/8, 1/4, 1/2, 1 Hp

Three Phase Voltages



Line	208/230V		460V	
	Lead Label		Lead Label	
L1	1	7	4	
L2	2	8	5	
L3	3	9	6	

Fig 1.2 UL/CSA/CE/RoHS

Voltage	Horsepower	UL/cUL File No.	RoHS	CE Details
Three Phase	1/8 Hp, 1/4 Hp, 1/2 Hp 1 Hp, 2 Hp, 3 Hp	E172017	Yes	Low Voltage Directive 73/23/EEC EN Standards: EN60034-1 (Regulations on motors in general)
Single Phase	1/4 Hp, 1/2 Hp	E172017	Yes	
Single Phase	1/8 Hp	E153713	Yes	

Notes:

1. Motors in File E172017 comply to UL1004 Standard for Safety Electric Motors.
2. Motors in UL File E153713 comply to UL2111 Overheating Protection for Motors.
3. Products bear the UL component recognition marking for UL and cUL (CSA).
4. Products with the cUL marking comply with CSA standards and can be legally sold in Canada.
5. Products bear the CE marking on the namplate.

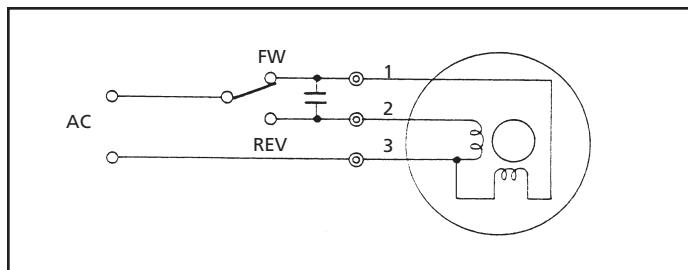
Table 1.1: Three Phase 1/8, 1/4, 1/2, 1, 2, 3 Hp Motors

Horsepower	Voltage (V)	Frequency (Hz)	Full Load Current (A)	Full Load (RPM)	Starts Per Minute
1/8 Hp	208	60	0.56	1710	10
	230	60	0.57	1730	
	400	50	0.31	1410	
	460	60	0.29	1730	
1/4 Hp	208	60	1.00	1700	10
	230	60	1.00	1720	
	400	50	0.56	1400	
	460	60	0.50	1720	
1/2 Hp	208	60	1.80	1700	10
	230	60	1.80	1720	
	400	50	1.00	1400	
	460	60	0.90	1720	
1 Hp	208	60	2.9	1740	10
	230	60	2.8	1750	
	400	50	1.60	1450	
	460	60	1.40	1750	
2 Hp	208	60	5.9	1750	10
	230	60	5.7	1760	
	400	50	3.2	1460	
	460	60	2.9	1760	
3 Hp	208	60	8.3	1760	10
	230	60	7.9	1770	
	400	50	4.5	1470	
	460	60	4.0	1770	

Table 1.2: Single Phase 1/8, 1/4, 1/2 Hp Motors

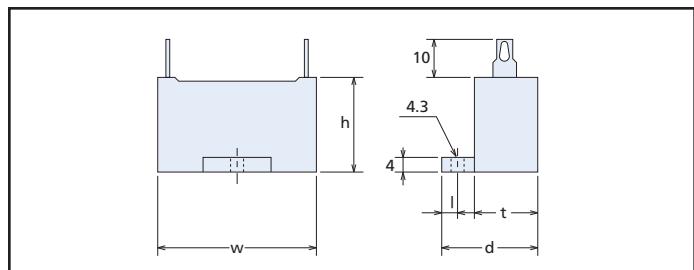
Horsepower	Motor Type	Voltage (V)	Frequency (Hz)	Full Load Current (A)	Full Load (RPM)	Capacitor (included with Gearmotor) mFD
1/8 Hp	Capacitor Run	115	60	1.50	1730	24
		220	60	0.75	1720	6
		230	60	0.75	1730	6
1/4 Hp	Capacitor Start	115	50	4.50	1420	250
		220	50	2.20	1410	250
		230	50	2.30	1420	250
		115	60	4	1700	250
		220	60	2.00	1690	250
		230	60	2.00	1700	250
1/2 Hp	Capacitor Start	115	50	7.40	1440	250
		220	50	3.70	1440	250
		230	50	3.70	1440	250
		115	60	6.70	1730	250
		220	60	3.50	1730	250
		230	60	3.40	1730	250

**Fig. 1.5: 1/8 Hp
Single Phase Voltages**



Wire	Color Code 115V	Color Code 220V, 230V
1	Blue	Brown
2	Black	Black
3	Grey	Grey

**Fig. 1.6:
Capacitors for 1/8 Hp Single Phase**



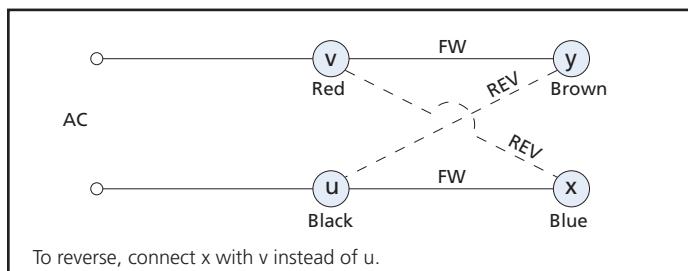
1/8 Hp Single Phase Motor Capacitors

Part No.	mFd	Volts*	W	h	t	d	I
C24M220V	24	220V *	2.28	1.46	0.93	1.52	0.28
C6.0M440V	6	440V **	2.28	1.61	1.14	1.73	0.28

* 220V Capacitors are for operation with 115V Motors

** 440V Capacitors are for operation with 220V or 230V motors.

**Fig. 1.7: 1/4, 1/2 Hp
Single Phase Voltage 115V**



**Fig. 1.8: 1/4, 1/2 Hp
Single Phase Voltage 220, 230V**

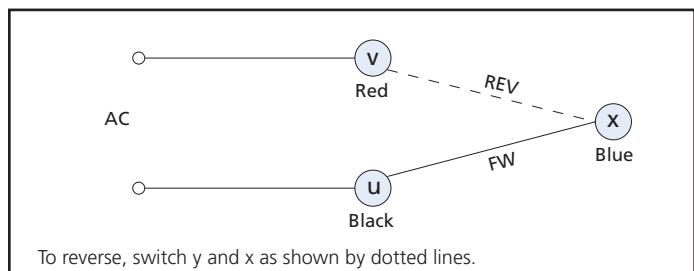
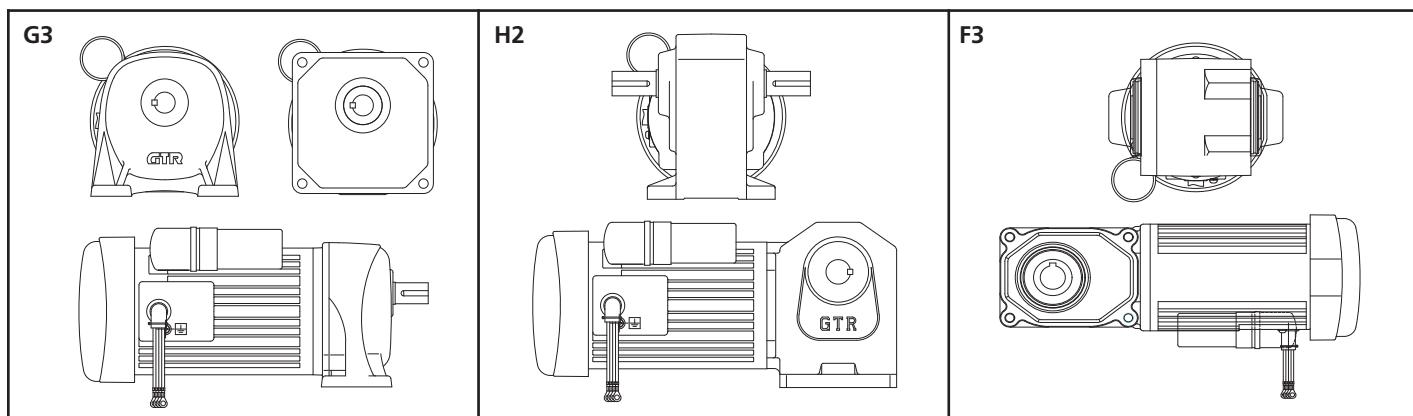


Fig 1.9 1/4 and 1/2 Hp Capacitor Start Models



Notes:

- These are capacitor start gearmotors using a governor switch to cut-out the starting capacitor.
- For specific dimensions please consult Brother. Drawings are also available at www.BrotherGearmotors.com

Table 1.3: Brake Data G3, H2, F3 Mid Type 1/8 to 3 Hp Three and Single Phase Standard

Horsepower	1/8 Hp	1/4 Hp	1/2 Hp	1 Hp	2 Hp	3 Hp	1/8 Hp	1/4 Hp	1/2 Hp
Motor Phase	Three Phase						Single Phase		
Brake Type	Power Off-Brake On, Spring Close								
Static Friction Torque (in-lb) ¹	8.67	17.35	34.70	65	130	191	8.67	17.35	34.70
Dynamic Friction Torque (in-lb) ¹	6.90	13.90	27.79	52	104	152	6.90	13.90	27.79
Voltage DC (Average) (VDC)	100V Class	-					90 VDC (Rectifier A100-D90: Included with Gearmotor)		
	200V Class	90 VDC (Rectifier A200-D90: Included with Gearmotor)					90 VDC (Rectifier A200-D90: Included with Gearmotor)		
	400V Class	180 VDC (Rectifier A400-D180: Included with Gearmotor)					-		
Power (@ 75C) (W)	100V Class	-					14	14	24
	200V Class	14	14	16	24	37	14	14	16
	400V Class	14	14	17	26	41	41	-	
Current (@ 75C) (A)	100V Class	-					0.15	0.15	0.27
	200V Class	0.15	0.15	0.18	0.27	0.41	0.41	0.15	0.18
	400V Class	0.08	0.08	0.09	0.14	0.23	0.23	-	
Allowable Total Work Emax (in-lb)	1.3×10^9	1.3×10^9	1.3×10^9	3.47×10^9	5.2×10^9	5.2×10^9	1.3×10^9	1.3×10^9	3.47×10^9
Allowable Braking Frequency (times/minute) ²	10/min						6/min		

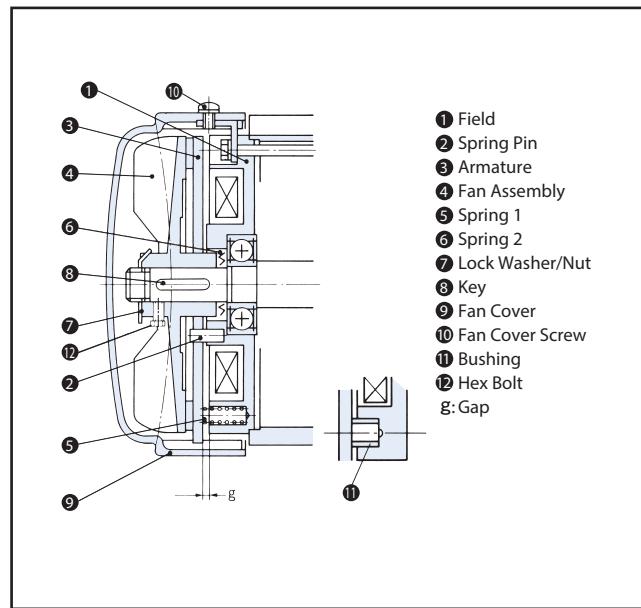
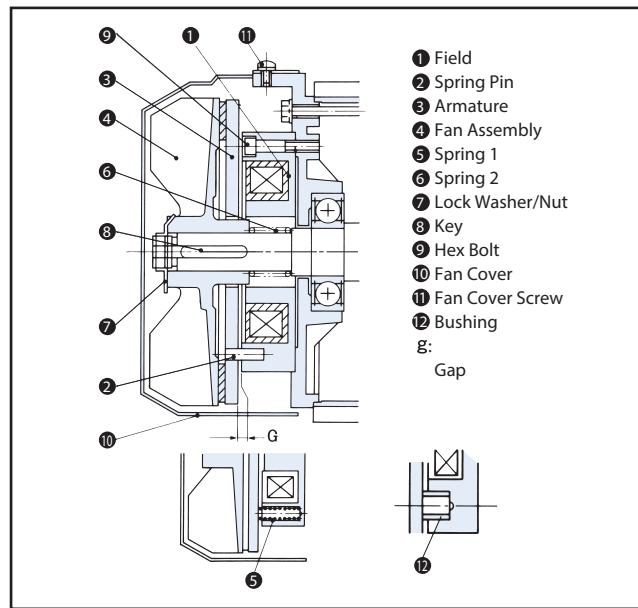
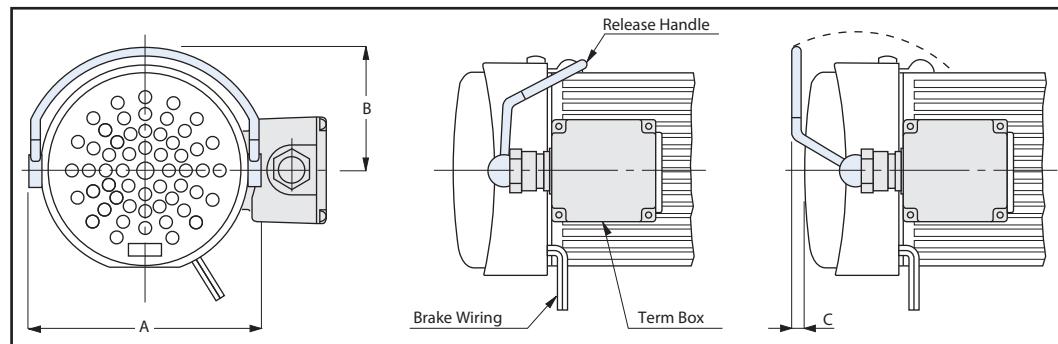
¹Target value.²Used as a reference value only. Can increase or decreased based on the application.Fig. 1.10: G3, H2, F3 Mid Type
1/8 to 1/2 Hp Three Phase and Single PhaseFig. 1.11: G3, H2, F3 Mid Type
1 to 3 Hp Three Phase

Fig. 1.12: Manual Brake Release



Note: Manual Brake release is optional and must be specified on your order.

Table 1.4:
Manual Release Dimensions

Dim (in)	Hp	1/8	1/4	1/2	1	2	3
A	6.14	6.14	6.14	6.14	7.09	8.35	8.35
B	3.27	3.27	3.27	3.27	4.02	4.88	4.88
C	0.32	0	0	0	0.08	0.24	0.24

Table 1.5: Brake Data G3, H2, F3 Mid Type 1/8 to 1 Hp Three Phase IP-65

Horsepower	1/8 Hp	1/4 Hp	1/2 Hp	1 Hp	2 Hp	3 Hp
Brake Type	Power Off-Brake On, Spring Close					-
Static Friction Torque (in-lb) ¹	8.67	17.35	34.70	65	-	-
Dynamic Friction Torque (in-lb) ¹	6.90	13.90	27.79	52	-	-
Voltage DC (Average) (VDC)	200V Class	90 VDC (Rectifier A200-D90: Included with Gearmotor)				
	400V Class	180 VDC (Rectifier A400-D180: Included with Gearmotor)				
Power (@ 75C) (W)	200V Class	10	16	18	22	-
	400V Class	12	18	20	25	-
Current (@ 75C) (A)	200V Class	0.11	0.18	0.20	0.25	-
	400V Class	0.06	0.10	0.11	0.14	-
Allowable Total Work Emax (in-lb)	1.3×10^9		1.3×10^9		1.3×10^9	3.47×10^9
Allowable Braking Frequency (times/minute) ²	10/min				-	

¹Target value.²Used as a reference value only. Can increase or decreased based on the application.

Fig 1.13: 1/8 Hp IP-65 Brake

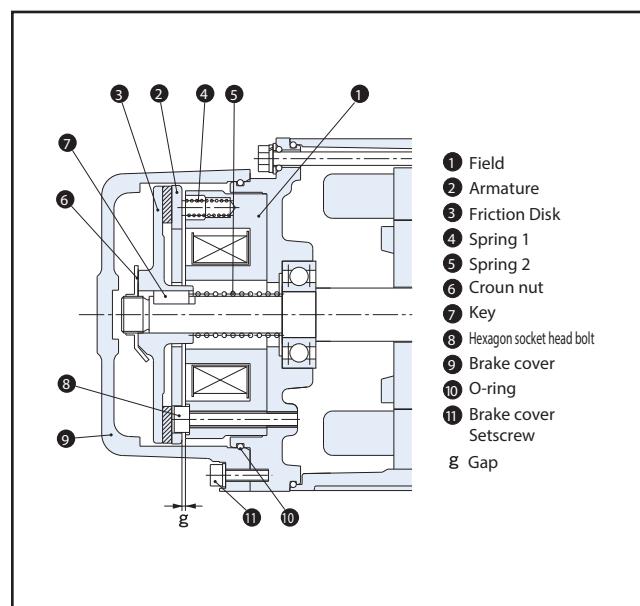


Fig 1.14: 1/4 to 3 Hp IP-65 Brake

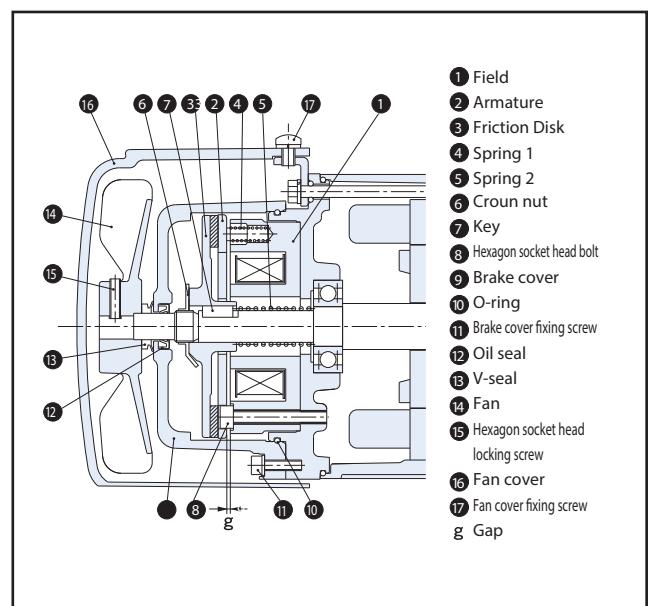
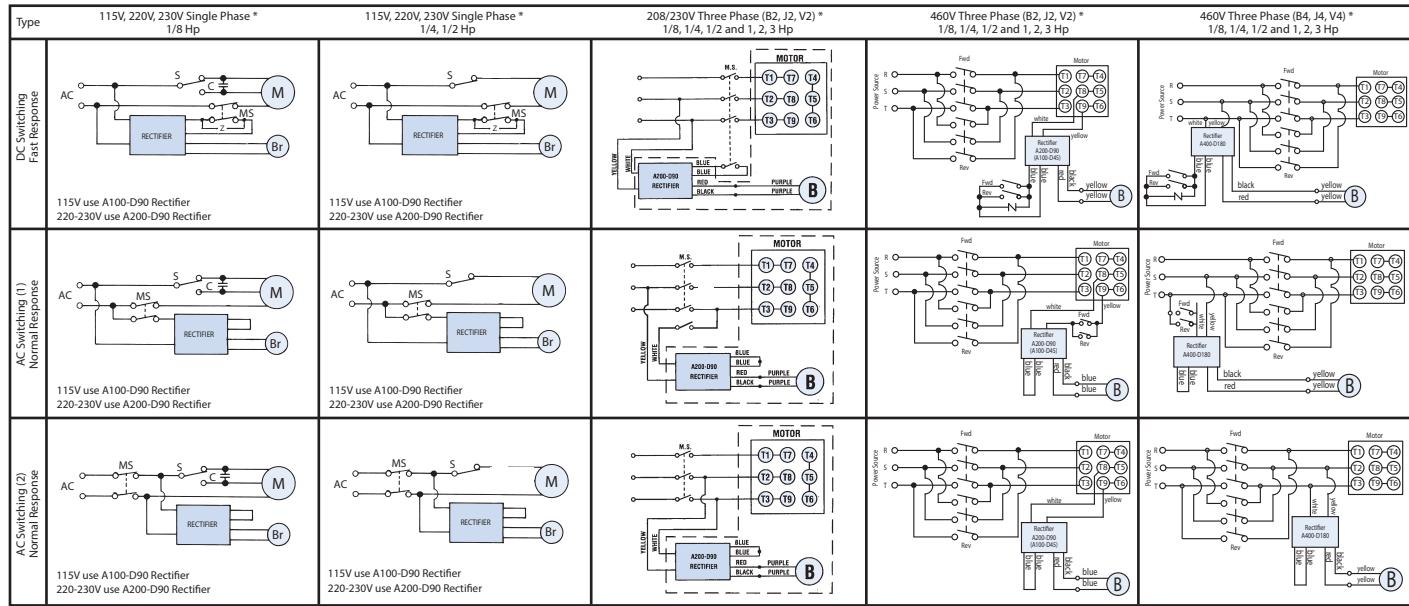


Fig. 1.15: Mid Type: 1/8, 1/4, 1/2, 1, 2, and 3 Hp



* For wiring with an Inverter, see page 17

M: Motor Br: Brake S: Reversing switch C: Capacitor MS: Magnetic switch Z: Surge Suppressor

Fig. 1.16A Rectifier

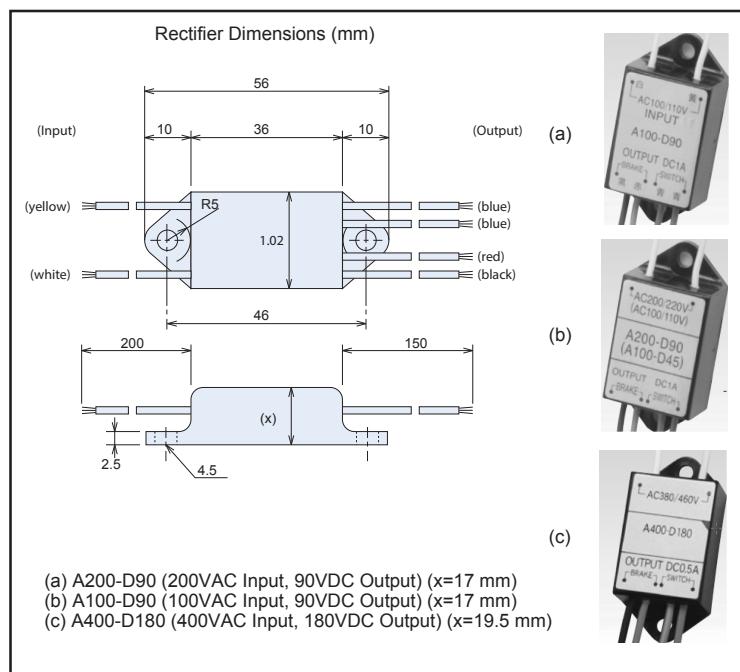
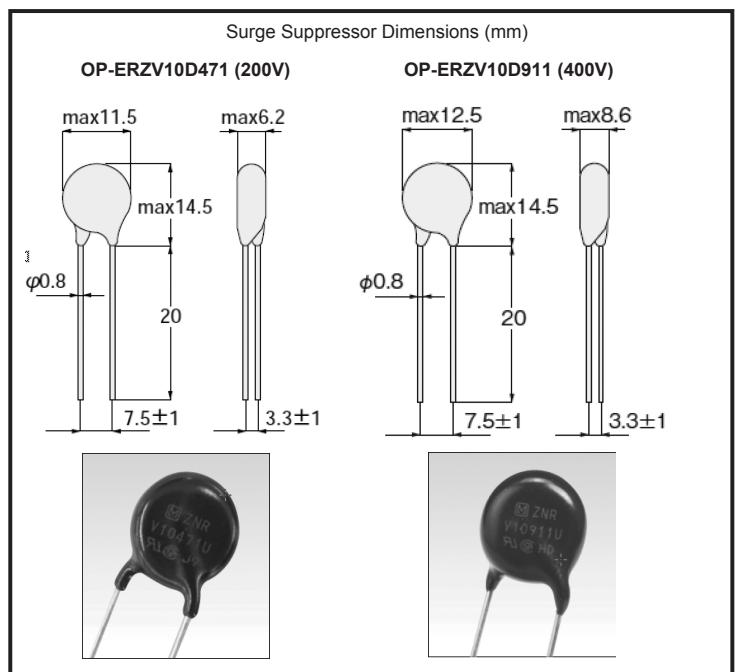


Fig. 1.16B Surge Suppressor

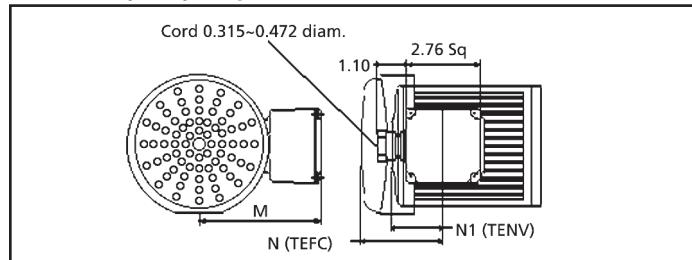


Brother AC Gearmotors

TERMINAL BOX / LEADS OPTIONS

Fig. 1.18: "A" Box: G3, H2 Models

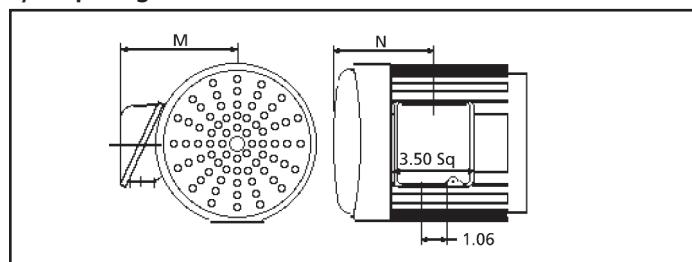
1 Phase: 1/8, 1/4 Hp



Dim	Single Phase	
	1/8 Hp	1/4 Hp
N1 (1/8 Hp 3 Ø only)	—	—
N (motor)	3.09	3.29
N (Brakemotor)	3.44	3.96
M	4.61	4.61

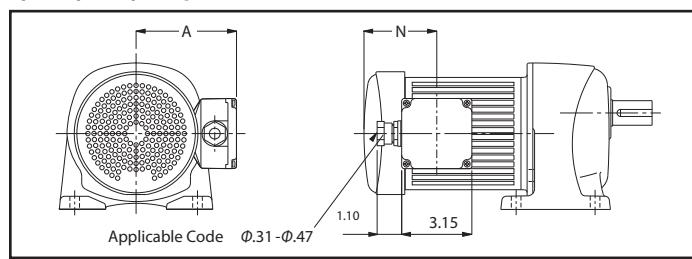
Fig. 1.20: "S" Box: G3, H2 Models

1/2 Hp Single Phase



Dim	Single Phase	
	1/2 Hp	
N (motor)	3.98	
N (Brakemotor)	4.25	
M	4.80	

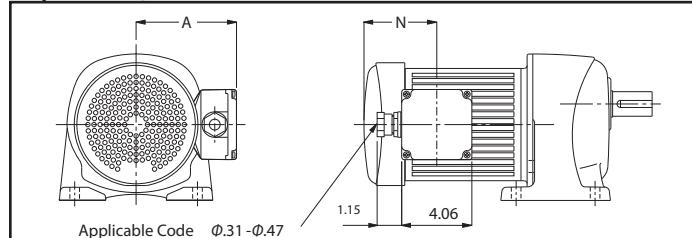
Fig 1.22: "E" Box: G3, H2 Models
1/8, 1/4, 1/2 Hp



Dim	1/8 Hp	1/4 Hp	1/2 Hp	1 Hp	2 Hp	3 Hp
A	4.27	4.27	4.51	4.98	5.41	5.41
N (motor)	1.87	3.07	3.27	3.70	4.35	4.35
N (Brakemotor)	3.90	5.04	5.55	6.44	n/a	n/a

Fig. 1.24: "W" Box 1 to 3 Hp

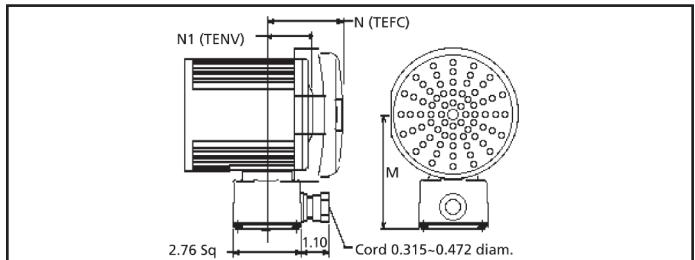
G3, H2 Models



Dim	IP-44	1 Hp	2 Hp	3 Hp	IP-65	1 Hp	2 Hp	3 Hp
A	5.22	5.50	5.93		5.22	5.50	5.93	
N (motor)	3.87	4.66	4.70		3.87	4.66	4.70	
N (Brakemotor)	3.27	5.65	5.69		6.33	-	-	

Fig. 1.19: "A" Box: F3 Model

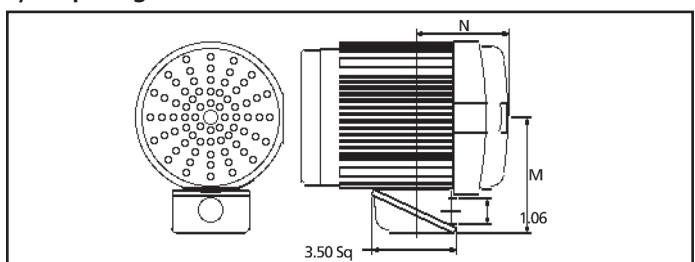
1 Phase: 1/8, 1/4 Hp



Dim	Single Phase	
	1/8 Hp	1/4 Hp
N1 (1/8 Hp 3 Ø only)	—	—
N (motor)	3.09	3.29
N (Brakemotor)	3.44	3.96
M	4.61	4.61

Fig. 1.21: "S" Box: F3 Models

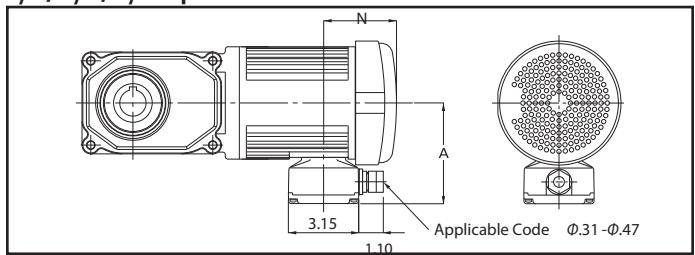
1/2 Hp Single Phase



Dim	Single Phase	
	1/2 Hp	
N (motor)	3.98	
N (Brakemotor)	4.25	
M	4.80	

Fig 1.23: "E" Box: F3 Models

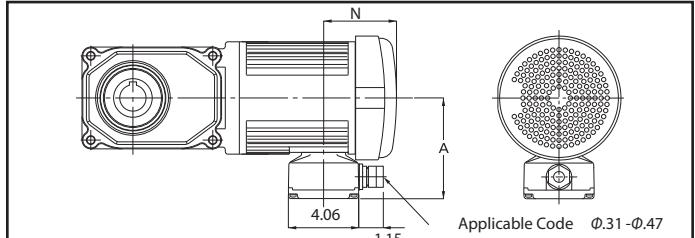
1/8, 1/4, 1/2 Hp



Dim	1/8 Hp	1/4 Hp	1/2 Hp	1 Hp	2 Hp	3 Hp
A	4.27	4.27	4.51	4.98	5.41	5.41
N (motor)	1.87	3.07	3.27	3.70	4.35	4.35
N (Brakemotor)	3.90	5.04	5.55	6.44	n/a	n/a

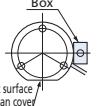
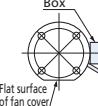
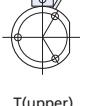
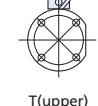
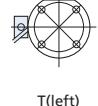
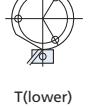
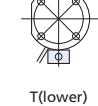
Fig. 1.25: "W" Box 1 to 3 Hp

F3 Models



Dim	IP-44	1 Hp	2 Hp	3 Hp	IP-65	1 Hp	2 Hp	3 Hp
A	5.22	5.50	5.93		5.22	5.50	5.93	
N (motor)	3.87	4.66	4.70		3.87	4.66	4.70	
N (Brakemotor)	3.27	5.65	5.69		6.33	-	-	

Fig 1.24A: Directing the Position of the Terminal Box or Lead Wires

G3, H2: 1/8, 1/4 Hp	G3, H2: 1/2, 1, 2, 3 Hp
	
Standard T3	Standard T3
	
T(upper)	T(upper)
TZ	TZ
	
T(left)	T(left)
T9	T9
	
T(lower)	T(lower)
T6	T6

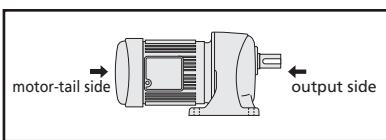
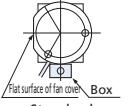
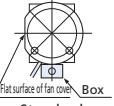
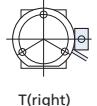
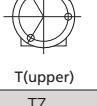
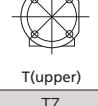
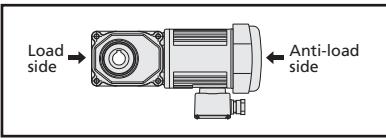


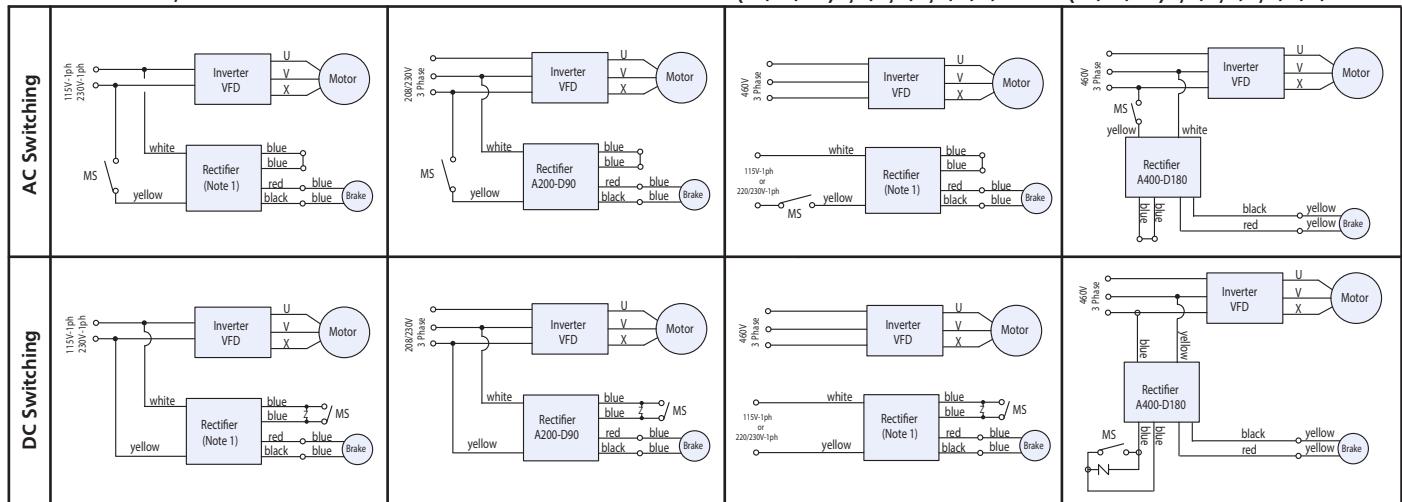
Fig 1.24B: Directing the Position of the Terminal Box or Lead Wires

F3: 1/8, 1/4 Hp	F3: 1/2, 1, 2, 3 Hp
	
Standard	Standard
Standard T6	Standard T6
	
T(right)	T(right)
T3	T3
	
T(upper)	T(upper)
TZ	TZ
	
T(left)	T(left)
T9	T9



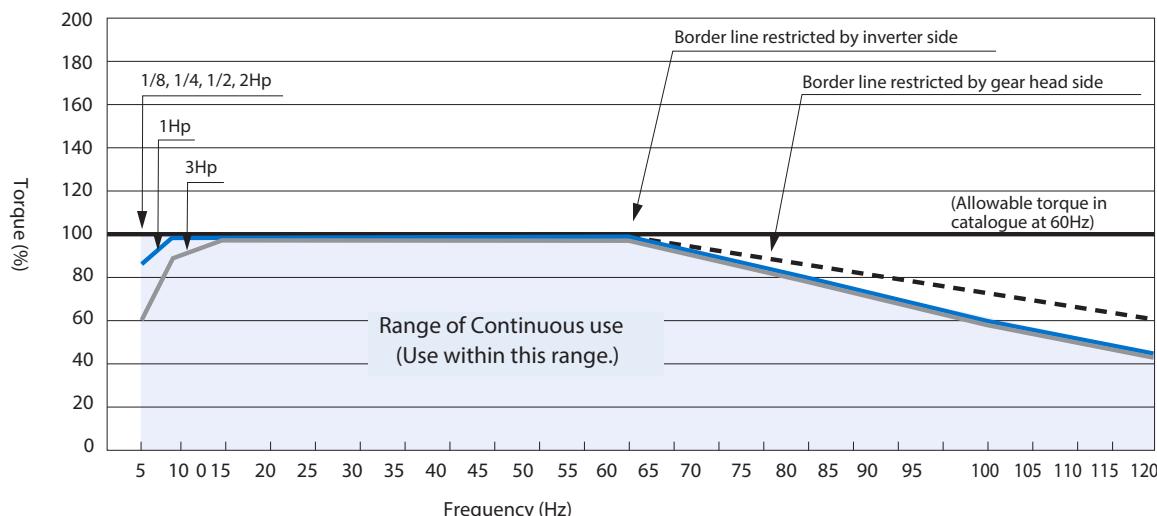
Notes:

1. Please select the "X" at the end of the gearmotor part number and indicate the position code per the applicable chart.
2. If the standard box position is desired or acceptable, there is no need to make any designation.
3. The position of the 1/8 and 1/4 Hp models cannot be rotated in 90 degree increments. Positioning at 90 degree increments is achieved in the factory by position of the tapped mounting holes. Please be careful and specify prior to shipment.

Fig 1.26A: VFD Wiring 115V 1 Phase
220/230V 1 PhaseFig 1.26B: VFD Wiring 208/230V
3 PhaseFig 1.26C: 460V Three Phase
(B2, J2, V2) 1/8, 1/4, 1/2, 1, 2, 3 HPFig 1.26D: 460V Three Phase
(B4, J4, V4) 1/8, 1/4, 1/2, 1, 2, 3 HP

Note: If the input power is 115V 1 phase, use Rectifier A100-D90. If the input power is 220/230V 1 phase, use rectifier A200-D90. (Input power to the brake is 90vdc)
 MS: Magnetic Switch (not supplied by Brother) Z : Surge Suppressor. (See Figure 1.16B)

Fig 1.27 Speed/Torque with a VFD (1/8, 1/4, 1/2 Hp, 1, 2, 3 Hp)



Cautionary Notes for Use with a VFD:

1. In general operation from 5~120 Hz is allowed if the torque capacity can be handled.
2. In applications requiring operation above 60 hz, vibration and noise will increase. The life of the oil seal will also be reduced due to increased circumferential velocity.
3. In low speed operations the effect of the cooling fan decreases. Be sure to check the motor temperature rise remains below allowable limits.
 The surface temperature of the motor should not exceed 176 °F (80°C).
4. The torque characteristics of the motor differ according to the VFD brand and type used. The above speed/torque curves were generated using a commercially available Volts/Hertz VFD. You should test the brand you use to confirm the performance.
5. When using a brake equipped motor, be sure to bypass the VFD and power the rectifier on the input side. Powering the rectifier using the output wires from the VFD to the motor will result in motor and/or brake failure.
6. When operating a VFD at 400~480V a repetitive surge voltage may arise and weaken the insulation of the motor causing premature failure. There are two ways to suppress surge voltage...
 - A. Output Reactor: may be effective if the lead wires are relatively short. Install it on the inverter output side.
 - B. Output Filter: install it near the inverter output side.

The remedies A and B may be effective. However, we recommend you consult the inverter manufacturer for more detailed recommendations as the inverter settings, lead length, etc effect the recommendation.



Spec Table 1.1

Specifications						Dimensional Drawings Page 19											
Hp	Frame	Ratio X:1 GR	Nominal RPM n	Torque (in-lbs) TR	O.H.L. (lbs) OHL	Motor				Brakemotor				3 Phase IP-65			
						1 Phase Std Foot	3 Phase Std Foot	3 Phase IP-65 Foot	1 Phase Std Foot	3 Phase Std Foot	3 Phase IP-65 Foot	1 Phase Std Foot	3 Phase Std Foot	3 Phase IP-65 Foot	1 Phase Std Foot	3 Phase Std Foot	3 Phase IP-65 Foot
1/8 Hp	18	5	360	22.5	132	Dwg 1.1	Dwg 1.3	Dwg 1.1	Dwg 1.1	Dwg 1.3	Dwg 1.1	Dwg 1.3	Dwg 1.1	Dwg 1.3	Dwg 1.1	Dwg 1.3	
		10	180	44	198												
		15	120	67	221												
		20	90	87	265												
		25	72	113	287												
		30	60	130	309												
		40	45	173	331												
	22	50	36	217	353		Dwg 1.1	Dwg 1.3	Dwg 1.1	Dwg 1.3	Dwg 1.1	Dwg 1.3	Dwg 1.1	Dwg 1.3	Dwg 1.1	Dwg 1.3	
		60	30	261	485												
		80	22.5	346	551												
		100	18	432	551												
		120	15	519	551												
		160	11.2	691	551												
		200	9	864	551												
	28	300	6	1155	772	Dwg 1.2	Dwg 1.4	Dwg 1.2	Dwg 1.4	Dwg 1.2	Dwg 1.4	Dwg 1.2	Dwg 1.4	Dwg 1.2	Dwg 1.4	Dwg 1.2	Dwg 1.4
		375	4.8	1444	772												
		450	4	1733	772												
	32	600	3	2311	1323	Dwg 1.2	Dwg 1.4	Dwg 1.2	Dwg 1.4	Dwg 1.2	Dwg 1.4	Dwg 1.2	Dwg 1.4	Dwg 1.2	Dwg 1.4	Dwg 1.2	Dwg 1.4
		750	2.4	2888	1323												
		900	2	3466	1323												
		1200	1.5	3819	1323												

Model Number for Ordering-Single Phase

G3	L	18	N	005	-	B	M	H	1	A	X
Type	Mount Form	Frame	Shaft/Bore Arrangement	Gear Ratio		UL/CSA	Motor Type	Motor Power	Supply Voltage	Terminal Box/Leads ^{4,5}	Special Spec ^{5,6,7}
G3: G3 Series	L: Foot Mount K: Flange Mount	18 22 28 32	N: Common Code	005 : 5:1 030 : 30:1 900 : 900:1 12X : 1200:1		B: UL/CSA	M: Motor ¹ B: Brakemotor ^{1,2} J: Brakemotor ^{1,2} w/ manual release	H: 1/8 HP	1: 115V, 60Hz, 1ph 5: 220V, 60Hz, 1ph 6: 230V, 60Hz, 1ph 7: OEM Spec. 1ph ⁶	A: Die Cast N: Leads, (4.5 inch)	Blank: Standard Type X: Special Spec

Model Number for Ordering-Three Phase

G3	L	18	N	5	-	M	F	1	A	E	N	X
Type	Mount Form	Frame	Shaft/Bore Arrangement	Gear Ratio		Enclosure	Motor Type	Motor Power	Supply Voltage	Terminal Box ^{4,5}	Brake/Options	Special Spec ^{5,6,7}
G3: G3 Series	L: Foot Mount K: Flange Mount	18 22 28 32	N: For use with "M" Enclosure S: For use with "W" Enclosure	5 : 5:1 30 : 30:1 900 : 900:1 12X : 1200:1		M: IP-44 W: IP-65	F: 1/8 to 1/2 HP	1: 1/8 HP (100 W)	A: 208/230/400/460V 60/60/50/60 Hz	E: Die Cast	N: No Brake B2: 90VDC Brake B4: 180VDC Brake	Blank: Standard X: Special Spec

Notes:

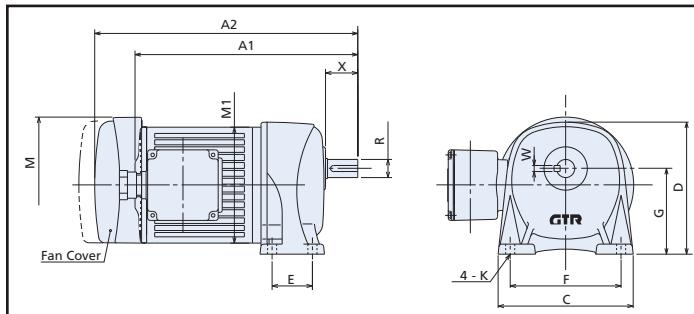
1. Motor and brakemotor electrical data shown on Page 10 Table 1.1 (3 Phase) and Page 11 Table 1.2 (1 Phase).
2. Brake electrical data shown on Pages 12~14.
3. Brother 3 Phase gearmotors are suitable for use with a VFD. See Page 17 for details.
4. See Page 15 for terminal box type or lead wire dimensional details.
5. Lead Wire or Terminal Box location: specify the code from Page 16, Fig 1.24A on your purchase order.
6. Special Voltage: specify the Voltage/Frequency from Page 10 Fig 1.4 (1 Phase) on your purchase order.
7. For any other special OEM requirement, please consult Brother.

Brother In-line Mid Series Gearmotors

GEARMOTOR DATA

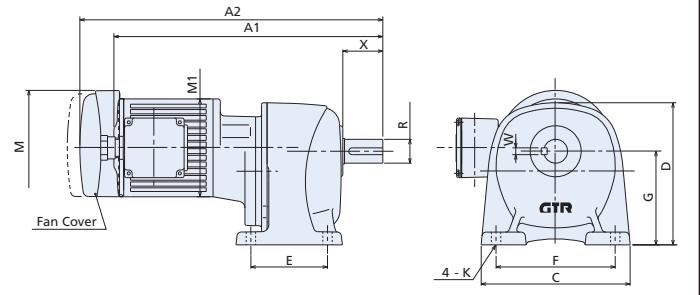
Frame	Motor/Brake-motor	Dwg	A1 (Motor)	A2 (Brake)	M1 (TENV) (Motor)	M (TEFC) (Brake)	C	D	E	F	G	K	R	W	X	Motor Wt	Brake-motor Wt
18	3 Phase Std	1.1	8.70	10.28	4.53	5.31	5.28	5.16	1.57	4.33	3.35	0.35	0.7500	0.1875	1.26	13.25	16.5
22		1.1	9.72	11.30	4.53	5.31	6.06	5.47	2.56	5.12	3.54	0.43	0.8750	0.1875	1.65	15.5	19
28		1.2	12.44	14.02	4.53	5.31	6.89	6.57	3.54	5.51	4.33	0.43	1.1250	0.2500	1.85	22	25.5
32		1.2	13.19	14.76	4.53	5.31	8.19	7.80	5.12	6.69	5.12	0.51	1.2500	0.2500	2.28	29	32
18	3 Phase IP-65	1.1	8.70	10.73	4.53	5.31	5.28	5.16	1.57	4.33	3.35	0.35	0.7500	0.1875	1.26	13.25	16.5
22		1.1	9.72	11.75	4.53	5.31	6.06	5.47	2.56	5.12	3.54	0.43	0.8750	0.1875	1.65	15.5	19
28		1.2	12.44	14.45	4.53	5.31	6.89	6.57	3.54	5.51	4.33	0.43	1.1250	0.2500	1.85	22	25.5
32		1.2	13.19	15.22	4.53	5.31	8.19	7.80	5.12	6.69	5.12	0.51	1.2500	0.2500	2.28	29	32
18	1 Phase Std	1.1	9.92	10.28	n/a	5.31	5.28	5.16	1.57	4.33	3.35	0.35	0.7500	0.1875	1.26	13.25	16.5
22		1.1	10.95	11.30	n/a	5.31	6.06	5.47	2.56	5.12	3.54	0.43	0.8750	0.1875	1.65	15.5	19
28		1.2	13.67	14.02	n/a	5.31	6.89	6.57	3.54	5.51	4.33	0.43	1.1250	0.2500	1.85	22	25.5
32		1.2	14.41	14.76	n/a	5.31	8.19	7.80	5.12	6.69	5.12	0.51	1.2500	0.2500	2.28	29	32

Dwg. 1.1



Note: Terminal box or lead wire dim see Page 15.

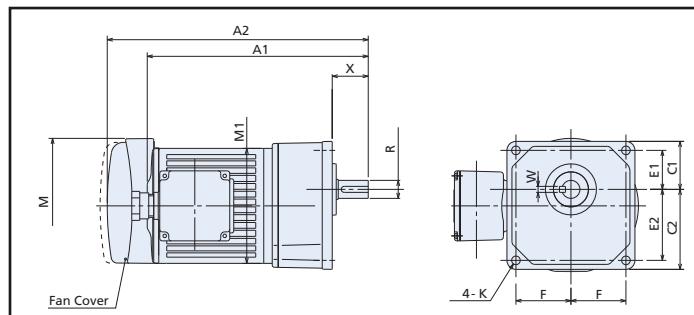
Dwg. 1.2



Note: Terminal box or lead wire dim see Page 15.

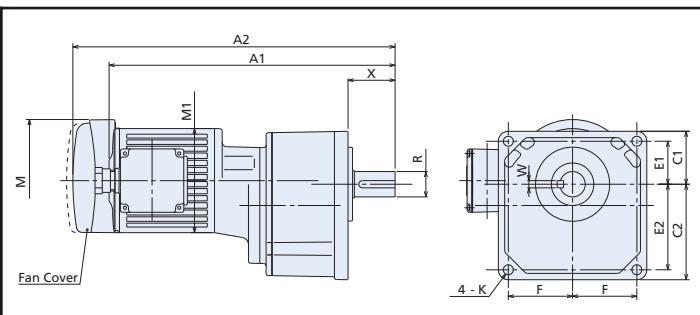
Frame	Motor/Brake-motor	Dwg	A1 (Motor)	A2 (Brake)	M1 (TENV) (Motor)	M (TEFC) (Brake)	C1	C2	E1	E2	F	K	R	W	X	Motor Wt	Brake-motor Wt
18	3 Phase Std	1.3	8.70	10.28	4.53	5.31	1.89	3.15	1.54	2.8	2.17	0.34	0.7500	0.1875	1.38	14.25	17.75
22		1.3	9.72	11.30	4.53	5.31	2.01	3.5	1.65	3.15	2.40	0.34	0.8750	0.1875	1.85	16.5	20
28		1.4	12.44	14.02	4.53	5.31	2.30	4.15	1.87	3.72	2.80	0.43	1.1250	0.2500	1.97	23.25	26.5
32		1.4	13.19	14.76	4.53	5.31	2.81	4.98	2.30	4.47	3.39	0.51	1.2500	0.2500	2.36	30	33
18	3 Phase IP-65	1.3	8.70	10.73	4.53	5.31	1.89	3.15	1.54	2.8	2.17	0.34	0.7500	0.1875	1.38	14.25	17.75
22		1.3	9.72	11.75	4.53	5.31	2.01	3.5	1.65	3.15	2.40	0.34	0.8750	0.1875	1.85	16.5	20
28		1.4	12.44	14.45	4.53	5.31	2.30	4.15	1.87	3.72	2.80	0.43	1.1250	0.2500	1.97	23.25	26.5
32		1.4	13.19	15.22	4.53	5.31	2.81	4.98	2.30	4.47	3.39	0.51	1.2500	0.2500	2.36	30	33
18	1 Phase Std	1.3	9.92	10.27	n/a	5.31	1.89	3.15	1.54	2.8	2.17	0.34	0.7500	0.1875	1.38	14.25	17.75
22		1.3	10.95	11.30	n/a	5.31	2.01	3.5	1.65	3.15	2.40	0.34	0.8750	0.1875	1.85	16.5	20
28		1.4	13.67	14.02	n/a	5.31	2.30	4.15	1.87	3.72	2.80	0.43	1.1250	0.2500	1.97	23.25	26.5
32		1.4	14.41	14.76	n/a	5.31	2.81	4.98	2.30	4.47	3.39	0.51	1.2500	0.2500	2.36	30	33

Dwg. 1.3



Note: Terminal box or lead wire dim see Page 15.

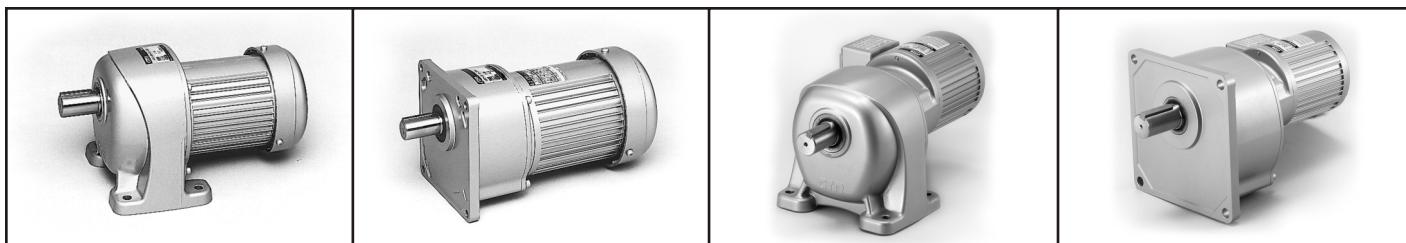
Dwg. 1.4



Note: Terminal box or lead wire dim see Page 15.

Notes/Disclaimer:

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3. Prints are available online using the Brother configurator by entering the complete part number. See www.BrotherGearmotors.com



Spec Table 1.2

Specifications						Dimensional Drawings Page 21													
Hp	Frame	Ratio X:1 GR	Nominal RPM n	Torque (in-lbs) TR	O.H.L. (lbs) OHL	Motor				Brakemotor									
						1 Phase Std Foot	3 Phase Std Foot	3 Phase IP-65 Foot	1 Phase Std Foot	3 Phase Std Foot	3 Phase IP-65 Foot								
1/4 Hp	18	5	360	45	55	Dwg 1.5	Dwg 1.7	Dwg 1.5	Dwg 1.5	Dwg 1.7	Dwg 1.5	Dwg 1.7	Dwg 1.5	Dwg 1.7	Dwg 1.5	Dwg 1.7			
		10	180	89	121														
		15	120	134	176														
		20	90	178	242														
		25	72	223	264														
	22	30	60	268	341	Dwg 1.5	Dwg 1.7	Dwg 1.5	Dwg 1.7	Dwg 1.5	Dwg 1.7	Dwg 1.5	Dwg 1.7	Dwg 1.5	Dwg 1.7	Dwg 1.5	Dwg 1.7		
		40	45	346	352														
		50	36	432	363														
		60	30	519	374														
		80	22.5	691	385														
	28	100	18	864	572	Dwg 1.5	Dwg 1.7	Dwg 1.5	Dwg 1.7	Dwg 1.5	Dwg 1.7	Dwg 1.5	Dwg 1.7	Dwg 1.5	Dwg 1.7	Dwg 1.5	Dwg 1.7		
		120	15	1037	583														
		160	11.2	1383	605														
		200	9	1728	616														
	32	300	6	2311	1587	Dwg 1.6	Dwg 1.8	Dwg 1.6	Dwg 1.8	Dwg 1.6	Dwg 1.8	Dwg 1.6	Dwg 1.8	Dwg 1.6	Dwg 1.8	Dwg 1.6	Dwg 1.8	Dwg 1.6	Dwg 1.8
		375	4.8	2888	1587														
		450	4	3466	1587														
	40	600	3	4621	1587	Dwg 1.6	n/a	Dwg 1.6	n/a	Dwg 1.6	n/a	Dwg 1.6	n/a	Dwg 1.6	n/a	Dwg 1.6	n/a	Dwg 1.6	n/a
		750	2.4	5777	1587														
		900	2	6770	1587														
		1200	1.5	6770	1587														

Model Number for Ordering-Single Phase

G3	L	18	N	005	-	B	M	K	1	A	X
Type	Mount Form	Frame	Shaft/Bore Arrangement	Gear Ratio		UL/CSA	Motor Type	Motor Power	Supply Voltage	Terminal Box/Leads	Special Spec
G3: G3 Series	L: Foot Mount K: Flange Mount F: Flange Mount (40 Frame)	18 22 28 32 40	N: Common Code	005 : 5:1 030 : 30:1 900 : 900:1 12X : 1200:1		B: UL/CSA	M: Motor ¹ B: Brakemotor ^{1,2} J: Brakemotor ^{1,2} w/ manual release	K: 1/4 HP	1: 115V, 60Hz, 1ph 5: 220V, 60Hz, 1ph 6: 230V, 60Hz, 1ph 7: OEM Spec. 1ph ⁶	A: Die Cast N: Leads, (4.5 inch)	Blank: Standard Type X: Special Spec

Model Number for Ordering-Three Phase

G3	L	18	N	5	-	M	F	2	A	E	N	X
Type	Mount Form	Frame	Shaft/Bore Arrangement	Gear Ratio		Enclosure	Motor Type	Motor Power	Supply Voltage	Terminal Box	Brake/Options	Special Spec
G3: G3 Series	L: Foot Mount K: Flange Mount F: Flange Mount (40 Frame)	18 22 28 32 40	N: For use with "M" Enclosure S: For use with "W" Enclosure	5 : 5:1 30 : 30:1 900 : 900:1 12X : 1200:1		M: IP-44 W: IP-65	F: 1/8 to 1/2 HP	2: 1/4 HP (200 W)	A: 208/230/400/460V 60/60/60/60 Hz	E: Die Cast	N: No Brake B2: 90VDC Brake B4: 180VDC Brake	Blank: Standard X: Special Spec

Notes:

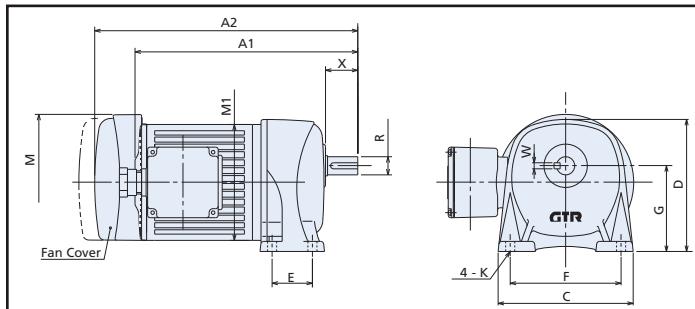
1. Motor and brakemotor electrical data shown on Page 10 Table 1.1 (3 Phase) and Page 11 Table 1.2 (1 Phase).
2. Brake electrical data shown on Pages 12~14.
3. Brother 3 Phase gearmotors are suitable for use with a VFD. See Page 17 for details.
4. See Page 15 for terminal box type or lead wire dimensional details.
5. Lead Wire or Terminal Box location: specify the code from Page 16, Fig 1.24A on your purchase order.
6. Special Voltage: specify the Voltage/Frequency from Page 10 Fig 1.4 (1 Phase) on your purchase order.
7. For any other special OEM requirement, please consult Brother.

Brother In-line Mid Series Gearmotors

GEARMOTOR DATA

Frame	Motor/Brake-motor	Dwg	A1 (Motor)	A2 (Brake)	M	C	D	E	F	G	K	R	W	X	Motor Wt	Brake-motor Wt
18	3 Phase Std	1.5	10.51	11.18	5.31	5.28	5.16	1.57	4.33	3.35	0.35	0.7500	0.1875	1.26	14.25	17.5
22		1.5	11.54	12.20	5.31	6.06	5.47	2.56	5.12	3.54	0.43	0.8750	0.1875	1.65	16.5	20
28		1.5	12.05	12.72	5.31	6.89	6.57	3.54	5.51	4.33	0.43	1.1250	0.2500	1.85	21	24.25
32		1.6	15.79	16.46	5.31	8.19	7.80	5.12	6.69	5.12	0.51	1.2500	0.2500	2.28	30	33
40		1.6	16.65	17.32	5.31	10.00	9.06	5.91	8.72	5.91	0.59	1.6250	0.3750	2.68	44	47.5
18	3 Phase IP-65	1.5	10.51	12.46	5.31	5.28	5.16	1.57	4.33	3.35	0.35	0.7500	0.1875	1.26	14.25	17.5
22		1.5	11.54	13.48	5.31	6.06	5.47	2.56	5.12	3.54	0.43	0.8750	0.1875	1.65	16.5	20
28		1.5	12.05	13.99	5.31	6.89	6.57	3.54	5.51	4.33	0.43	1.1250	0.2500	1.85	21	24.25
32		1.6	15.79	17.73	5.31	8.19	7.80	5.12	6.69	5.12	0.51	1.2500	0.2500	2.28	30	33
40		1.6	16.65	18.60	5.31	10.00	9.06	5.91	8.72	5.91	0.59	1.6250	0.3750	2.68	44	47.5
18	1 Phase Std (Note)	1.5	12.48	13.15	5.31	5.28	5.16	1.57	4.33	3.35	0.35	0.7500	0.1875	1.26	18.75	22
22		1.5	13.50	14.17	5.31	6.06	5.47	2.56	5.12	3.54	0.43	0.8750	0.1875	1.65	21	24.25
28		1.5	14.02	14.69	5.31	6.89	6.57	3.54	5.51	4.33	0.43	1.1250	0.2500	1.85	25.5	28.75
32		1.6	17.76	18.43	5.31	8.19	7.80	5.12	6.69	5.12	0.51	1.2500	0.2500	2.28	34.25	37.5
40		1.6	18.62	19.29	5.31	10.00	9.06	5.91	8.72	5.91	0.59	1.6250	0.3750	2.68	48.5	52

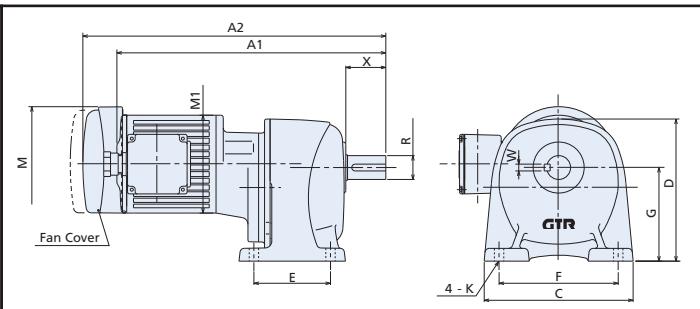
Dwg. 1.5



Note: Terminal box or lead wire dim see Page 15.

Note: 1 Phase Std motors have a capacitor mounted, see Page 11, Fig. 1.9.

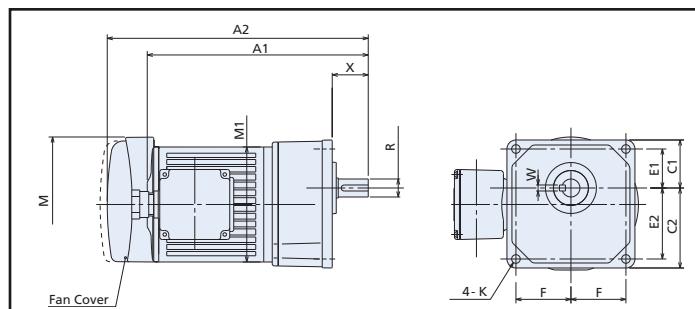
Dwg. 1.6



Note: Terminal box or lead wire dim see Page 15.

Frame	Motor/Brake-motor	Dwg	A1 (motor)	A2 (Brake)	M	C1	C2	E1	E2	F	K	R	W	X	Motor Wt	Brake-motor Wt
18	3 Phase Std	1.7	10.51	11.18	5.31	1.89	3.15	1.54	2.8	2.17	0.34	0.7500	0.1875	1.38	15.5	19
22		1.7	11.54	12.20	5.31	2.01	3.5	1.65	3.15	2.40	0.34	0.8750	0.1875	1.85	17.5	21
28		1.7	12.05	12.72	5.31	2.30	4.15	1.87	3.72	2.80	0.43	1.1250	0.2500	1.97	22	25.5
32		1.8	15.79	16.46	5.31	2.81	4.98	2.30	4.47	3.39	0.51	1.2500	0.2500	2.36	31	34.25
18	3 Phase IP-65	1.7	10.51	12.46	5.31	1.89	3.15	1.54	2.8	2.17	0.34	0.7500	0.1875	1.38	15.5	19
22		1.7	11.54	13.48	5.31	2.01	3.5	1.65	3.15	2.40	0.34	0.8750	0.1875	1.85	17.5	21
28		1.7	12.05	14.00	5.31	2.30	4.15	1.87	3.72	2.80	0.43	1.1250	0.2500	1.97	22	25.5
32		1.8	15.79	17.74	5.31	2.81	4.98	2.30	4.47	3.39	0.51	1.2500	0.2500	2.36	31	34.25
18	1 Phase Std (Note)	1.7	12.48	13.15	5.31	1.89	3.15	1.54	2.8	2.17	0.34	0.7500	0.1875	1.38	15.5	19
22		1.7	13.50	14.17	5.31	2.01	3.5	1.65	3.15	2.40	0.34	0.8750	0.1875	1.85	17.5	21
28		1.7	14.02	14.69	5.31	2.30	4.15	1.87	3.72	2.80	0.43	1.1250	0.2500	1.97	22	25.5
32		1.8	17.76	18.43	5.31	2.81	4.98	2.30	4.47	3.39	0.51	1.2500	0.2500	2.36	31	34.25

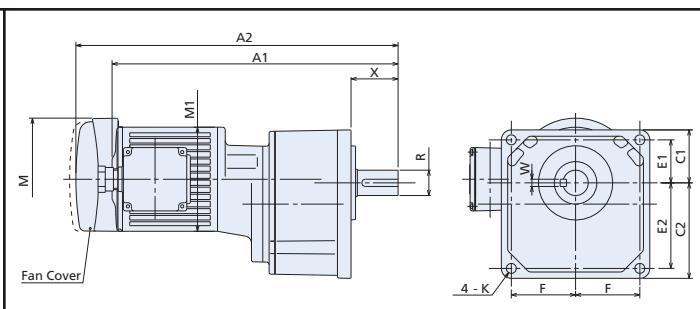
Dwg. 1.7



Note: Terminal box or lead wire dim see Page 15.

Note: 1 Phase Std motors have a capacitor mounted, see Page 11, Fig. 1.9.

Dwg. 1.8



Note: Terminal box or lead wire dim see Page 15.

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Spec Table 1.3

Specifications						Dimensional Drawings Page 23											
Hp	Frame	Ratio X:1 GR	Nominal RPM n	Torque (in-lbs) TR	O.H.L. (lbs) OHL	Motor				Brakemotor							
						1 Phase Std Foot	3 Phase Std Foot	3 Phase IP-65 Foot	1 Phase Std Foot	3 Phase Std Foot	3 Phase IP-65 Foot						
1/2 Hp	22	5	360	89	88	Dwg 1.9	Dwg 1.11	Dwg 1.9	Dwg 1.11	Dwg 1.9	Dwg 1.11	Dwg 1.9	Dwg 1.11	Dwg 1.9	Dwg 1.11	Dwg 1.9	Dwg 1.11
		10	180	178	176												
		15	120	268	242												
		20	90	357	308												
		25	72	446	330												
	28	30	60	535	484	Dwg 1.9	Dwg 1.11	Dwg 1.9	Dwg 1.11	Dwg 1.9	Dwg 1.11	Dwg 1.9	Dwg 1.11	Dwg 1.9	Dwg 1.11	Dwg 1.9	Dwg 1.11
		40	45	691	506												
		50	36	864	528												
		60	30	1037	550												
		80	22.5	1383	572												
	32	100	18	1728	1030	Dwg 1.9	Dwg 1.11	Dwg 1.9	Dwg 1.11	Dwg 1.9	Dwg 1.11	Dwg 1.9	Dwg 1.11	Dwg 1.9	Dwg 1.11	Dwg 1.9	Dwg 1.11
		120	15	2074	1060												
		160	11.2	2765	1120												
		200	9	3457	1140												
	40	300	6	4621	1587	Dwg 1.10	n/a	Dwg 1.10	n/a	Dwg 1.10	n/a	Dwg 1.10	n/a	Dwg 1.10	n/a	Dwg 1.10	n/a
		375	4.8	5777	1587												
		450	4	6770	1587												
	50	600	3	9243	2205	Dwg 1.10	n/a	Dwg 1.10	n/a	Dwg 1.10	n/a	Dwg 1.10	n/a	Dwg 1.10	n/a	Dwg 1.10	n/a
		750	2.4	10850	2205												
		900	2	10850	2205												
		1200	1.5	10850	2205												

Model Number for Ordering-Single Phase

G3	L	22	N	005	-	B	M	L	1	S	X
Type	Mount Form	Frame	Shaft/Bore Arrangement	Gear Ratio		UL/CSA	Motor Type	Motor Power	Supply Voltage	Terminal Box/Leads	Special Spec
G3: G3 Series	L: Foot Mount K: Flange Mount F: Flange Mount (40,50 Frame)	22 28 32 40 50	N: Common Code	005 : 5:1 030 : 30:1 900 : 900:1 12X : 1200:1		B: UL/CSA	M: Motor ¹ B: Brakemotor ^{1,2} J: Brakemotor ^{1,2} w/ manual release	L: 1/2 HP	1: 115V, 60Hz, 1ph 5: 220V, 60Hz, 1ph 6: 230V, 60Hz, 1ph 7: OEM Spec. 1ph ⁶	S: Steel Box N: Leads, (4.5 inch)	Blank: Standard Type X: Special Spec

Model Number for Ordering-Three Phase

G3	L	22	N	5	-	M	F	4	A	E	N	X
Type	Mount Form	Frame	Shaft/Bore Arrangement	Gear Ratio		Enclosure	Motor Type	Motor Power	Supply Voltage	Terminal Box	Brake/Options	Special Spec
G3: G3 Series	L: Foot Mount K: Flange Mount F: Flange Mount (40,50 Frame)	22 28 32 40 50	N: For use with "M" Enclosure S: For use with "W" Enclosure	5 : 5:1 30 : 30:1 900 : 900:1 12X : 1200:1		M: IP-44 W: IP-65	F: 1/8 to 1/2 HP	4: 1/2 HP (400 W)	A: 208/230/400/460V 60/60/50/60 Hz	E: Die Cast	N: No Brake B2: 90VDC Brake B4: 180VDC Brake	Blank: Standard Type X: Special Spec

Notes:

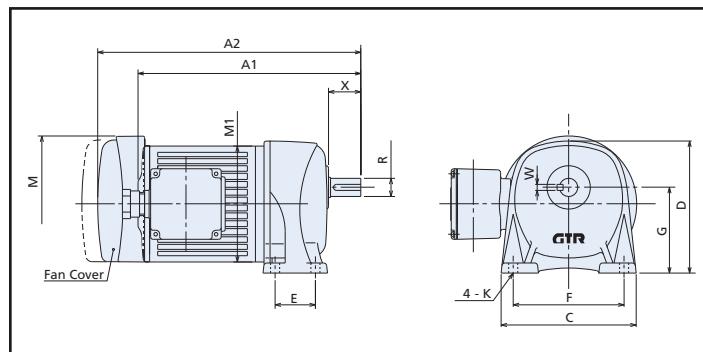
1. Motor and brakemotor electrical data shown on Page 10 Table 1.1 (3 Phase) and Page 11 Table 1.2 (1 Phase).
2. Brake electrical data shown on Pages 12~14.
3. Brother 3 Phase gearmotors are suitable for use with a VFD. See Page 17 for details.
4. See Page 15 for terminal box type or lead wire dimensional details.
5. Lead Wire or Terminal Box location: specify the code from Page 16, Fig 1.24A on your purchase order.
6. Special Voltage: specify the Voltage/Frequency from Page 10 Fig 1.4 (1 Phase) on your purchase order.
7. For any other special OEM requirement, please consult Brother.

Brother In-line Mid Series Gearmotors

GEARMOTOR DATA

Frame	Motor/Brake-motor	Dwg	A1 (Motor)	A2 (Brake)	M	C	D	E	F	G	K	R	W	X	Motor Wt	Brake-motor Wt
22	3 Phase Std	1.9	12.36	13.13	5.55	6.06	5.47	2.56	5.12	3.54	0.43	0.8750	0.1875	1.65	21	24.25
28			12.99	13.76	5.55	6.89	6.57	3.54	5.51	4.33	0.43	1.1250	0.2500	1.85	25.5	29
32		1.10	13.74	14.51	5.55	8.19	7.80	5.12	6.69	5.12	0.51	1.2500	0.2500	2.28	32	35.25
40			17.99	18.76	5.55	10.00	9.06	5.91	8.72	5.91	0.59	1.6250	0.3750	2.68	51	54
50			19.09	19.86	5.55	11.42	10.43	6.30	9.06	6.69	0.71	2.0000	0.5000	3.07	116	119
22	3 Phase IP-65	1.9	12.36	14.59	5.55	6.06	5.47	2.56	5.12	3.54	0.43	0.8750	0.1875	1.65	21	24.25
28			12.99	15.22	5.55	6.89	6.57	3.54	5.51	4.33	0.43	1.1250	0.2500	1.85	25.5	29
32		1.10	13.74	15.96	5.55	8.19	7.80	5.12	6.69	5.12	0.51	1.2500	0.2500	2.28	32	35.25
40			17.99	20.22	5.55	10.00	9.06	5.91	8.72	5.91	0.59	1.6250	0.3750	2.68	51	54
50			19.09	21.32	5.55	11.42	10.43	6.30	9.06	6.69	0.71	2.0000	0.5000	3.07	116	119
22	1 Phase Std (Note)	1.9	15.39	15.67	6.38	6.06	5.47	2.56	5.12	3.54	0.43	0.8750	0.1875	1.65	33	38.5
28			16.02	16.30	6.38	6.89	6.57	3.54	5.51	4.33	0.43	1.1250	0.2500	1.85	37.5	43
32		1.10	16.77	17.05	6.38	8.19	7.80	5.12	6.69	5.12	0.51	1.2500	0.2500	2.28	44	49.75
40			21.02	21.30	6.38	10.00	9.06	5.91	8.72	5.91	0.59	1.6250	0.3750	2.68	63	68.5
50			22.13	22.40	6.38	11.42	10.43	6.30	9.06	6.69	0.71	2.0000	0.5000	3.07	128	133.5

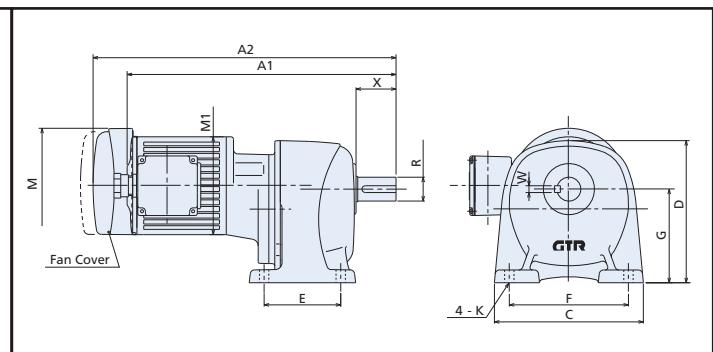
Dwg. 1.9



Note: Terminal box or lead wire dim see Page 15.

Note: 1 Phase Std motors have a capacitor mounted, see Page 11, Fig. 1.9.

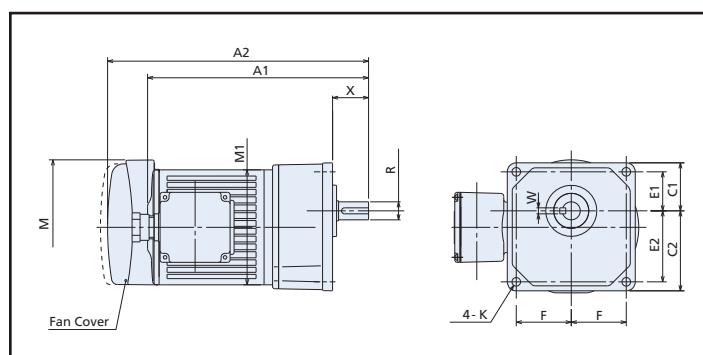
Dwg. 1.10



Note: Terminal box or lead wire dim see Page 15.

Frame	Motor/Brake-motor	Dwg	A1 (Motor)	A2 (Brake)	M	C1	C2	E1	E2	F	K	R	W	X	Motor Wt	Brake-motor Wt
22	3 phase Std	1.11	12.36	13.13	5.55	2.01	3.5	1.65	3.15	2.40	0.34	0.8750	0.1875	1.85	22	25.5
28			12.99	13.76	5.55	2.30	4.15	1.87	3.72	2.80	0.43	1.1250	0.2500	1.97	26.5	30
32			13.74	14.51	5.55	2.81	4.98	2.30	4.47	3.39	0.51	1.2500	0.2500	2.36	33	36.5
22	3 Phase IP-65	1.11	12.36	14.59	5.55	2.01	3.5	1.65	3.15	2.40	0.34	0.8750	0.1875	1.85	22	25.5
28			12.99	15.22	5.55	2.30	4.15	1.87	3.72	2.80	0.43	1.1250	0.2500	1.97	26.5	29.75
32			13.74	15.96	5.55	2.81	4.98	2.30	4.47	3.39	0.51	1.2500	0.2500	2.36	33	36.5
22	1 Phase Std (Note)	1.11	15.39	15.67	6.38	2.01	3.5	1.65	3.15	2.40	0.34	0.8750	0.1875	1.85	34	39.75
28			16.02	16.30	6.38	2.30	4.15	1.87	3.72	2.80	0.43	1.1250	0.2500	1.97	38.75	44
32			16.77	17.05	6.38	2.81	4.98	2.30	4.47	3.39	0.51	1.2500	0.2500	2.36	45.25	50.75

Dwg. 1.11

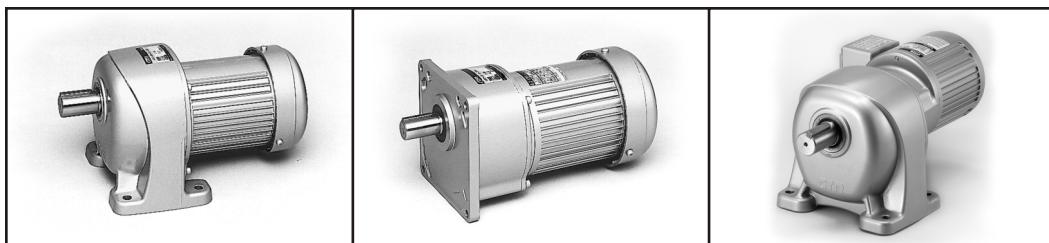


Note: Terminal box or lead wire dim see Page 15.

Note: 1 Phase Std motors have a capacitor mounted, see Page 11, Fig. 1.9.

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3. Prints are available online using the Brother configurator by entering the complete part number. See www.BrotherGearmotors.com



Spec Table 1.4

Specifications						Dimensional Drawings Page 25							
Hp	Frame	Ratio X:1 GR	Nominal RPM n	Torque (in-lbs) TR	O.H.L. (lbs) OHL	Motor				Brakemotor			
		3 Phase Std Foot	3 Phase IP-65 Flange	3 Phase Std Foot	3 Phase IP-65 Flange	3 Phase Std Foot	3 Phase IP-65 Flange	3 Phase Std Foot	3 Phase IP-65 Flange				
1 Hp	28	5	360	167	110	Dwg 1.12	Dwg 1.14	Dwg 1.12	Dwg 1.14	Dwg 1.12	Dwg 1.14	Dwg 1.12	Dwg 1.14
		10	180	335	220								
		15	120	502	308								
		20	90	669	396								
		25	72	837	440								
	32	30	60	1004	891	Dwg 1.12	Dwg 1.14	Dwg 1.12	Dwg 1.14	Dwg 1.12	Dwg 1.14	Dwg 1.12	Dwg 1.14
		40	45	1296	935								
		50	36	1620	968								
		60	30	1944	990								
		80	22.5	2593	1010								
	40	100	18	3241	1450	Dwg 1.12	n/a	Dwg 1.12	n/a	Dwg 1.12	n/a	Dwg 1.12	n/a
		120	15	3889	1480								
		160	11.2	5185	1550								
		200	9	6481	1580								
	50	300	6	8665	2205	Dwg 1.13	n/a	Dwg 1.13	n/a	Dwg 1.13	n/a	Dwg 1.13	n/a
		375	4.8	10832	2205								
		450	4	10850	2205								

Model Number for Ordering-Three Phase

G3	L	28	N	5	-	M	V	6	A	W	N	X
Type	Mount Form	Frame	Shaft/Bore Arrangement	Gear Ratio	Enclosure	Motor Type	Motor Power	Supply Voltage	Terminal Box ^{4,5}	Brake/Options	Special Spec ^{5,6,7}	
G3: G3 Series	L: Foot Mount K: Flange Mount F: Flange Mount (40,50 Frame)	28 32 40 50	N: For use with "M" Enclosure S: For use with "W" Enclosure	5 : 5:1 30 : 30:1 450 : 900:1	M: IP-44 W: IP-65	V: 1 to 3 HP	6: 1 HP (750 W)	A: 208/230/400/460V 60/60/50/60 Hz	W: Large Box with Terminal Block	N: No Brake B2: 90VDC Brake B4: 180VDC Brake	Blank: Standard X: Special Spec	

Notes:

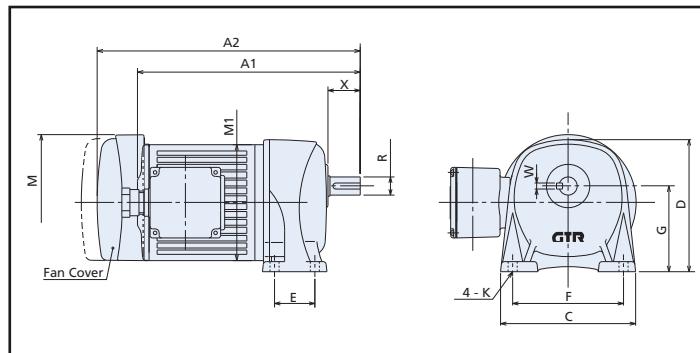
1. Motor and brakemotor electrical data shown on Page 10 Table 1.1 (3 Phase) and Page 11 Table 1.2 (1 Phase).
2. Brake electrical data shown on Pages 12~14.
3. Brother 3 Phase gearmotors are suitable for use with a VFD. See Page 17 for details.
4. See Page 15 for terminal box type or lead wire dimensional details.
5. Lead Wire or Terminal Box location: specify the code from Page 16, Fig 1.24A on your purchase order.
6. Special Voltage: specify the Voltage/Frequency from Page 10 Fig 1.4 (1 Phase) on your purchase order.
7. For any other special OEM requirement, please consult Brother.

Brother In-line Mid Series Gearmotors

GEARMOTOR DATA

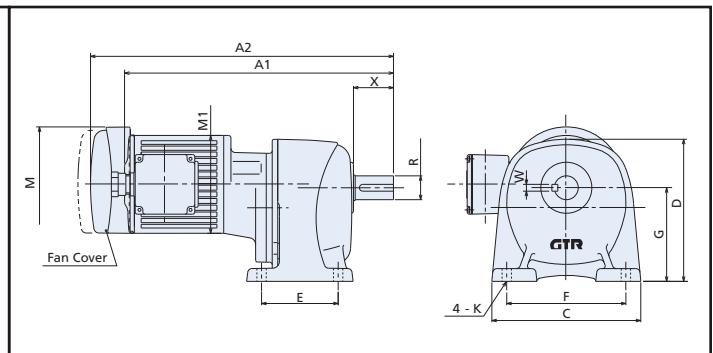
Frame	Motor/ Brake- motor	Dwg	A1 (Motor)	A2 (Brake)	M	C	D	E	F	G	K	R	W	X	Motor Wt	Brake- motor Wt	
28	3 Phase Std	1.12	13.80	14.07	6.38	6.89	6.57	3.54	5.51	4.33	0.43	1.1250	0.2500	1.85	33	38.5	
32			14.94	15.22	6.38	8.19	7.80	5.12	6.69	5.12	0.51	1.2500	0.2500	2.28	41	46.25	
40			15.81	16.08	6.38	10.00	9.06	5.91	8.72	5.91	0.59	1.6250	0.3750	2.68	55	60.5	
50		1.13	20.30	20.57	6.38	11.42	10.43	6.30	9.06	6.69	0.71	2.0000	0.5000	3.07	124.5	130	
28	3 Phase IP-65		13.8	16.48	6.38	6.89	6.57	3.54	5.51	4.33	0.43	1.1250	0.2500	1.85	33	38.5	
32			14.94	17.62	6.38	8.19	7.80	5.12	6.69	5.12	0.51	1.2500	0.2500	2.28	41	46.5	
40			15.81	18.48	6.38	10.00	9.06	5.91	8.72	5.91	0.59	1.6250	0.3750	2.68	55	60.75	
50			20.30	22.97	6.38	11.42	10.43	6.30	9.06	6.69	0.71	2.0000	0.5000	3.07	124.5	130	

Dwg. 1.12



Note: Terminal box or lead wire dim see Page 15.

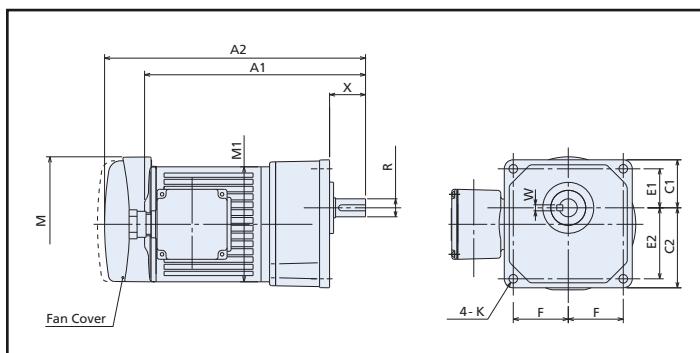
Dwg. 1.13



Note: Terminal box or lead wire dim see Page 15.

Frame	Motor/ Brake- motor	Dwg	A1 (Motor)	A2 (Brake)	M	C1	C2	E1	E2	F	K	R	W	X	Motor Wt	Brake- motor Wt
28	3 Phase Std	1.14	13.80	14.07	6.38	2.30	4.15	1.87	3.72	2.80	0.43	1.1250	0.2500	1.97	34.25	40
32			14.94	15.22	6.38	2.81	4.98	2.30	4.47	3.39	0.51	1.2500	0.2500	2.36	42	47.5
28	3 Phase IP-65	1.14	13.8	16.48	6.38	2.30	4.15	1.87	3.72	2.80	0.43	1.1250	0.2500	1.97	34.25	40
32			14.94	17.62	6.38	2.81	4.98	2.30	4.47	3.39	0.51	1.2500	0.2500	2.36	42	47.5

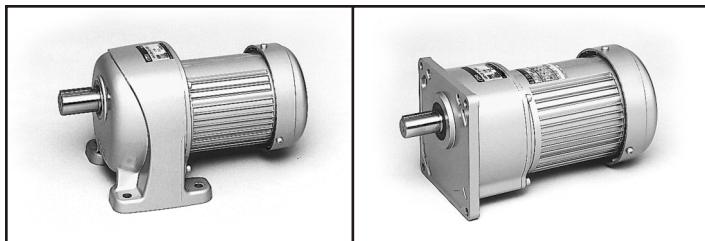
Dwg. 1.14



Note: Terminal box or lead wire dim see Page 15.

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Spec Table 1.5

Specifications						Dimensional Drawings Page 27							
Hp	Frame	Ratio X:1 GR	Nominal RPM n	Torque (in-lbs) TR	O.H.L. (lbs) OHL	Motor				Brakemotor			
						3 Phase Std Foot	3 Phase IP-65 Flange	3 Phase Std Foot	3 Phase IP-65 Flange	3 Phase Std Foot	3 Phase IP-65 Flange	3 Phase Std Foot	3 Phase IP-65 Flange
2 Hp	32	5	360	338	397	Dwg 1.15	Dwg 1.16	Dwg 1.15	Dwg 1.16	Dwg 1.15	Dwg 1.16	n/a	n/a
		10	180	668	551								
		15	120	1006	639								
		20	90	1335	728								
		25	72	1673	860								
	40	30	60	2003	1147	Dwg 1.15	n/a	Dwg 1.15	n/a	Dwg 1.15	n/a	n/a	n/a
		40	45	2592	1323								
		50	36	3234	1588								
		60	30	3884	1588								
		80	22.5	5176	1588								
	50	100	18	6476	2205	Dwg 1.15	n/a	Dwg 1.15	n/a	Dwg 1.15	n/a	n/a	n/a
		120	15	7768	2205								
		160	11.2	10317	2205								
		200	9	10838	2205								
		5	360	494	485								
3 Hp	40	10	180	980	706	Dwg 1.17	n/a	Dwg 1.17	n/a	Dwg 1.17	n/a	n/a	n/a
		15	120	1474	794								
		20	90	1959	904								
		25	72	2454	1058								
		30	60	2939	1566								
	50	40	45	3797	1632	Dwg 1.17	n/a	Dwg 1.17	n/a	Dwg 1.17	n/a	n/a	n/a
		50	36	4751	1940								
		60	30	5696	2205								
		80	22.5	7595	2205								
		100	18	9537	2205								

Model Number for Ordering-Three Phase

G3	L	32	N	5	-	M	V	8	A	W	N	X
Type	Mount Form	Frame	Shaft/Bore Arrangement	Gear Ratio	-	Enclosure	Motor Type	Motor Power	Supply Voltage	Terminal Box ^{4,5}	Brake/Options	Special Spec ^{5,6,7}
G3: G3 Series	L: Foot Mount K: Flange Mount F: Flange Mount (40,50 Frame)	32 40 50	N: For use with "M" Enclosure S: For use with "W" Enclosure	5 : 5:1 30 : 30:1 200 : 200:1	-	M: IP-44 W: IP-65	V: 1 to 3 HP	8: 2 HP (1.5 kW) 9: 3 HP (2.2 kW)	A: 208/230/400/460V W: 60/60/50/60 Hz	W: Large Box with Terminal Block	N: No Brake B2: 90VDC Brake B4: 180VDC Brake	Blank: Standard X: Special Spec

Notes:

1. Motor and brakemotor electrical data shown on Page 10 Table 1.1 (3 Phase) and Page 11 Table 1.2 (1 Phase).
2. Brake electrical data shown on Pages 12~14.
3. Brother 3 Phase gearmotors are suitable for use with a VFD. See Page 17 for details.
4. See Page 15 for terminal box type or lead wire dimensional details.
5. Lead Wire or Terminal Box location: specify the code from Page 16, Fig 1.24A on your purchase order.
6. Special Voltage: specify the Voltage/Frequency from Page 10 Fig 1.4 (1 Phase) on your purchase order.
7. For any other special OEM requirement, please consult Brother.

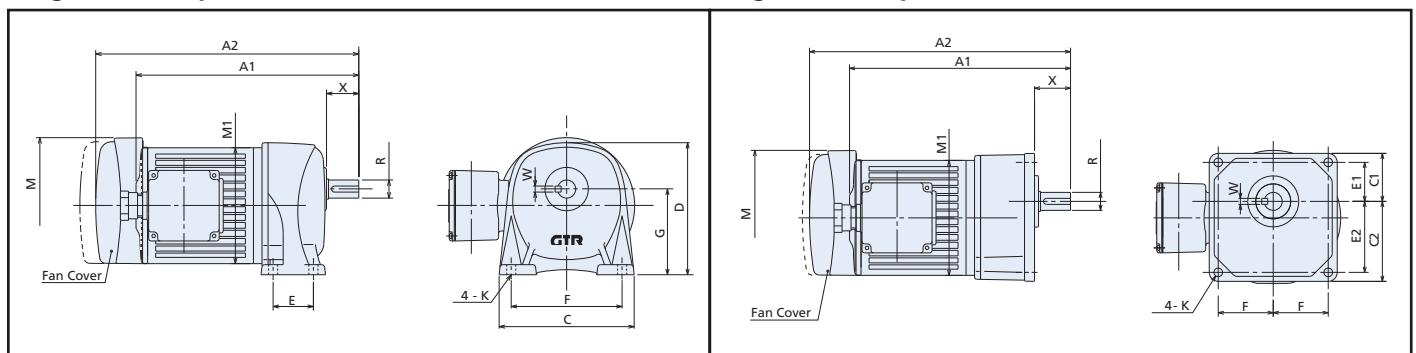
Brother In-line Mid Series Gearmotors

GEARMOTOR DATA

Frame	Motor/Brake-motor	Dwg	A1 (Motor)	A2 (Brake)	M	C	D	E	F	G	K	R	W	X	Motor Wt	Brake-motor Wt
32	3 Phase Std	1.15	16.56	17.36	7.32	8.19	7.80	5.12	6.69	5.12	0.51	1.2500	0.2500	2.28	54	62
40			18.01	18.82	7.32	10.00	9.06	5.91	8.72	5.91	0.59	1.6250	0.3750	2.68	69.5	77
50			19.11	19.92	7.32	11.42	10.43	6.30	9.06	6.69	0.71	2.0000	0.5000	3.07	134.5	142
32	3 Phase IP-65	1.15	16.56	n/a	7.32	8.19	7.80	5.12	6.69	5.12	0.51	1.2500	0.2500	2.28	54	n/a
40			18.01	n/a	7.32	10.00	9.06	5.91	8.72	5.91	0.59	1.6250	0.3750	2.68	69.5	n/a
50			19.11	n/a	7.32	11.42	10.43	6.30	9.06	6.69	0.71	2.0000	0.5000	3.07	134.5	n/a

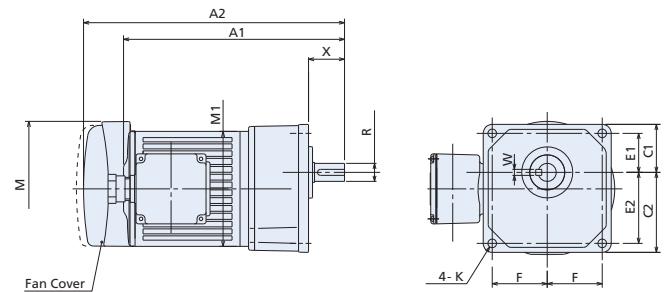
Frame	Motor/Brake-motor	Dwg	A1 (Motor)	A2 (Brake)	M	C1	C2	E1	E2	F	K	R	W	X	Motor Wt	Brake-motor Wt
32	3 Phase Std	1.16	16.56	17.36	7.32	2.81	4.98	2.30	4.47	3.39	0.51	1.2500	0.2500	2.36	55	63
32	3 Phase IP-65	1.16	16.56	n/a	7.32	2.81	4.98	2.30	4.47	3.39	0.51	1.2500	0.2500	2.36	55	n/a

Dwg. 1.15 (2 Hp)



Note: Terminal box or lead wire dim see Page 15.

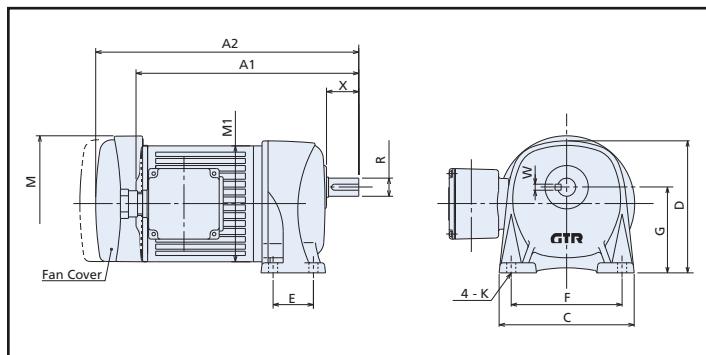
Dwg. 1.16 (2 Hp)



Note: Terminal box or lead wire dim see Page 15.

Frame	Motor/Brake-motor	Dwg	A1 (Motor)	A2 (Brake)	M	C1	C2	E1	E2	F	K	R	W	X	Motor Wt	Brake-motor Wt
40	3 Phase Std	1.17	18.37	19.17	7.32	10.00	9.06	5.91	8.72	5.91	0.59	1.6250	0.3750	2.68	76	84
50			20.10	20.91	7.32	11.42	10.43	6.30	9.06	6.69	0.71	2.0000	0.5000	3.07	142	150
40	3 Phase IP-65	1.17	18.37	n/a	7.32	10.00	9.06	5.91	8.72	5.91	0.59	1.6250	0.3750	2.68	76	n/a
50			20.10	n/a	7.32	11.42	10.43	6.30	9.06	6.69	0.71	2.0000	0.5000	3.07	142	n/a

Dwg. 1.17 (3 Hp)



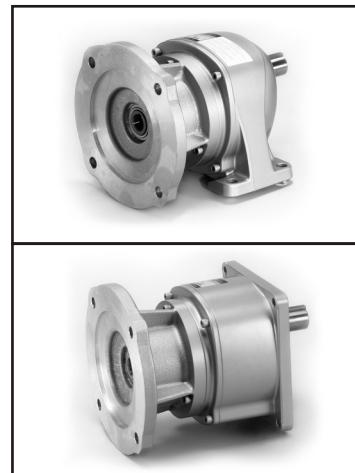
Note: Terminal box or lead wire dim see Page 15.

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Spec Table 1.6

Hp	Frame	Specifications				Dimensional Drawings Page 29	
		Ratio X:1 GR	Nominal RPM n	Torque (in-lbs) TR	O.H.L. (lbs) OHL	Foot	Flange
1/4 Hp	18	5	360	45	55	Dwg 1.18	Dwg 1.19
		10	180	89	121		
		15	120	134	176		
		20	90	178	242		
		25	72	223	264		
	22	30	60	268	341	Dwg 1.18	Dwg 1.19
		40	45	346	352		
		50	36	432	363		
		60	30	519	374		
		80	22.5	691	385		
	28	100	18	864	572	Dwg 1.18	Dwg 1.19
		120	15	1037	583		
		160	11.2	1383	605		
		200	9	1728	616		
1/2 Hp	22	5	360	89	88	Dwg 1.18	Dwg 1.19
		10	180	178	176		
		15	120	268	242		
		20	90	357	308		
		25	72	446	330		
	28	30	60	535	484	Dwg 1.18	Dwg 1.19
		40	45	691	506		
		50	36	864	528		
		60	30	1037	550		
		80	22.5	1383	572		
	32	100	18	1728	1030	Dwg 1.18	Dwg 1.19
		120	15	2074	1060		
		160	11.2	2765	1120		
		200	9	3457	1140		
1 Hp	28	5	360	167	110	Dwg 1.18	Dwg 1.19
		10	180	335	220		
		15	120	502	308		
		20	90	669	396		
		25	72	837	440		
	32	30	60	1004	891	Dwg 1.18	Dwg 1.19
		40	45	1296	935		
		50	36	1620	968		
		60	30	1944	990		
		80	22.5	2593	1010		
	40	100	18	3241	1450	Dwg 1.18	Dwg 1.19
		120	15	3889	1480		
		160	11.2	5185	1550		
		200	9	6481	1580		



Model Number for Ordering

G3	L	18	N	005	-	N	C	K	X
Type	Mount Form	Frame	Shaft/Bore Arrangement	Gear Ratio		UL/CSA	Motor Type	Motor Power	Special Spec
G3: G3 Series	L: Foot Mount K: Flange Mount	18 22 28 32 40	N: Common Code	005 : 5:1 030 : 30:1 120 : 120:1		N: Common Code (no UL)	C: NEMA 56CReducer	K: 1/4 HP L: 1/2 HP M: 1 HP	Blank: Standard Type X: Special Spec Special Specs, consult Brother

CAD Drawings

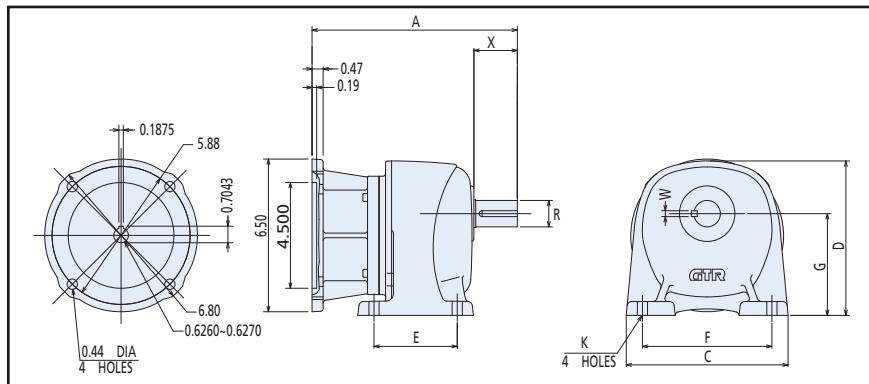
Go to www.BrotherGearmotors.com and enter the desired model number in the configurator. DXF, 3D, and PDF files are available to view or download.

Brother In-line Mid Series Gear Reducers

GEAR REDUCER DATA

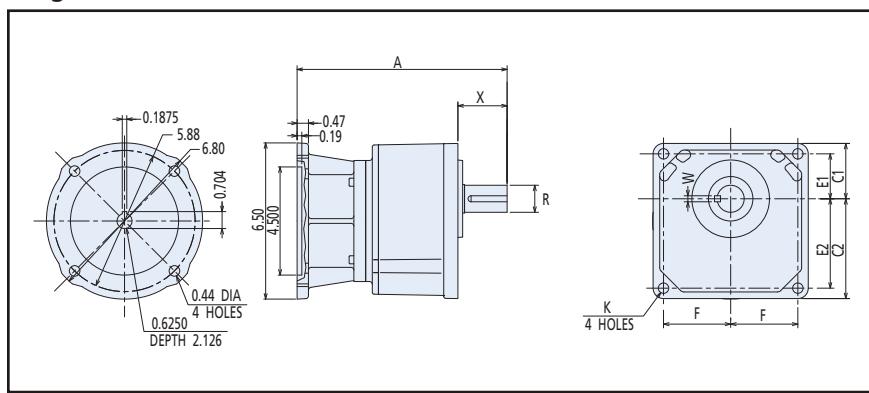
Hp	Frame	Dwg	A	C	D	E	F	G	K	R	W	X	Wt
1/4 Hp	18	1.18	6.97	5.28	5.16	1.57	4.33	3.35	0.35	0.7500	0.1875	1.26	8
	22		7.99	6.06	5.47	2.56	5.12	3.54	0.43	0.8750	0.1875	1.65	10
	28		8.51	6.89	6.57	3.54	5.51	4.33	0.43	1.1250	0.2500	1.85	14
1/2 Hp	22	1.18	8.11	6.06	5.47	2.56	5.12	3.54	0.43	0.8750	0.1875	1.65	10
	28		8.74	6.89	6.57	3.54	5.51	4.33	0.43	1.1250	0.2500	1.85	14
	32		9.49	8.19	7.80	5.12	6.69	5.12	0.51	1.2500	0.2500	2.28	25
1 Hp	28	1.18	8.80	6.89	6.57	3.54	5.51	4.33	0.43	1.1250	0.2500	1.85	14
	32		9.95	8.19	7.80	5.12	6.69	5.12	0.51	1.2500	0.2500	2.28	25
	40		10.81	10.00	9.06	5.91	8.72	5.91	0.59	1.6250	0.3750	2.68	40

Dwg. 1.18



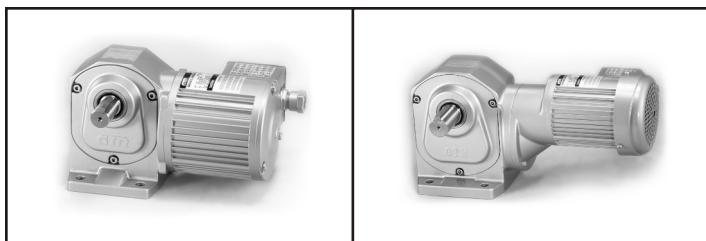
Hp	Frame	Dwg	A	C1	C2	E1	E2	F	K	R	W	X	Wt
1/4 Hp	18	1.19	6.97	1.89	3.15	1.54	2.8	2.17	0.34	0.7500	0.1875	1.38	9
	22		7.99	2.01	3.5	1.65	3.15	2.40	0.34	0.8750	0.1875	1.85	11
	28		8.51	2.30	4.15	1.87	3.72	2.80	0.43	1.1250	0.2500	1.97	15
1/2 Hp	22	1.19	8.11	2.01	3.5	1.65	3.15	2.40	0.34	0.8750	0.1875	1.85	12
	28		8.74	2.30	4.15	1.87	3.72	2.80	0.43	1.1250	0.2500	1.97	16.5
	32		9.49	2.81	4.98	2.30	4.47	3.39	0.51	1.2500	0.2500	2.36	23
1 Hp	28	1.19	8.80	2.30	4.15	1.87	3.72	2.80	0.43	1.1250	0.2500	1.97	15.5
	32		9.95	2.81	4.98	2.30	4.47	3.39	0.51	1.2500	0.2500	2.36	23

Dwg. 1.19



Notes/Disclaimer:

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3. Prints are available online using the Brother configurator by entering the complete part number. See www.BrotherGearmotors.com



Spec Table 2.1

Specifications						Dimensional Drawings Page 31					
Hp	Frame	Ratio X:1 GR	Nominal RPM n	Torque (in-lbs) TR	O.H.L. (lbs) OHL	1 Phase Std	Motor 3 Phase Std	3 Phase IP-65	1 Phase Std	3 Phase Std	Brakemotor 3 Phase IP-65
1/8 Hp	22	5	360	21	132	Dwg 2.1	Dwg 2.1	Dwg 2.1	Dwg 1.9	Dwg 1.9	Dwg 1.9
		10	170	42	209						
		15	120	63	232						
		20	90	85	265						
		25	72	106	287						
		30	60	127	309						
		40	45	169	353						
		50	36	211	386						
		60	30	254	397						
		80	22.5	328	397						
		100	18	410	397						
		120	15	491	397						
	28	160	11.2	655	397	Dwg 2.2	Dwg 2.2	Dwg 2.2	Dwg 2.2	Dwg 2.2	Dwg 2.2
		200	9	819	397						
		240	7.5	983	397						
1/2 Hp	32	300	6	1069	639	Dwg 2.2	Dwg 2.2	Dwg 2.2	Dwg 2.2	Dwg 2.2	Dwg 2.2
		375	4.8	1336	639						
		450	4	1603	639						
	32	600	3	2113	926	Dwg 2.2	Dwg 2.2	Dwg 2.2	Dwg 2.2	Dwg 2.2	Dwg 2.2
		750	2.4	2642	926						
		900	2	3170	926						
		1200	1.5	3819	926						
		1500	1.2	3818	926						

Model Number for Ordering-Single Phase

H2	L	22	L	005	-	B	M	H	1	A	X
Type	Mount Form	Frame	Shaft/Bore Arrangement	Gear Ratio		UL/CSA	Motor Type	Motor Power	Supply Voltage	Terminal Box/Leads ^{4,5}	Special Spec ^{5,6,7}
H2: H2 Series	L: Foot Mount	22 28 32	L: Left R: Right T: Both	005 : 5:1 030 : 30:1 900 : 900:1 12X : 1200:1		B: UL/CSA	M: Motor ¹ B: Brakemotor ^{1,2} J: Brakemotor ^{1,2} w/ manual release	H: 1/8 HP	1: 115V, 60Hz, 1ph 5: 220V, 60Hz, 1ph 6: 230V, 60Hz, 1ph 7: OEM Spec. 1ph ⁶	A: Die Cast N: Leads, (4.5 inch)	Blank: Standard Type X: Special Spec

Model Number for Ordering-Three Phase

H2	L	22	L	5	-	M	F	1	A	E	N	X
Type	Mount Form	Frame	Shaft/Bore Arrangement	Gear Ratio		Enclosure	Motor Type	Motor Power	Supply Voltage	Terminal Box ^{4,5}	Brake/Options	Special Spec ^{5,6,7}
H2: H2 Series	L: Foot Mount	22 28 32	"M" Enclosure L: Left R: Right T: Both "W" Enclosure H: Left M: Right B: Both	5 : 5:1 30 : 30:1 900 : 900:1 12X : 1200:1		M: IP-44 W: IP-65	F: 1/8 to 1/2 HP	1: 1/8 HP (100 W)	A: 208/230/400/460V 60/60/50/60 Hz	E: Die Cast	N: No Brake B2: 90VDC Brake B4: 180VDC Brake	Blank: Standard X: Special Spec

Notes:

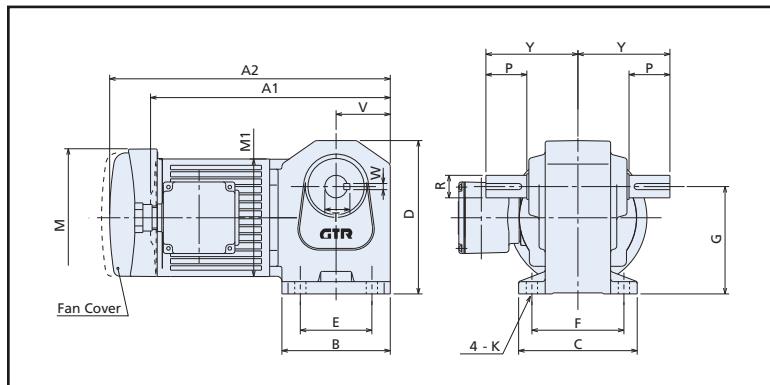
1. Motor and brakemotor electrical data shown on Page 10 Table 1.1 (3 Phase) and Page 11 Table 1.2 (1 Phase).
2. Brake electrical data shown on Pages 12~14.
3. Brother 3 Phase gearmotors are suitable for use with a VFD. See Page 17 for details.
4. See Page 15 for terminal box type or lead wire dimensional details.
5. Lead Wire or Terminal Box location: specify the code from Page 16, Fig 1.24A on your purchase order.
6. Special Voltage: specify the Voltage/Frequency from Page 10 Fig 1.4 (1 Phase) on your purchase order.
7. For any other special OEM requirement, please consult Brother.

Brother Rt-Angle Foot Mount Mid Series Gearmotors

GEARMOTOR DATA

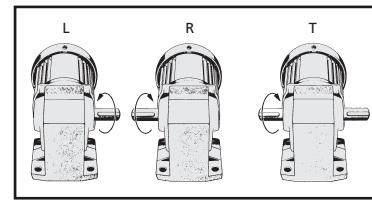
Frame	Motor/Brake-motor	Dwg	A1 (Motor)	A2 (Brake)	M1 (TENV) (Motor)	M (TEFC) (Brake)	B	C	D	E	F	G	K	V	Y	R	W	P	Motor Wt	Brake-motor Wt
22	3 Phase Std	2.1	9.23	10.81	4.53	5.31	4.17	4.57	5.91	2.76	3.54	4.13	0.43	2.09	3.54	0.8750	0.1875	1.57	14.25	17.5
	3 Phase IP-65	2.1	9.23	11.26	4.53	5.31	4.17	4.57	5.91	2.76	3.54	4.13	0.43	2.09	3.54	0.8750	0.1875	1.57	14.25	17.5
	1 Phase Std	2.1	10.46	10.81	n/a	5.31	4.17	4.57	5.91	2.76	3.54	4.13	0.43	2.09	3.54	0.8750	0.1875	1.57	14.25	17.5

Dwg. 2.1



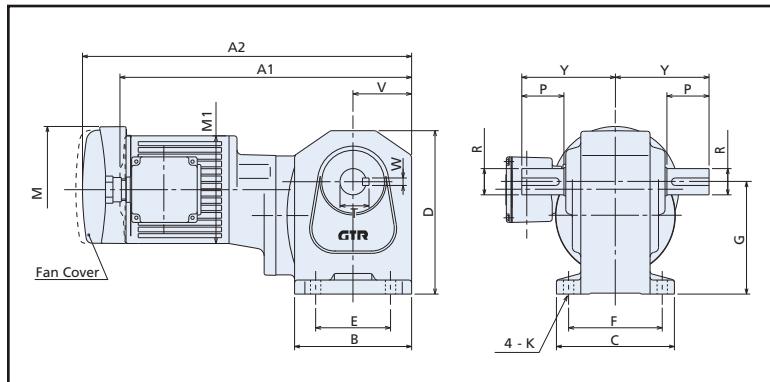
Note: Terminal box or lead wire dim see Page 15.

Fig. 2.1



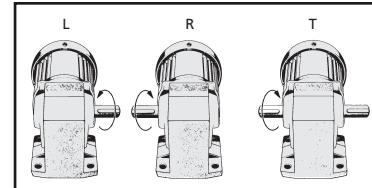
Frame	Motor/Brake-motor	Dwg	A1 (Motor)	A2 (Brake)	M1 (TENV) (Motor)	M (TEFC) (Brake)	B	C	D	E	F	G	K	V	Y	R	W	P	Motor Wt	Brake-motor Wt
28	3 Phase Std	2.2	12.26	13.49	4.53	5.31	4.92	4.96	6.87	3.15	3.94	4.72	0.43	2.46	3.94	1.1250	0.2500	1.77	22	25.25
	32		13.01	14.24	4.53	5.31	5.98	5.91	8.07	3.74	4.72	5.51	0.51	2.99	4.72	1.2500	0.2500	2.17	29	32
28	3 Phase IP-65	2.2	12.26	14.29	4.53	5.31	4.92	4.96	6.87	3.15	3.94	4.72	0.43	2.46	3.94	1.1250	0.2500	1.77	22	25.25
	32		13.01	15.04	4.53	5.31	5.98	5.91	8.07	3.74	4.72	5.51	0.51	2.99	4.72	1.2500	0.2500	2.17	29	32
28	1 Phase Std	2.2	13.49	13.84	n/a	5.31	4.92	4.96	6.87	3.15	3.94	4.72	0.43	2.46	3.94	1.1250	0.2500	1.77	22	25.25
	32		14.24	14.59	n/a	5.31	5.98	5.91	8.07	3.74	4.72	5.51	0.51	2.99	4.72	1.2500	0.2500	2.17	29	32

Dwg. 2.2



Note: Terminal box or lead wire dim see Page 15.

Fig. 2.1



Notes/Disclaimer:

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3. Prints are available online using the Brother configurator by entering the complete part number. See www.BrotherGearmotors.com



Spec Table 2.2

Specifications						Dimensional Drawings Page 33					
Hp	Frame	Ratio X:1 GR	Nominal RPM n	Torque (in-lbs) TR	O.H.L. (lbs) OHL	1 Phase Std	Motor 3 Phase Std	3 Phase IP-65	1 Phase Std	3 Phase Std	Brakemotor 3 Phase IP-65
1/4 Hp	22	5	360	42	132	Dwg 2.3	Dwg 2.3	Dwg 2.3	Dwg 2.3	Dwg 2.3	Dwg 2.3
		10	180	85	209						
		15	120	127	231						
		20	90	169	264						
		25	72	211	286						
		30	60	254	308						
		40	45	338	352						
		50	36	423	385						
	28	60	30	507	407	Dwg 2.3	Dwg 2.3	Dwg 2.3	Dwg 2.3	Dwg 2.3	Dwg 2.3
		80	22.5	654	550						
		100	18	817	594						
		120	15	981	616						
		160	11.2	1308	638						
		200	9	1634	638						
	32	240	7.5	1961	638	Dwg 2.4	Dwg 2.4	Dwg 2.4	Dwg 2.4	Dwg 2.4	Dwg 2.4
		300	6	2170	860						
		375	4.8	2712	926						
	40	450	4	3255	926	Dwg 2.4	Dwg 2.4	Dwg 2.4	Dwg 2.4	Dwg 2.4	Dwg 2.4
		600	3	4339	1521						
		750	2.4	5424	1521						
		900	2	6509	1521						
		1200	1.5	6770	1521						

Model Number for Ordering-Single Phase

H2	L	22	L	005	-	B	M	K	1	A	X
Type	Mount Form	Frame	Shaft/Bore Arrangement	Gear Ratio		UL/CSA	Motor Type	Motor Power	Supply Voltage	Terminal Box/Leads 4,5	Special Spec 5,6,7
H2: H2 Series	L: Foot Mount	22 28 32 40	L: Left R: Right T: Both	005 : 5:1 030 : 30:1 900 : 900:1 12X : 1200:1		B: UL/CSA	M: Motor 1 B: Brakemotor 1,2 J: Brakemotor 1,2 w/ manual release	K: 1/4 HP	1: 115V, 60Hz, 1ph 5: 220V, 60Hz, 1ph 6: 230V, 60Hz, 1ph 7: OEM Spec. 1ph 6	A: Die Cast N: Leads, (4.5 inch)	Blank: Standard Type X: Special Spec

Model Number for Ordering-Three Phase

H2	L	22	L	5	-	M	F	2	A	E	N	X
Type	Mount Form	Frame	Shaft/Bore Arrangement	Gear Ratio		Enclosure	Motor Type	Motor Power	Supply Voltage	Terminal Box 4,5	Brake/Options	Special Spec 5,6,7
H2: H2 Series	L: Foot Mount	22 28 32 40	"M" Enclosure L: Left R: Right T: Both "W" Enclosure H: Left M: Right B: Both	5 : 5:1 30 : 30:1 900 : 900:1 12X : 1200:1		M: IP-44 W: IP-65	F: 1/8 to 1/2 HP	2: 1/4 HP (200 W)	A: 208/230/400/460V 60/60/50/60 Hz	E: Die Cast	N: No Brake B2: 90VDC Brake B4: 180VDC Brake	Blank: Standard X: Special Spec

Notes:

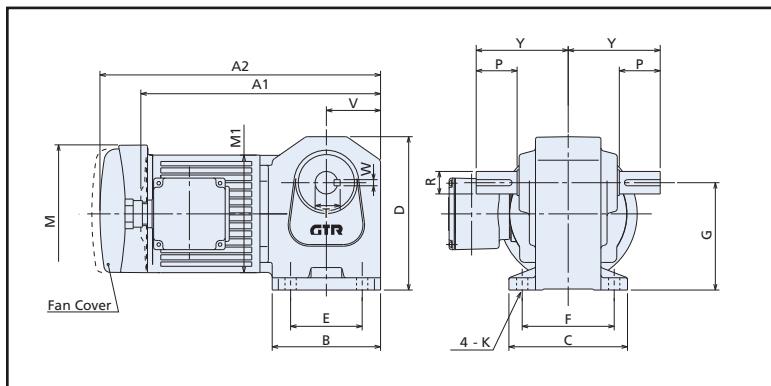
1. Motor and brakemotor electrical data shown on Page 10 Table 1.1 (3 Phase) and Page 11 Table 1.2 (1 Phase).
2. Brake electrical data shown on Pages 12~14.
3. Brother 3 Phase gearmotors are suitable for use with a VFD. See Page 17 for details.
4. See Page 15 for terminal box type or lead wire dimensional details.
5. Lead Wire or Terminal Box location: specify the code from Page 16, Fig 1.24A on your purchase order.
6. Special Voltage: specify the Voltage/Frequency from Page 10 Fig 1.4 (1 Phase) on your purchase order.
7. For any other special OEM requirement, please consult Brother.

Brother Rt-Angle Foot Mount Mid Series Gearmotors

GEARMOTOR DATA

Frame	Motor/Brake-motor	Dwg	A1 (Motor)	A2 (Brake)	M	B	C	D	E	F	G	K	V	Y	R	W	P	Motor Wt	Brake-motor Wt
22	3 Phase Std	2.3	11.04	11.71	5.31	4.17	4.57	5.91	2.76	3.54	4.13	0.43	2.09	3.54	0.8750	0.1875	1.57	16.5	20
28			11.54	12.20	5.31	4.92	4.96	6.87	3.15	3.94	4.72	0.43	2.46	3.94	1.1250	0.2500	1.77	21	24.25
22	3 Phase IP-65	2.3	11.04	12.99	5.31	4.17	4.57	5.91	2.76	3.54	4.13	0.43	2.09	3.54	0.8750	0.1875	1.57	16.5	20
28			11.54	13.48	5.31	4.92	4.96	6.87	3.15	3.94	4.72	0.43	2.46	3.94	1.1250	0.2500	1.77	21	24.25
22	1 Phase Std (Note)	2.3	13.01	13.68	5.31	4.17	4.57	5.91	2.76	3.54	4.13	0.43	2.09	3.54	0.8750	0.1875	1.57	21	24.25
28			13.50	14.17	5.31	4.92	4.96	6.87	3.15	3.94	4.72	0.43	2.46	3.94	1.1250	0.2500	1.77	25.5	28.75

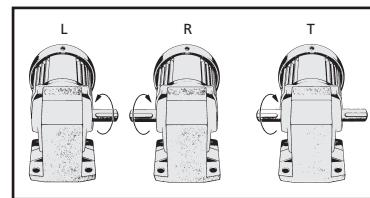
Dwg. 2.3



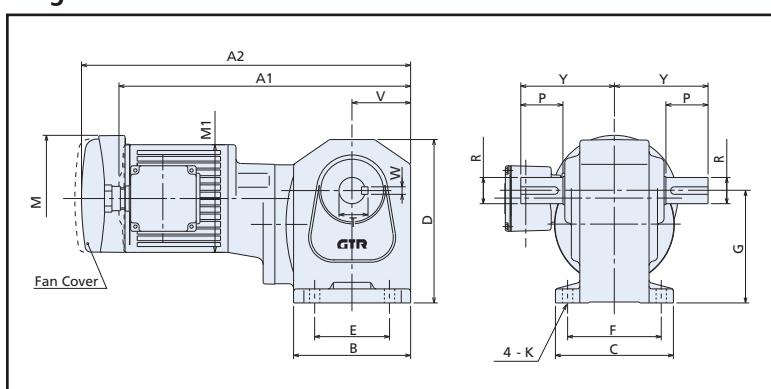
Note: Terminal box or lead wire dim see Page 15.

Note: 1 Phase Std motors have a capacitor mounted, see Page 11, Fig. 1.9.

Fig. 2.1



Dwg. 2.4



Note: Terminal box or lead wire dim see Page 15.

Note: 1 Phase Std motors have a capacitor mounted, see Page 11, Fig. 1.9.

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3. Prints are available online using the Brother configurator by entering the complete part number. See www.BrotherGearmotors.com



Spec Table 2.3

Specifications						Dimensional Drawings Page 35					
Hp	Frame	Ratio X:1 GR	Nominal RPM n	Torque (in-lbs) TR	O.H.L. (lbs) OHL	1 Phase Std	Motor 3 Phase Std	3 Phase IP-65	1 Phase Std	3 Phase Std	Brakemotor 3 Phase IP-65
1/2 Hp	28	5	360	85	209	Dwg 2.5	Dwg 2.5	Dwg 2.5	Dwg 2.5	Dwg 2.5	Dwg 2.5
		10	180	169	330						
		15	120	254	374						
		20	90	338	418						
		25	72	423	451						
		30	60	507	495						
		40	45	676	550						
		50	36	845	594						
	32	60	30	1014	616	Dwg 2.5	Dwg 2.5	Dwg 2.5	Dwg 2.5	Dwg 2.5	Dwg 2.5
		80	22.5	1308	770						
		100	18	1634	858						
		120	15	1961	924						
		160	11.2	2615	924						
		200	9	3269	924						
	40	240	7.5	3819	924	Dwg 2.6	Dwg 2.6	Dwg 2.6	Dwg 2.6	Dwg 2.6	Dwg 2.6
		300	6	4227	1521						
		375	4.8	5284	1521						
	50	450	4	6341	1521	Dwg 2.6	Dwg 2.6	Dwg 2.6	Dwg 2.6	Dwg 2.6	Dwg 2.6
		600	3	8455	2138						
		750	2.4	10568	2138						
		900	2	10850	2138						
		1200	1.5	10850	2138						

Model Number for Ordering-Single Phase

H2	L	28	L	005	-	B	M	L	1	S	X
Type	Mount Form	Frame	Shaft/Bore Arrangement	Gear Ratio		UL/CSA	Motor Type	Motor Power	Supply Voltage	Terminal Box/Leads 4,5	Special Spec 5,6,7
H2: H2 Series	L: Foot Mount	28 32 40 50	L: Left R: Right T: Both	005 : 5:1 030 : 30:1 900 : 900:1 12X : 1200:1		B: UL/CSA	M: Motor 1 B: Brakemotor 1,2 J: Brakemotor 1,2 w/ manual release	L: 1/2 HP	1: 115V, 60Hz, 1ph 5: 220V, 60Hz, 1ph 6: 230V, 60Hz, 1ph 7: OEM Spec. 1ph 6	S: Steel Box N: Leads, (4.5 inch)	Blank: Standard Type X: Special Spec

Model Number for Ordering-Three Phase

H2	L	28	L	5	-	M	F	4	A	E	N	X
Type	Mount Form	Frame	Shaft/Bore Arrangement	Gear Ratio		Enclosure	Motor Type	Motor Power	Supply Voltage	Terminal Box 4,5	Brake/Options	Special Spec 5,6,7
H2: H2 Series	L: Foot Mount	28 32 40 50	"M" Enclosure L: Left R: Right T: Both "W" Enclosure H: Left M: Right B: Both	5 : 5:1 30 : 30:1 900 : 900:1 12X : 1200:1		M: IP-44 W: IP-65	F: 1/8 to 1/2 HP	4: 1/2 HP (400 W)	A: 208/230/400/460V 60/60/50/60 Hz	E: Die Cast	N: No Brake B2: 90VDC Brake B4: 180VDC Brake	Blank: Standard X: Special Spec

Notes:

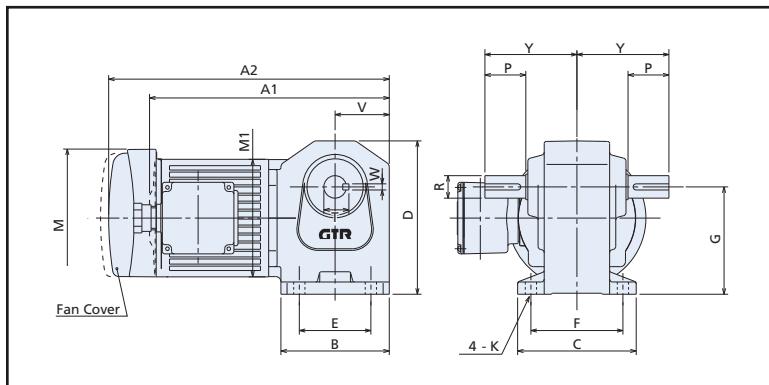
1. Motor and brakemotor electrical data shown on Page 10 Table 1.1 (3 Phase) and Page 11 Table 1.2 (1 Phase).
2. Brake electrical data shown on Pages 12~14.
3. Brother 3 Phase gearmotors are suitable for use with a VFD. See Page 17 for details.
4. See Page 15 for terminal box type or lead wire dimensional details.
5. Lead Wire or Terminal Box location: specify the code from Page 16, Fig 1.24A on your purchase order.
6. Special Voltage: specify the Voltage/Frequency from Page 10 Fig 1.4 (1 Phase) on your purchase order.
7. For any other special OEM requirement, please consult Brother.

Brother Rt-Angle Foot Mount Mid Series Gearmotors

GEARMOTOR DATA

Frame	Motor/Brake-motor	Dwg	A1 (Motor)	A2 (Brake)	M	B	C	D	E	F	G	K	V	Y	R	W	P	Motor Wt	Brake-motor Wt
28	3 Phase Std	2.5	12.81	13.58	5.55	4.92	4.96	6.87	3.15	3.94	4.72	0.43	2.46	3.94	1.1250	0.2500	1.77	24.25	27.5
			13.56	14.33	5.55	5.98	5.91	8.07	3.74	4.72	5.51	0.51	2.99	4.72	1.2500	0.2500	2.17	31	34.25
28	3 Phase IP-65	2.5	12.81	15.04	5.55	4.92	4.96	6.87	3.15	3.94	4.72	0.43	2.46	3.94	1.1250	0.2500	1.77	24.25	27.5
			13.56	15.79	5.55	5.98	5.91	8.07	3.74	4.72	5.51	0.51	2.99	4.72	1.2500	0.2500	2.17	31	27.5
28	1 Phase Std (Note)	2.5	15.85	16.12	6.38	4.92	4.96	6.87	3.15	3.94	4.72	0.43	2.46	3.94	1.1250	0.2500	1.77	36.5	42
			16.59	16.87	6.38	5.98	5.91	8.07	3.74	4.72	5.51	0.51	2.99	4.72	1.2500	0.2500	2.17	43	48.5

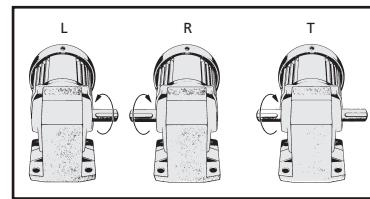
Dwg. 2.5



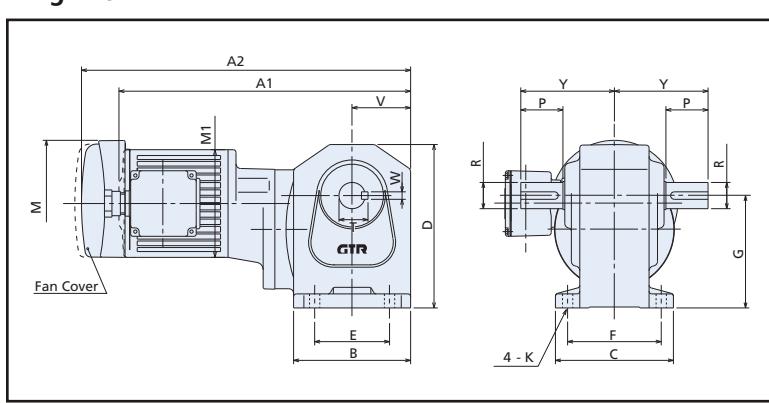
Note: Terminal box or lead wire dim see Page 15.

Note: 1 Phase Std motors have a capacitor mounted, see Page 11, Fig. 1.9.

Fig. 2.1



Dwg. 2.6



Note: Terminal box or lead wire dim see Page 15.

Note: 1 Phase Std motors have a capacitor mounted, see Page 11, Fig. 1.9.

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Spec Table 2.4

Specifications						Dimensional Drawings Page 37			
Hp	Frame	Ratio X:1 GR	Nominal RPM n	Torque (in-lbs) TR	O.H.L. (lbs) OHL	Motor		Brakemotor	
		3 Phase Std	3 Phase IP-65	3 Phase Std	3 Phase IP-65				
1 Hp	32	5	360	159	341	Dwg 2.7	Dwg 2.7	Dwg 2.7	Dwg 2.7
		10	180	317	451				
		15	120	476	495				
		20	90	634	550				
		25	72	793	616				
		30	60	951	660				
		40	45	1268	770				
		50	36	1585	858				
	40	60	30	1902	924	Dwg 2.7	Dwg 2.7	Dwg 2.7	Dwg 2.7
		80	22.5	2452	1300				
		100	18	3065	1360				
		120	15	3677	1410				
		160	11.2	4903	1450				
		200	9	6129	1500				
	50	240	7.5	6770	1500	Dwg 2.8	Dwg 2.8	Dwg 2.8	Dwg 2.8
		300	6	7926	1742				
		375	4.8	9908	1808				
		450	4	10850	1918				

Model Number for Ordering-Three Phase

H2	L	32	L	5	-	M	V	6	A	W	N	X
Type	Mount Form	Frame	Shaft/Bore Arrangement	Gear Ratio		Enclosure	Motor Type	Motor Power	Supply Voltage	Terminal Box 4,5	Brake/Options	Special Spec 5,6,7
H2: H2 Series	L: Foot Mount	32 40 50	"M" Enclosure L: Left R: Right T: Both "W" Enclosure H: Left M: Right B: Both	5 : 5:1 30 : 30:1 900 : 900:1 12X : 1200:1	M: IP-44 W: IP-65	V:1 to 3 HP	6: 1 HP (750 W)	A: 208/230/400/460V 60/60/50/60 Hz	W: Large Box with Terminal Block	N: No Brake B2: 90VDC Brake B4: 180VDC Brake	Blank: Standard	X: Special Spec

Notes:

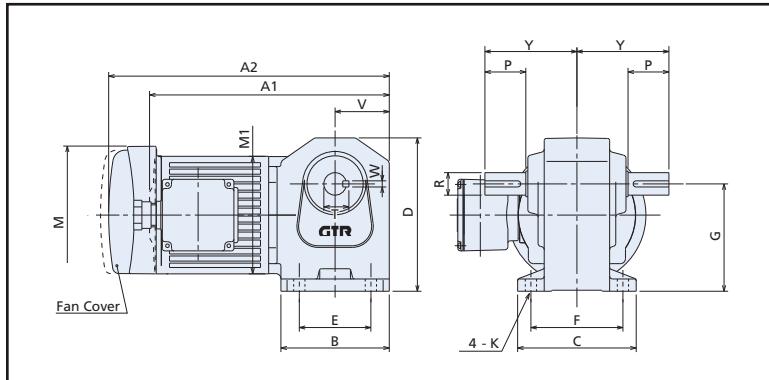
1. Motor and brakemotor electrical data shown on Page 10 Table 1.1 (3 Phase) and Page 11 Table 1.2 (1 Phase).
2. Brake electrical data shown on Pages 12~14.
3. Brother 3 Phase gearmotors are suitable for use with a VFD. See Page 17 for details.
4. See Page 15 for terminal box type or lead wire dimensional details.
5. Lead Wire or Terminal Box location: specify the code from Page 16, Fig 1.24A on your purchase order.
6. Special Voltage: specify the Voltage/Frequency from Page 10 Fig 1.4 (1 Phase) on your purchase order.
7. For any other special OEM requirement, please consult Brother.

Brother Rt-Angle Foot Mount Mid Series Gearmotors

GEARMOTOR DATA

Frame	Motor/ Brake- motor	Dwg	A1 (Motor)	A2 (Brake)	M	B	C	D	E	F	G	K	V	Y	R	W	P	Motor Wt	Brake- motor Wt
32	3 Phase Std	2.7	14.72	15.00	6.38	5.98	5.91	8.07	3.74	4.72	5.51	0.51	2.99	4.72	1.2500	0.2500	2.17	38.5	44
40			15.45	15.73	6.38	7.09	7.09	9.55	4.72	5.51	6.5	0.59	3.54	5.51	1.6250	0.3750	2.56	57.25	63
32	3 Phase IP-65	2.7	14.72	17.40	6.38	5.98	5.91	8.07	3.74	4.72	5.51	0.51	2.99	4.72	1.2500	0.2500	2.17	38.5	44
40			15.45	18.13	6.38	7.09	7.09	9.55	4.72	5.51	6.5	0.59	3.54	5.51	1.6250	0.3750	2.56	57.25	63

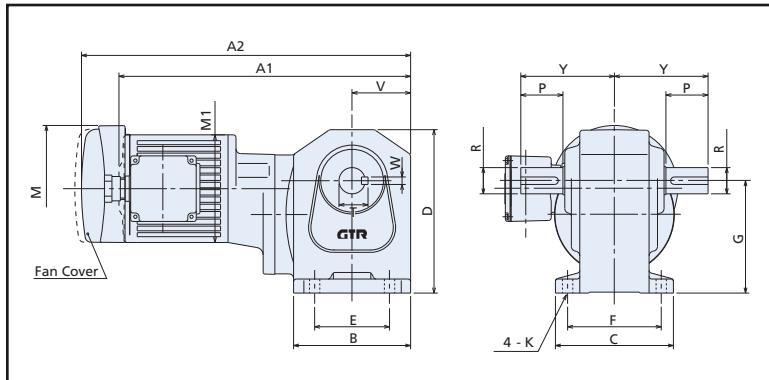
Dwg. 2.7



Note: Terminal box or lead wire dim see Page 15.

Frame	Motor/ Brake- motor	Dwg	A1 (Motor)	A2 (Brake)	M	B	C	D	E	F	G	K	V	Y	R	W	P	Motor Wt	Brake- motor Wt
50	3 Phase Std	2.8	19.90	20.18	6.38	8.27	9.06	12.13	5.91	7.09	7.87	0.71	4.13	6.5	2.0000	0.5000	2.95	129	134.5
50	3 Phase IP-65	2.8	19.90	22.58	6.38	8.27	9.06	12.13	5.91	7.09	7.87	0.71	4.13	6.5	2.0000	0.5000	2.95	129	134.5

Dwg. 2.8

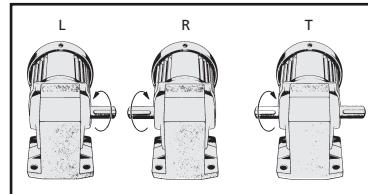


Note: Terminal box or lead wire dim see Page 15.

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Fig. 2.1





Spec Table 2.5

Specifications						Dimensional Drawings Page 39			
Hp	Frame	Ratio X:1 GR	Nominal RPM n	Torque (in-lbs) TR	O.H.L. (lbs) OHL	Motor		Brakemotor	
		3 Phase Std	3 Phase IP-65	3 Phase Std	3 Phase IP-65				
2 Hp	40	5	360	321	595	Dwg 2.9	Dwg 2.9	Dwg 2.9	n/a
		10	180	633	794				
		15	120	954	992				
		20	90	1266	1058				
		25	72	1587	1147				
		30	60	1899	1191				
		40	45	2454	1257				
		50	36	3061	1323				
	50	60	30	3676	1367	Dwg 2.9	Dwg 2.9	Dwg 2.9	n/a
		80	22.5	4899	1918				
		100	18	6121	1985				
		120	15	7343	2029				
		160	11.2	9797	2095				
		200	9	10838	2139				
3 Hp	50	240	7.5	10838	2139	Dwg 2.10	Dwg 2.10	Dwg 2.10	n/a
		5	360	468	882				
		10	180	928	992				
		15	120	1396	1103				
		20	90	1855	1235				
		25	72	2324	1367				
		30	60	2783	1477				
		40	45	3563	1588				
		50	36	4491	1698				
		60	30	5384	1830				
		80	22.5	7187	1896				
		100	18	9017	1985				
		120	15	10751	1985				

Model Number for Ordering-Three Phase

H2	L	40	L	5	-	M	V	8	A	W	N	X
Type	Mount Form	Frame	Shaft/Bore Arrangement	Gear Ratio		Enclosure	Motor Type	Motor Power	Supply Voltage	Terminal Box 4,5	Brake/Options	Special Spec 5,6,7
H2: H2 Series	L: Foot Mount	40 50	"M" Enclosure L: Left R: Right T: Both "W" Enclosure H: Left M: Right B: Both	5 : 5:1 30 : 30:1 900 : 900:1 12X : 1200:1	M: IP-44 W: IP-65	V:1 to 3 HP	8: 2 HP (1.5 kW) 9: 3 HP (2.2 kW)	A: 208/230/400/460V 60/60/50/60 Hz	W: Large Box with Terminal Block	N: No Brake B2: 90VDC Brake B4: 180VDC Brake	Blank: Standard X: Special Spec	

Notes:

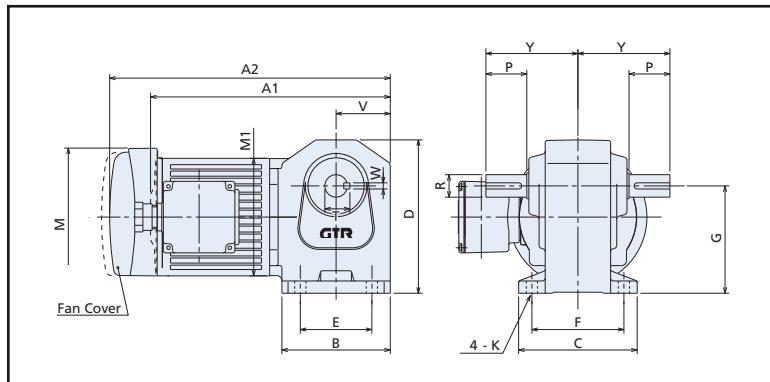
1. Motor and brakemotor electrical data shown on Page 10 Table 1.1 (3 Phase) and Page 11 Table 1.2 (1 Phase).
2. Brake electrical data shown on Pages 12~14.
3. Brother 3 Phase gearmotors are suitable for use with a VFD. See Page 17 for details.
4. See Page 15 for terminal box type or lead wire dimensional details.
5. Lead Wire or Terminal Box location: specify the code from Page 16, Fig 1.24A on your purchase order.
6. Special Voltage: specify the Voltage/Frequency from Page 10 Fig 1.4 (1 Phase) on your purchase order.
7. For any other special OEM requirement, please consult Brother.

Brother Rt-Angle Foot Mount Mid Series Gearmotors

GEARMOTOR DATA

Frame	Motor/ Brake- motor	Dwg	A1 (Motor)	A2 (Brake)	M	B	C	D	E	F	G	K	V	Y	R	W	P	Motor Wt	Brake- motor Wt
40	3 Phase Std	2.9	17.97	18.78	7.32	7.09	7.09	9.55	4.72	5.51	6.5	0.59	3.54	5.51	1.6250	0.3750	2.56	73	80.5
50			18.72	19.53	7.32	8.27	9.06	12.13	5.91	7.09	7.87	0.71	4.13	6.5	2.0000	0.5000	2.95	137	144.5
40	3 Phase IP-65	2.9	17.97	n/a	7.32	7.09	7.09	9.55	4.72	5.51	6.5	0.59	3.54	5.51	1.6250	0.3750	2.56	73	n/a
50			18.72	n/a	7.32	8.27	9.06	12.13	5.91	7.09	7.87	0.71	4.13	6.5	2.0000	0.5000	2.95	137	n/a

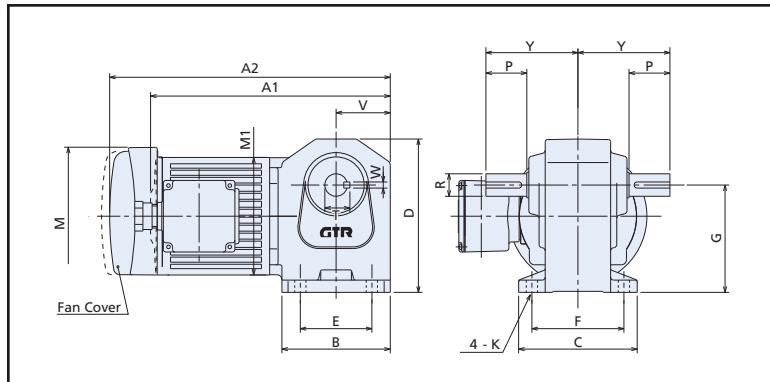
Dwg. 2.9 (2 Hp)



Note: Terminal box or lead wire dim see Page 15.

Frame	Motor/ Brake- motor	Dwg	A1 (Motor)	A2 (Brake)	M	B	C	D	E	F	G	K	V	Y	R	W	P	Motor Wt	Brake- motor Wt
50	3 Phase Std	2.8	19.90	20.18	6.38	8.27	9.06	12.13	5.91	7.09	7.87	0.71	4.13	6.5	2.0000	0.5000	2.95	129	134.5
50	3 Phase IP-65	2.8	19.90	22.58	6.38	8.27	9.06	12.13	5.91	7.09	7.87	0.71	4.13	6.5	2.0000	0.5000	2.95	129	134.5

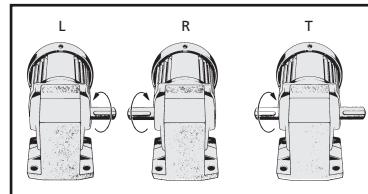
Dwg. 2.10 (3 Hp)



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Fig. 2.1



Spec Table 2.6

Specifications						Dimensional Drawings Page 41
Hp	Frame	Ratio X:1 GR	Nominal RPM n	Torque (in-lbs) TR	O.H.L. (lbs) OHL	
1/4 Hp	22	5	360	42	132	Dwg 2.11
		10	180	85	209	
		15	120	127	231	
		20	90	169	264	
		25	72	211	286	
		30	60	254	308	
		40	45	338	352	
		50	36	423	385	
	28	60	30	507	407	Dwg 2.11
		80	22.5	654	550	
		100	18	817	594	
		120	15	981	616	
		160	11.2	1308	638	
		200	9	1634	638	
1/2 Hp	28	240	7.5	1961	638	Dwg 2.11
		5	360	85	209	
		10	180	169	330	
		15	120	254	374	
		20	90	338	418	
		25	72	423	451	
		30	60	507	495	
		40	45	676	550	
	32	50	36	845	594	Dwg 2.11
		60	30	1014	616	
		80	22.5	1308	770	
		100	18	1634	858	
		120	15	1961	924	
		160	11.2	2615	924	
1 Hp	32	200	9	3269	924	Dwg 2.11
		240	7.5	3819	924	
	40	5	360	159	341	Dwg 2.11
		10	180	317	451	
		15	120	476	495	
		20	90	634	550	
		25	72	793	616	
		30	60	951	660	
		40	45	1268	770	
		50	36	1585	858	
		60	30	1902	924	
		80	22.5	2452	1300	Dwg 2.11
		100	18	3065	1360	
		120	15	3677	1410	
		160	11.2	4903	1450	
		200	9	6129	1500	
		240	7.5	6770	1500	



Model Number for Ordering

H2	L	22	R	012	-	N	C	K	X
Type	Mount Form	Frame	Shaft/Bore Arrangement	Gear Ratio		UL/CSA	Motor Type	Motor Power	Special Spec
H2: H2 Series	L: Foot Mount	22 28 32 40	R: Right Shaft L: Left Shaft T: Double Shaft Ref: Fig 2.2	005 : 5:1 030 : 30:1 120 : 120:1		N: Common Code (no UL)	C: NEMA 56CReducer	K: 1/4 HP L: 1/2 HP M: 1 HP	Blank: Standard Type X: Special Spec Special Specs, consult Brother

CAD Drawings

Go to www.BrotherGearmotors.com and enter the desired model number in the configurator. DXF, 3D, and PDF files are available to view or download.

Brother Rt-Angle Foot Mount Mid Series Gear Reducers

GEAR REDUCER DATA

Hp	Frame	Dwg	A	B	C	D	E	F	G	K	V	Y	R	W	P	Wt
1/4 Hp	22	2.11	7.50	4.17	4.57	5.91	2.76	3.54	4.13	0.43	2.09	3.54	0.8750	0.1875	1.57	10
	28		7.99	4.92	4.96	6.87	3.15	3.94	4.72	0.43	2.46	3.94	1.1250	0.2500	1.77	14
1/2 Hp	28	2.11	8.56	4.92	4.96	6.87	3.15	3.94	4.72	0.43	2.46	3.94	1.1250	0.2500	1.77	14
	32		9.31	5.98	5.91	8.07	3.74	4.72	5.51	0.51	2.99	4.72	1.2500	0.2500	2.17	20
1 Hp	32	2.11	9.31	5.98	5.91	8.07	3.74	4.72	5.51	0.51	2.99	4.72	1.2500	0.2500	2.17	20
	40		10.46	7.09	7.09	9.55	4.72	5.51	6.5	0.59	3.54	5.51	1.6250	0.3750	2.56	43

Dwg. 2.11

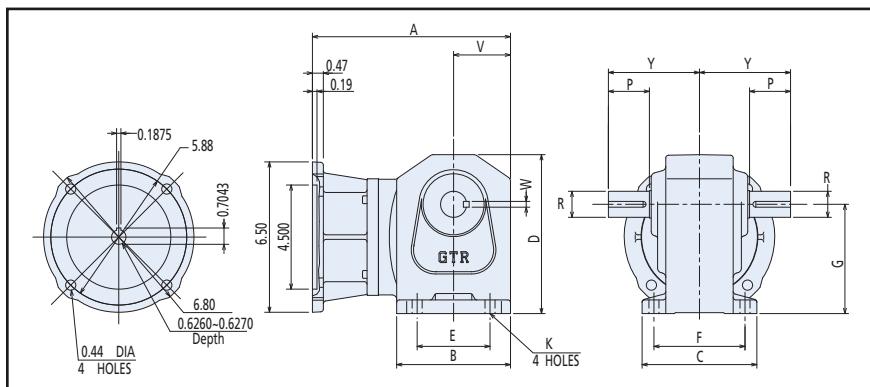
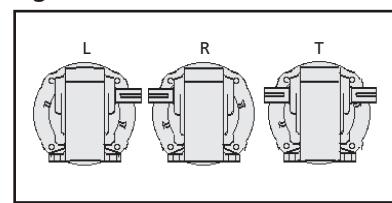


Fig. 2.2



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Spec Table 3.1

Specifications						Dimensional Drawings Page 43					
Hp	Frame	Ratio X:1 GR	Nominal RPM n	Torque (in-lbs) TR	O.H.L. (lbs) OHL	1 Phase Std	Motor 3 Phase Std	3 Phase IP-65	1 Phase Std	3 Phase Std	Brakemotor 3 Phase IP-65
1/8 Hp	20	5	360	19	221	Dwg 3.1	Dwg 3.1	Dwg 3.1	Dwg 3.1	Dwg 3.1	Dwg 3.1
		7.5	240	28	243						
		10	170	38	265						
		12.5	144	48	287						
		15	120	58	298						
		20	90	76	331						
		25	72	97	353						
		30	60	115	375						
		40	45	159	408						
		50	36	195	419						
1/8 Hp	25	60	30	221	419	Dwg 3.1	Dwg 3.1	Dwg 3.1	Dwg 3.1	Dwg 3.1	Dwg 3.1
		80	22.5	283	573						
		100	18	363	573						
		120	15	434	573						
		160	11.2	584	573						
		200	9	717	573						
		240	7.5	867	573						
		300	6	974	706	n/a	Dwg 3.2	Dwg 3.2	n/a	Dwg 3.2	Dwg 3.2
		375	4.8	1213	706						
1/8 Hp	35	450	4	1460	816	n/a	Dwg 3.2	Dwg 3.2	n/a	Dwg 3.2	Dwg 3.2
		600	3	1832	816						
		750	2.4	2292	816						
1/8 Hp	45	900	2	2956	1169	n/a	Dwg 3.2	Dwg 3.2	n/a	Dwg 3.2	Dwg 3.2
		1200	1.5	3939	1169						
		55	1500	1.2	5213	2205	n/a	Dwg 3.2	Dwg 3.2	n/a	Dwg 3.2

Model Number for Ordering-Single Phase

F3	S	20	N	005	-	B	M	H	1	A	X
Type	Mount Form	Frame	Shaft/Bore Arrangement	Gear Ratio		UL/CSA	Motor Type	Motor Power	Supply Voltage	Terminal Box/Leads ^{4,5}	Special Spec ^{5,6,7,8}
F3: F3 Series	S: Hollow Bore	20 25 30 35 45 55	N: Common Code	005 : 5:1 030 : 30:1 900 : 900:1 12X : 1200:1		B: UL/CSA	M: Motor ¹ B: Brakemotor ^{1,2} J: Brakemotor ^{1,2} w/ manual release	H: 1/8 HP	1: 115V, 60Hz, 1ph 5: 220V, 60Hz, 1ph 6: 230V, 60Hz, 1ph 7: OEM Spec. 1ph ⁶	A: Die Cast N: Leads, (4.5 inch)	Blank: Standard Type X: Special Spec

Model Number for Ordering-Three Phase

F3	S	20	N	5	-	M	F	1	A	E	N	X
Type	Mount Form	Frame	Shaft/Bore Arrangement	Gear Ratio		Enclosure	Motor Type	Motor Power	Supply Voltage	Terminal Box ^{4,5}	Brake/Options	Special Spec ^{5,6,7,8}
F3: F3 Series	S: Hollow Bore	20 25 30 35 45 55	N: For use with "M" Enclosure S: For use with "W" Enclosure	5 : 5:1 30 : 30:1 900 : 900:1 12X : 1200:1		M: IP-44 W: IP-65	F: 1/8 to 1/2 HP	1: 1/8 HP (100 W)	A: 208/230/400/460V 60/60/50/60 Hz	E: Die Cast	N: No Brake B2: 90VDC Brake B4: 180VDC Brake	Blank: Standard X: Special Spec

Notes:

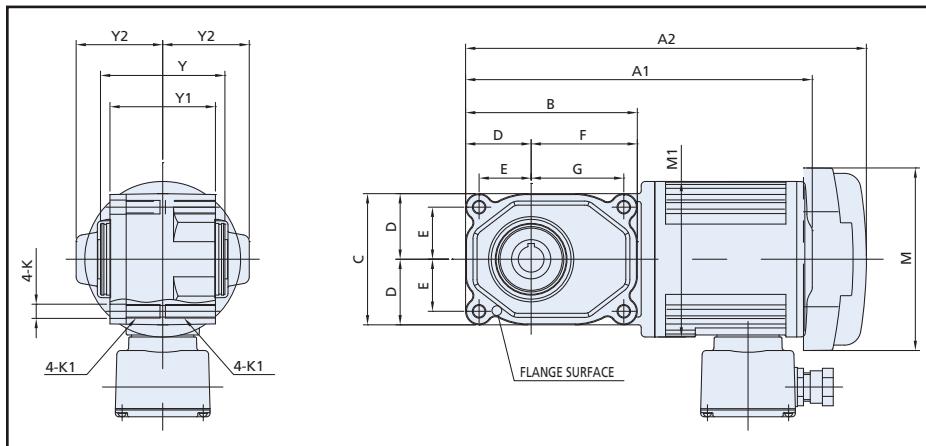
1. Motor and brakemotor electrical data shown on Page 10 Table 1.1 (3 Phase) and Page 11 Table 1.2 (1 Phase).
2. Brake electrical data shown on Pages 12~14.
3. Brother 3 Phase gearmotors are suitable for use with a VFD. See Page 17 for details.
4. See Page 15 for terminal box type or lead wire dimensional details.
5. Lead Wire or Terminal Box location: specify the code from Page 16, Fig 1.24A on your purchase order.
6. Special Voltage: specify the Voltage/Frequency from Page 10 Fig 1.4 (1 Phase) on your purchase order.
7. Special Bore Size: See Page 54, Fig 3.1 for available options.
8. For any other special OEM requirement, please consult Brother.

Brother Rt-Angle Hollow Bore Mid Series Gearmotors

GEARMOTOR DATA

Frame	Motor/ Brake- motor	Dwg	A1 (Motor)	A2 (Brake)	M1 (TENV) (Motor)	M (TEFC) (Brake)	B	C	D	E	F	G	K	K1	Y	Y1	Y2	Motor Wt	Brake- motor Wt
20	3 Phase Std	3.1	10.10	11.67	4.53	5.31	5.00	3.82	1.91	1.52	3.09	2.70	0.41	M10	3.62	3.07	2.52	13.25	16.5
				11.32	12.89	4.53	5.31	6.26	4.21	2.11	1.71	4.15	3.76	0.41	M10	4.49	3.94	3.11	17.75
20	3 Phase IP-65	3.1	10.10	12.13	4.53	5.31	5.00	3.82	1.91	1.52	3.09	2.70	0.41	M10	3.62	3.07	2.52	14.5	17.75
				11.32	13.35	4.53	5.31	6.26	4.21	2.11	1.71	4.15	3.76	0.41	M10	4.49	3.94	3.11	17.75
20	1 Phase Std	3.1	11.67	11.67	n/a	5.31	5.00	3.82	1.91	1.52	3.09	2.70	0.41	M10	3.62	3.07	2.52	13.25	16.5
				12.89	12.89	n/a	5.31	6.26	4.21	2.11	1.71	4.15	3.76	0.41	M10	4.49	3.94	3.11	17.75

Dwg. 3.1

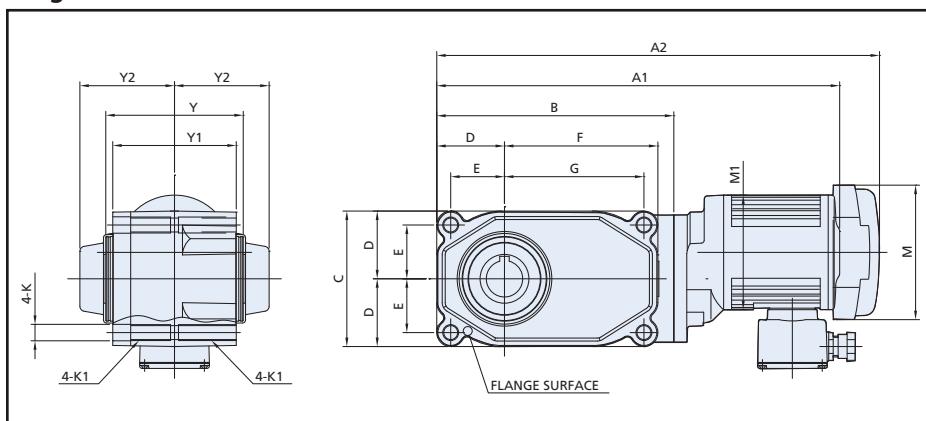


Note: Bore Dimensions see Page 54, Fig 3.1.

Terminal box or lead wire dim see Page 15.

Frame	Motor/ Brake- motor	Dwg	A1 (Motor)	A2 (Brake)	M1 (TENV) (Motor)	M (TEFC) (Brake)	B	C	D	E	F	G	K	K1	Y	Y1	Y2	Motor Wt	Brake- motor Wt
30	3 Phase Std	3.2	14.11	15.69	4.53	5.31	7.56	4.57	2.28	1.81	4.80	4.33	0.41	M10	4.72	4.17	3.23	23.25	26.5
			15.93	17.50	4.53	5.31	9.37	5.35	2.68	2.13	6.06	5.51	0.65	M16	5.43	4.88	3.74	31	34.25
			18.37	19.94	4.53	5.31	11.48	6.85	3.43	2.72	7.28	6.57	0.81	M20	6.46	5.91	4.25	46.5	49.75
			21.04	22.62	4.53	5.31	13.23	10.24	4.57	3.70	8.66	7.80	0.81	M20	8.50	7.87	5.63	168	171
30	1 Phase Std	3.2	14.11	16.14	4.53	5.31	7.56	4.57	2.28	1.81	4.80	4.33	0.41	M10	4.72	4.17	3.23	23.25	26.5
			15.93	17.95	4.53	5.31	9.37	5.35	2.68	2.13	6.06	5.51	0.65	M16	5.43	4.88	3.74	31	34.25
			18.37	20.39	4.53	5.31	11.48	6.85	3.43	2.72	7.28	6.57	0.81	M20	6.46	5.91	4.25	46.5	49.75
			21.04	22.62	4.53	5.31	13.23	10.24	4.57	3.70	8.66	7.80	0.81	M20	8.50	7.87	5.63	168	171

Dwg. 3.2



Note: Bore Dimensions see Page 54, Fig 3.1.

Terminal box or lead wire dim see Page 15.

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Spec Table 3.2

Specifications						Dimensional Drawings Page 45					
Hp	Frame	Ratio X:1 GR	Nominal RPM n	Torque (in-lbs) TR	O.H.L. (lbs) OHL	1 Phase Std	Motor 3 Phase Std	3 Phase IP-65	1 Phase Std	3 Phase Std	Brakemotor 3 Phase IP-65
1/4 Hp	25	5	360	41	276	Dwg 3.3	Dwg 3.3	Dwg 3.3	Dwg 3.3	Dwg 3.3	Dwg 3.3
		7.5	240	62	309						
		10	170	81	342						
		12.5	144	106	364						
		15	120	124	386						
		20	90	168	419						
		25	72	212	452						
		30	60	239	474						
		40	45	327	518						
		50	36	407	551						
	30	60	30	487	573						
		80	22.5	628	695	Dwg 3.3	Dwg 3.3	Dwg 3.3	Dwg 3.3	Dwg 3.3	Dwg 3.3
		100	18	770	706						
		120	15	929	706						
		160	11.2	1239	706						
		200	9	1549	706						
	35	240	7.5	1629	706	Dwg 3.4	Dwg 3.4	Dwg 3.4	Dwg 3.4	Dwg 3.4	Dwg 3.4
		300	6	2080	816						
	45	375	4.8	2602	816	Dwg 3.4	Dwg 3.4	Dwg 3.4	Dwg 3.4	Dwg 3.4	Dwg 3.4
		450	4	3124	1169						
		600	3	3948	1169						
	55	750	2.4	4930	1169	Dwg 3.4	Dwg 3.4	Dwg 3.4	Dwg 3.4	Dwg 3.4	Dwg 3.4
		900	2	6258	2205						
		1200	1.5	8346	2205						

Model Number for Ordering-Single Phase

F3	S	25	N	005	-	B	M	K	1	A	X
Type	Mount Form	Frame	Shaft/Bore Arrangement	Gear Ratio		UL/CSA	Motor Type	Motor Power	Supply Voltage	Terminal Box/Leads ^{4,5}	Special Spec ^{5,6,7,8}
F3: F3 Series	S: Hollow Bore	25 30 35 45 55	N: Common Code	005 : 5:1 030 : 30:1 900 : 900:1 12X : 1200:1		B: UL/CSA	M: Motor ¹ B: Brakemotor ^{1,2} J: Brakemotor ^{1,2} w/ manual release	K: 1/4 HP	1: 115V, 60Hz, 1ph 5: 220V, 60Hz, 1ph 6: 230V, 60Hz, 1ph 7: OEM Spec. 1ph ⁶	A: Die Cast N: Leads, (4.5 inch)	Blank: Standard Type X: Special Spec

Model Number for Ordering-Three Phase

F3	S	25	N	5	-	M	F	1	A	E	N	X
Type	Mount Form	Frame	Shaft/Bore Arrangement	Gear Ratio		Enclosure	Motor Type	Motor Power	Supply Voltage	Terminal Box ^{4,5}	Brake/Options	Special Spec ^{5,6,7,8}
F3: F3 Series	S: Hollow Bore	25 30 35 45 55	N: For use with "M" Enclosure S: For use with "W" Enclosure	5 : 5:1 30 : 30:1 900 : 900:1 12X : 1200:1		M: IP-44 W: IP-65	F: 1/8 to 1/2 HP	2: 1/4 HP (200 W)	A: 208/230/400/460V 60/60/50/60 Hz	E: Die Cast	N: No Brake B2: 90VDC Brake B4: 180VDC Brake	Blank: Standard X: Special Spec

Notes:

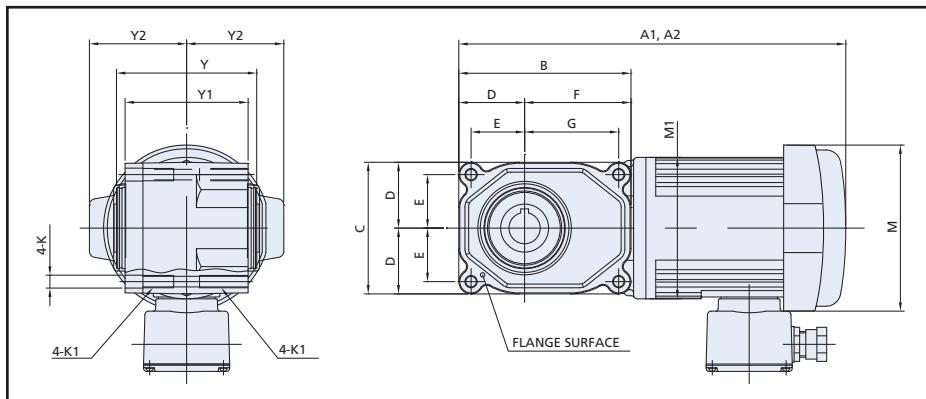
1. Motor and brakemotor electrical data shown on Page 10 Table 1.1 (3 Phase) and Page 11 Table 1.2 (1 Phase).
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5. Lead Wire or Terminal Box location: specify the code from Page 16, Fig 1.24A on your purchase order.
6. Special Voltage: specify the Voltage/Frequency from Page 10 Fig 1.4 (1 Phase) on your purchase order.
7. Special Bore Size: See Page 54, Fig 3.1 for available options.
8. For any other special OEM requirement, please consult Brother.

Brother Rt-Angle Hollow Bore Mid Series Gearmotors

GEARMOTOR DATA

Frame	Motor/ Brake- motor	Dwg	A1 (Motor)	A2 (Brake)	M	B	C	D	E	F	G	K	K1	Y	Y1	Y2	Motor Wt	Brake- motor Wt
25	3 Phase std	3.3	12.40	13.07	5.31	5.51	4.21	2.11	1.71	3.41	3.01	0.41	M10	4.49	3.94	3.11	18.75	22
30			13.96	14.63	5.31	7.09	4.57	2.28	1.81	4.80	4.33	0.49	M12	4.72	4.17	3.23	22	25.5
25	3 Phase IP-65	3.3	12.38	14.35	5.31	5.51	4.21	2.11	1.71	3.41	3.01	0.41	M10	4.49	3.94	3.11	18.75	22
30			13.94	15.91	5.31	7.09	4.57	2.28	1.81	4.80	4.33	0.49	M12	4.72	4.17	3.23	22	25.5
25	1 Phase Std (Note)	3.3	14.37	15.04	5.31	5.51	4.21	2.11	1.71	3.41	3.01	0.41	M10	4.49	3.94	3.11	25.5	28.75
30			15.96	16.59	5.31	7.09	4.57	2.28	1.81	4.80	4.33	0.49	M12	4.72	4.17	3.23	28.75	32

Dwg. 3.3

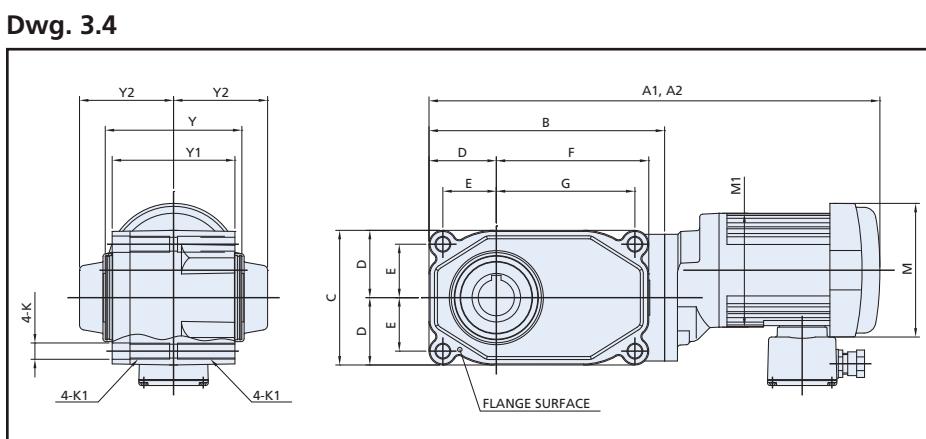


Note: Bore Dimensions see Page 54, Fig 3.1.

Terminal box or lead wire dim see Page 15.

Note: 1 Phase Std motors have a capacitor mounted, see Page 11, Fig. 1.9.

Dwg. 3.4



Note: Bore Dimensions see Page 54, Fig 3.1.

Terminal box or lead wire dim see Page 15.

Note: 1 Phase Std motors have a capacitor mounted, see Page 11, Fig. 1.9.

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Spec Table 3.3

Specifications						Dimensional Drawings Page 47					
Hp	Frame	Ratio X:1 GR	Nominal RPM n	Torque (in-lbs) TR	O.H.L. (lbs) OHL	1 Phase Std	Motor 3 Phase Std	3 Phase IP-65	1 Phase Std	Brakemotor 3 Phase Std	3 Phase IP-65
1/2 Hp	30	5	360	81	342	Dwg 3.5	Dwg 3.5	Dwg 3.5	Dwg 3.5	Dwg 3.5	Dwg 3.5
		7.5	240	124	397						
		10	170	168	430						
		12.5	144	212	463						
		15	120	239	485						
		20	90	327	540						
		25	72	407	573						
		30	60	487	595						
		40	45	655	639						
		50	36	814	673						
	35	60	30	982	695						
		80	22.5	1239	783	Dwg 3.5	Dwg 3.5	Dwg 3.5	Dwg 3.5	Dwg 3.5	Dwg 3.5
		100	18	1549	794						
		120	15	1868	794						
		160	11.2	2390	816						
		200	9	2390	816						
	45	240	7.5	2390	816						
		300	6	4169	1169	Dwg 3.6	Dwg 3.6	Dwg 3.6	Dwg 3.6	Dwg 3.6	Dwg 3.6
		375	4.8	5213	1169						
	55	450	4	6258	2205	Dwg 3.6	Dwg 3.6	Dwg 3.6	Dwg 3.6	Dwg 3.6	Dwg 3.6
		600	3	8346	2205						

Model Number for Ordering-Single Phase

F3	S	30	N	005	-	B	M	L	1	S	X
Type	Mount Form	Frame	Shaft/Bore Arrangement	Gear Ratio		UL/CSA	Motor Type	Motor Power	Supply Voltage	Terminal Box/Leads ^{4,5}	Special Spec ^{5,6,7,8}
F3: F3 Series	S: Hollow Bore	30 35 45 55	N: Common Code 005 : 5:1 030 : 30:1 900 : 900:1 12X : 1200:1	005 : 5:1 030 : 30:1 900 : 900:1 12X : 1200:1		B: UL/CSA	M: Motor ¹ B: Brakemotor ^{1,2} J: Brakemotor ^{1,2} w/ manual release	L: 1/2 HP	1: 115V, 60Hz, 1ph 5: 220V, 60Hz, 1ph 6: 230V, 60Hz, 1ph 7: OEM Spec. 1ph ⁶	S: Steel Box N: Leads, (4.5 inch)	Blank: Standard Type X: Special Spec

Model Number for Ordering-Three Phase

F3	S	30	N	5	-	M	F	4	A	E	N	X
Type	Mount Form	Frame	Shaft/Bore Arrangement	Gear Ratio		Enclosure	Motor Type	Motor Power	Supply Voltage	Terminal Box ^{4,5}	Brake/Options	Special Spec ^{5,6,7,8}
F3: F3 Series	S: Hollow Bore	30 35 45 55	N: For use with "M" Enclosure S: For use with "W" Enclosure	5 : 5:1 30 : 30:1 900 : 900:1 12X : 1200:1		M: IP-44 W: IP-65	F: 1/8 to 1/2 HP	4: 1/2 HP (400 W)	A: 208/230/400/460V 60/60/50/60 Hz	E: Die Cast	N: No Brake B2: 90VDC Brake B4: 180VDC Brake	Blank: Standard Type X: Special Spec

Notes:

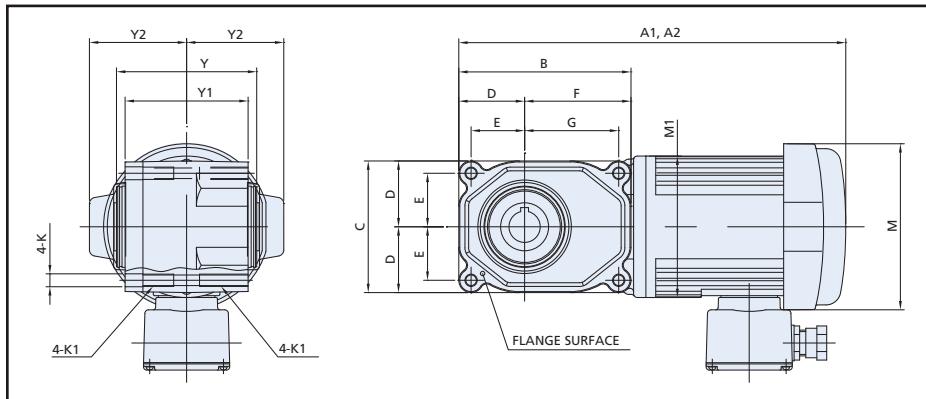
1. Motor and brakemotor electrical data shown on Page 10 Table 1.1 (3 Phase) and Page 11 Table 1.2 (1 Phase).
2. Brake electrical data shown on Pages 12~14.
3. Brother 3 Phase gearmotors are suitable for use with a VFD. See Page 17 for details.
4. See Page 15 for terminal box type or lead wire dimensional details.
5. Lead Wire or Terminal Box location: specify the code from Page 16, Fig 1.24A on your purchase order.
6. Special Voltage: specify the Voltage/Frequency from Page 10 Fig 1.4 (1 Phase) on your purchase order.
7. Special Bore Size: See Page 54, Fig 3.1 for available options.
8. For any other special OEM requirement, please consult Brother.

Brother Rt-Angle Hollow Bore Mid Series Gearmotors

GEARMOTOR DATA

Frame	Motor/ Brake- motor	Dwg	A1 (Motor)	A2 (Brake)	M	B	C	D	E	F	G	K	K1	Y	Y1	Y2	Motor Wt	Brake- motor Wt
30	3 Phase std	3.3	3.5	14.17	14.94	5.55	6.26	4.57	2.28	1.89	3.98	3.58	0.41	M10	4.72	4.17	3.23	25.5
35			3.5	16.48	17.24	5.55	8.74	5.35	2.68	2.13	6.06	5.51	0.65	M16	5.43	4.88	3.74	33
30	3 Phase IP-65	3.3	3.5	14.11	16.40	5.55	6.26	4.57	2.28	1.89	3.98	3.58	0.41	M10	4.72	4.17	3.23	25.5
35			3.5	16.42	18.70	5.55	8.74	5.35	2.68	2.13	6.06	5.51	0.65	M16	5.43	4.88	3.74	33
30	1 Phase Std (Note)	3.3	3.5	17.20	17.48	5.55	6.26	4.57	2.28	1.89	3.98	3.58	0.41	M10	4.72	4.17	3.23	38.75
35			3.5	19.51	19.78	5.55	8.74	5.35	2.68	2.13	6.06	5.51	0.65	M16	5.43	4.88	3.74	46.5

Dwg. 3.5



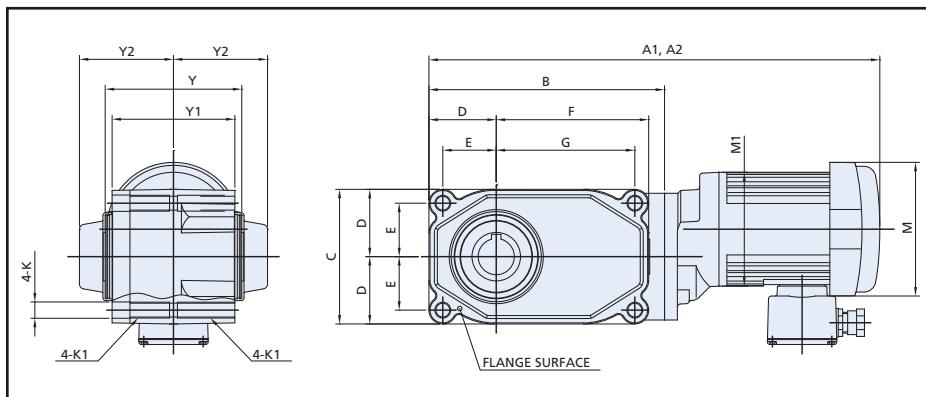
Note: Bore Dimensions see Page 54, Fig 3.1.

Terminal box or lead wire dim see Page 15.

Note: 1 Phase Std motors have a capacitor mounted, see Page 11, Fig. 1.9.

Frame	Motor/ Brake- motor	Dwg	A1 (Motor)	A2 (Brake)	M	B	C	D	E	F	G	K	K1	Y	Y1	Y2	Motor Wt	Brake- motor Wt
45	3 Phase std	3.6	21.14	21.91	5.55	11.48	6.85	3.43	2.72	7.28	6.57	0.81	M20	6.46	5.91	4.25	53	57.5
55			23.74	24.51	5.55	13.23	10.24	4.57	3.70	8.66	7.80	0.81	M20	8.50	7.87	5.63	174.25	178.75
45	3 Phase IP-65	3.6	21.08	23.37	5.55	11.48	6.85	3.43	2.72	7.28	6.57	0.81	M20	6.46	5.91	4.25	53	57.5
55			23.68	25.96	5.55	13.23	10.24	4.57	3.70	8.66	7.80	0.81	M20	8.50	7.87	5.63	174.25	178.75
45	1 Phase Std (Note)	3.6	24.17	24.45	6.38	11.48	6.85	3.43	2.72	7.28	6.57	0.81	M20	6.46	5.91	4.25	66.25	71.75
55			26.77	27.05	6.38	13.23	10.24	4.57	3.70	8.66	7.80	0.81	M20	8.50	7.87	5.63	187.5	193

Dwg. 3.6



Note: Bore Dimensions see Page 54, Fig 3.1.

Terminal box or lead wire dim see Page 15.

Note: 1 Phase Std motors have a capacitor mounted, see Page 11, Fig. 1.9.

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Spec Table 3.4

Specifications						Dimensional Drawings Page 48			
Hp	Frame	Ratio X:1 GR	Nominal RPM n	Torque (in-lbs) TR	O.H.L. (lbs) OHL	Motor		Brakemotor	
		3 Phase Std	3 Phase IP-65	3 Phase Std	3 Phase IP-65				
1 Hp	35	5	360	159	441	Dwg 3.7	Dwg 3.7	Dwg 3.7	Dwg 3.7
		7.5	240	221	507				
		10	170	301	551				
		12.5	144	381	584				
		15	120	460	617				
		20	90	620	673				
		25	72	761	717				
		30	60	921	739				
		40	45	1221	783				
		50	36	1531	783				
	45	60	30	1841	783	Dwg 3.7	Dwg 3.7	Dwg 3.7	Dwg 3.7
		80	22.5	2328	1069				
		100	18	2903	1069				
		120	15	3496	1069				
		160	11.2	4656	1169				
	55	200	9	4903	1169	Dwg 3.8	Dwg 3.8	Dwg 3.8	Dwg 3.8
		240	7.5	4903	1169				
		55	300	6	7824	2205	Dwg 3.8	Dwg 3.8	Dwg 3.8

Model Number for Ordering-Three Phase

F3	S	35	N	5	-	M	V	6	A	W	N	X
Type	Mount Form	Frame	Shaft/Bore Arrangement	Gear Ratio		Enclosure	Motor Type	Motor Power	Supply Voltage	Terminal Box ^{4,5}	Brake/Options	Special Spec ^{5,6,7,8}
F3: F3 Series	S: Hollow Bore	35 45 55	N: For use with "M" Enclosure S: For use with "W" Enclosure	5: 5:1 30 : 30:1 450 : 900:1	M: IP-44 W: IP-65	V: 1 to 3 HP	6: 1 HP (750 W)	A: 208/230/400/460V 60/60/50/60 Hz	W: Large Box with Terminal Block	N: No Brake B2: 90VDC Brake B4: 180VDC Brake	Blank: Standard X: Special Spec	

Notes:

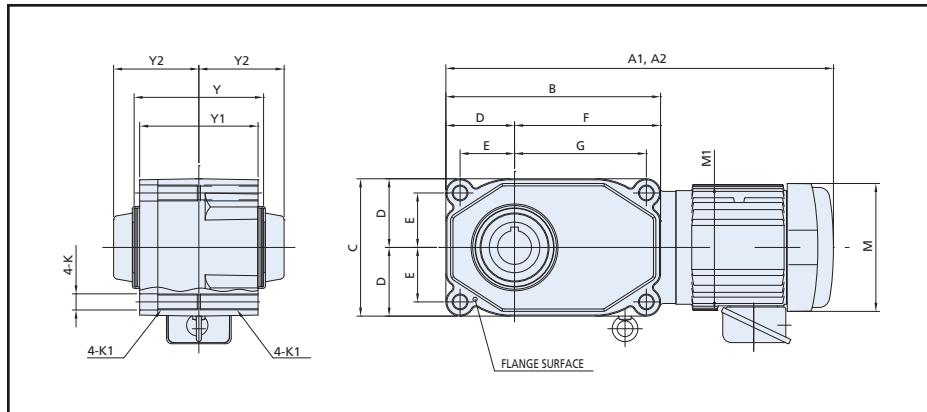
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6. Special Voltage: specify the Voltage/Frequency from Page 10 Fig 1.4 (1 Phase) on your purchase order.
7. Special Bore Size: See Page 54, Fig 3.1 for available options.
8. For any other special OEM requirement, please consult Brother.

Brother Rt-Angle Hollow Bore Mid Series Gearmotors

GEARMOTOR DATA

Frame	Motor/ Brake- motor	Dwg	A1 (Motor)	A2 (Brake)	M	B	C	D	E	F	G	K	K1	Y	Y1	Y2	Motor Wt	Brake- motor Wt
35	3 Phase std	3.7	16.00	16.28	6.38	7.28	5.35	2.68	2.20	4.61	4.13	0.49	M12	5.43	4.88	3.74	38.75	43
45			19.33	19.61	6.38	10.71	6.85	3.43	2.72	7.28	6.57	0.81	M20	6.46	5.91	4.25	55.25	59.5
35	3 Phase IP-65	3.7	15.94	18.68	6.38	7.28	5.35	2.68	2.20	4.61	4.13	0.49	M12	5.43	4.88	3.74	38.75	43
45			19.27	22.01	6.38	10.71	6.85	3.43	2.72	7.28	6.57	0.81	M20	6.46	5.91	4.25	55.25	59.5

Dwg. 3.7

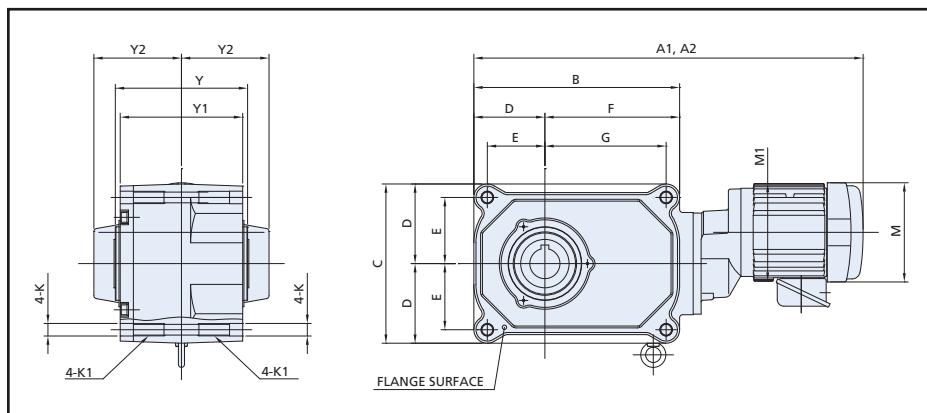


Note: Bore Dimensions see Page 54, Fig 3.1.

Terminal box or lead wire dim see Page 15.

Frame	Motor/ Brake- motor	Dwg	A1 (Motor)	A2 (Brake)	M	B	C	D	E	F	G	K	K1	Y	Y1	Y2	Motor Wt	Brake- motor Wt
55	3 Phase std	3.8	25.04	25.31	6.38	13.23	10.24	4.57	3.70	8.66	7.80	0.81	M20	8.50	7.87	5.63	181	187.5
55	3 Phase IP-65	3.8	24.98	27.72	6.38	13.23	10.24	4.57	3.70	8.66	7.80	0.81	M20	8.50	7.87	5.63	181	187.5

Dwg. 3.8



Note: Bore Dimensions see Page 54, Fig 3.1.

Terminal box or lead wire dim see Page 15.

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Spec Table 3.5

Hp	Frame	Specifications				Dimensional Drawings Page 51			
		Ratio X:1 GR	Nominal RPM n	Torque (in-lbs) TR	O.H.L. (lbs) OHL	Motor		Brakemotor	
		3 Phase Std	3 Phase IP-65	3 Phase Std	3 Phase IP-65				
2 Hp	45	5	360	301	662	Dwg 3.9	Dwg 3.9	Dwg 3.9	n/a
		7.5	240	460	750				
		10	170	620	816				
		12.5	144	761	882				
		15	120	921	915				
		20	90	1221	1003				
		25	72	1531	1058				
		30	60	1841	1069				
		40	45	2443	1069				
		50	36	3054	1069				
		60	30	3682	1069				
	55	80	22.5	4656	1444	Dwg 3.9	Dwg 3.9	Dwg 3.9	n/a
		100	18	5824	1444				
		120	15	6983	1687				
		160	11.2	9285	1874				
		200	9	11188	2029				
		240	7.5	11188	2205				
3 Hp	45	5	360	451	706	Dwg 3.10	Dwg 3.10	Dwg 3.10	n/a
		7.5	240	673	794				
		10	170	903	882				
		12.5	144	1115	926				
		15	120	1345	992				
		20	90	1797	1069				
		25	72	2248	1069				
	50	30	60	2700	1069	Dwg 3.10	Dwg 3.10	Dwg 3.10	n/a
		40	45	3594	1180				
		50	36	4496	1180				
	55	60	30	5390	1180	Dwg 3.10	Dwg 3.10	Dwg 3.10	n/a
		80	22.5	6824	1444				
		100	18	8532	1444				
		120	15	10232	1687				



Model Number for Ordering-Three Phase

F3	S	45	N	5	-	M	V	8	A	W	N	X
Type	Mount Form	Frame	Shaft/Bore Arrangement	Gear Ratio		Enclosure	Motor Type	Motor Power	Supply Voltage	Terminal Box 4,5	Brake/Options	Special Spec 5,6,7
F3: F3 Series	S: Hollow Bore	45 50 55	N: For use with "M" Enclosure S: For use with "W" Enclosure	5 : 5:1 30 : 30:1 200 : 200:1	M: IP-44 W: IP-65	V: 1 to 3 HP	8: 2 HP (1.5 kW)	A: 208/230/400/460V 60/60/50/60 Hz	W: Large Box with Terminal Block	N: No Brake B2: 90VDC Brake B4: 180VDC Brake	Blank: Standard X: Special Spec	

Notes:

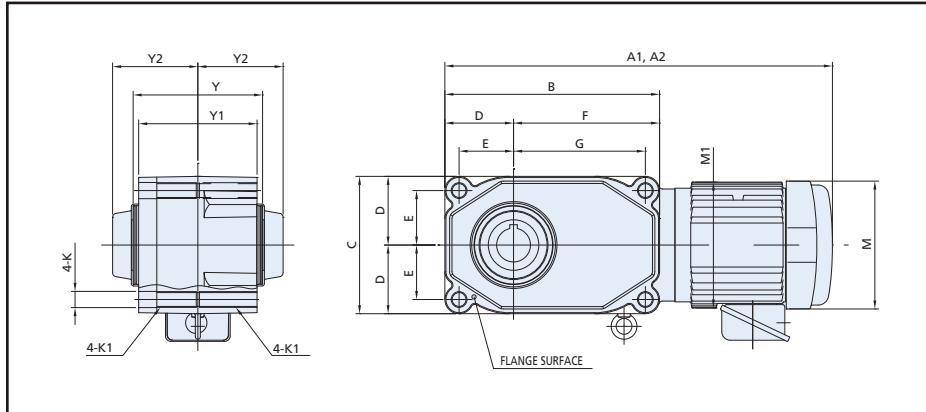
1. Motor and brakemotor electrical data shown on Page 10 Table 1.1 (3 Phase) and Page 11 Table 1.2 (1 Phase).
2. Brake electrical data shown on Pages 12~14.
3. Brother 3 Phase gearmotors are suitable for use with a VFD. See Page 17 for details.
4. See Page 15 for terminal box type or lead wire dimensional details.
5. Lead Wire or Terminal Box location: specify the code from Page 16, Fig 1.24A on your purchase order.
6. Special Voltage: specify the Voltage/Frequency from Page 10 Fig 1.4 (1 Phase) on your purchase order.
7. Special Bore Size: See Page 54, Fig 3.1 for available options.
8. For any other special OEM requirement, please consult Brother.

Brother Rt-Angle Hollow Bore Mid Series Gearmotors

GEARMOTOR DATA

Frame	Motor/ Brake- motor	Dwg	A1 (Motor)	A2 (Brake)	M	B	C	D	E	F	G	K	K1	Y	Y1	Y2	Motor Wt	Brake- motor Wt
45	3 Phase std	3.9	20.00	20.81	7.32	9.25	6.85	3.43	2.87	5.83	5.28	0.65	M16	6.46	5.91	4.25	70.5	77.25
55			23.56	24.37	7.32	13.23	10.24	4.57	3.70	8.66	7.80	0.81	M20	8.50	7.87	5.63	189.75	196.25
45	3 Phase IP-65	3.9	19.96	n/a	7.32	9.25	6.85	3.43	2.87	5.83	5.28	0.65	M16	6.46	5.91	4.25	70.5	n/a
55			23.52	n/a	7.32	13.23	10.24	4.57	3.70	8.66	7.80	0.81	M20	8.50	7.87	5.63	189.75	n/a

Dwg. 3.9 (2 Hp)

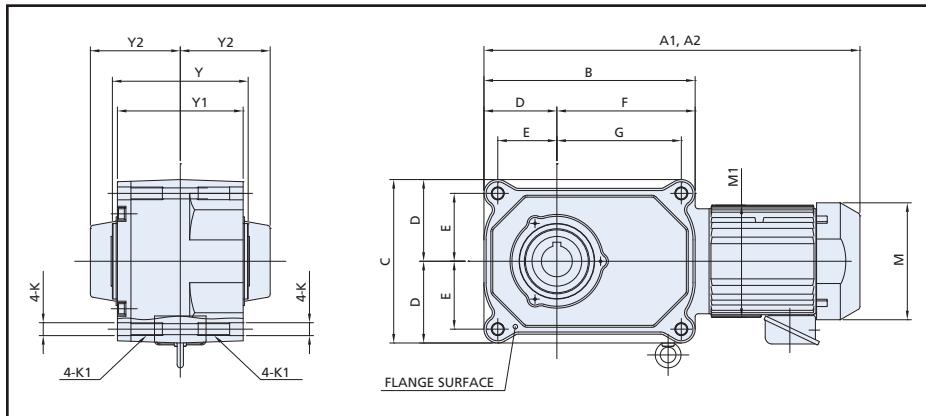


Note: Bore Dimensions see Page 54, Fig 3.1.

Terminal box or lead wire dim see Page 15.

Frame	Motor/ Brake- motor	Dwg	A1 (Motor)	A2 (Brake)	M	B	C	D	E	F	G	K	K1	Y	Y1	Y2	Motor Wt	Brake- motor Wt
45	3 Phase std	3.10	20.98	21.79	7.32	9.25	6.85	3.43	2.87	5.83	5.28	0.65	M16	6.46	5.91	4.25	77.25	84
50			24.09	24.90	7.32	11.97	8.35	4.65	4.02	7.32	6.69	0.65	M16	6.61	6.06	4.72	97	103.75
55			24.55	25.35	7.32	13.23	10.24	4.57	3.70	8.66	7.80	0.81	M20	8.50	7.87	5.63	200.75	207.25
45	3 Phase IP-65	3.10	20.94	n/a	7.32	9.25	6.85	3.43	2.87	5.83	5.28	0.65	M16	6.46	5.91	4.25	77.25	n/a
50			24.06	n/a	7.32	11.97	8.35	4.65	4.02	7.32	6.69	0.65	M16	6.61	6.06	4.72	97.00	n/a
55			24.51	n/a	7.32	13.23	10.24	4.57	3.70	8.66	7.80	0.81	M20	8.50	7.87	5.63	200.75	n/a

Dwg. 3.10 (3 Hp)



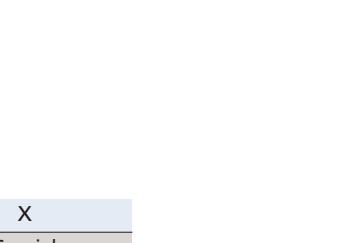
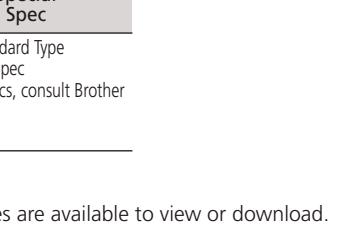
Note: Bore Dimensions see Page 54, Fig 3.1.

Terminal box or lead wire dim see Page 15.

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Spec Table 3.6

Hp	Frame	Specifications				Dimensional Drawings Page 53	NEMA 56C Reducer
		Ratio X:1 GR	Nominal RPM n	Torque (in-lbs) TR	O.H.L. (lbs) OHL		
1/4 Hp	25	5	360	41	276	Dwg 3.11	
		7.5	240	62	309		
		10	170	81	342		
		12.5	144	106	364		
		15	120	124	386		
		20	90	168	419		
		25	72	212	452		
		30	60	239	474		
		40	45	327	518		
		50	36	407	551		
	30	60	30	487	573	Dwg 3.11	
		80	22.5	628	695		
		100	18	770	706		
		120	15	929	706		
		160	11.2	1239	706		
		200	9	1549	706		
1/2 Hp	30	240	7.5	1629	706	Dwg 3.11	
		5	360	81	342		
		7.5	240	124	397		
		10	170	168	430		
		12.5	144	212	463		
		15	120	239	485		
		20	90	327	540		
		25	72	407	573		
		30	60	487	595		
		40	45	655	639		
	35	50	36	814	673	Dwg 3.11	
		60	30	982	695		
		80	22.5	1239	783		
		100	18	1549	794		
		120	15	1868	794		
		160	11.2	2390	816		
1 Hp	35	200	9	2390	816	Dwg 3.11	
		240	7.5	2390	816		
		5	360	159	441		
		7.5	240	221	507		
		10	170	301	551		
		12.5	144	381	584		
		15	120	460	617		
		20	90	620	673		
		25	72	761	717		
		30	60	921	739		
	45	40	45	1221	783	Dwg 3.11	
		50	36	1531	783		
		60	30	1841	783		
		80	22.5	2328	1069		
		100	18	2903	1069		
		120	15	3496	1069		

Model Number for Ordering

F3	S	25	N	012	-	N	C	K	X
Type	Mount Form	Frame	Shaft/Bore Arrangement	Gear Ratio		UL/CSA	Motor Type	Motor Power	Special Spec
F3: F3 Series	S: Hollow Bore	25 30 35 45	N: Common Code 005 : 5:1 007 : 7.5:1 012 : 12.5:1 030 : 30:1 120 : 120:1	005 : 5:1 007 : 7.5:1 012 : 12.5:1 030 : 30:1 120 : 120:1		N: Common Code (no UL)	C: NEMA 56C Reducer	K: 1/4 HP L: 1/2 HP M: 1 HP	Blank: Standard Type X: Special Spec Special Specs, consult Brother

CAD Drawings

Go to www.BrotherGearmotors.com and enter the desired model number in the configurator. DXF, 3D, and PDF files are available to view or download.

Special Specs

Notes:

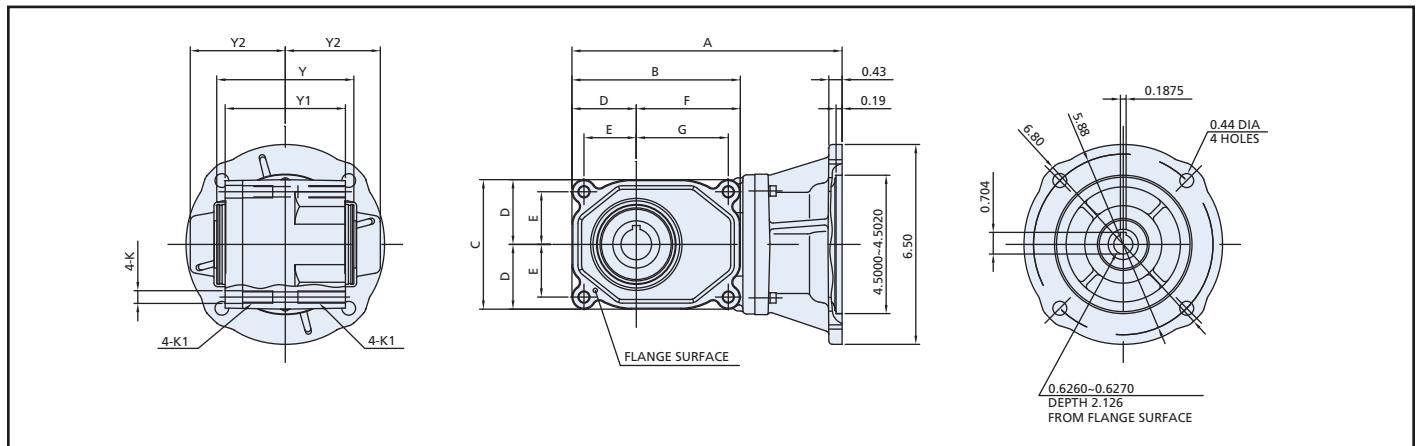
1. Special Bore Size: see Page 54, Fig 3.1 for available options.
2. For any other special OEM requirement, please consult Brother.

Brother Rt-Angle Hollow Bore Mid Series Gear Reducers

GEAR REDUCER DATA

Hp	Frame	Dwg	A	B	C	D	E	F	G	K (Hole)	K1 (Tap)	Y	Y1	Y2	Wt
1/4 Hp	25	3.11	8.86	5.51	4.21	2.11	1.71	3.41	3.01	0.41	M10	4.49	3.94	3.11	10
	30		10.42	7.09	4.57	2.28	1.81	4.80	4.33	0.49	M12	4.72	4.17	3.23	13.5
1/2 Hp	30	3.11	9.93	6.26	4.57	2.28	1.89	3.98	3.58	0.41	M10	4.72	4.17	3.23	13
	35		12.23	8.74	5.35	2.68	2.13	6.06	5.51	0.65	M16	5.43	4.88	3.74	20.75
1 Hp	35	3.11	11.01	7.28	6.85	3.43	2.72	7.28	6.57	0.81	M20	5.43	4.88	3.74	19
	45		14.34	10.71	6.85	3.43	2.72	7.28	6.57	0.81	M20	6.46	5.91	4.25	37.75

Dwg. 3.11



Note: Bore Dimensions see Page 54, Fig 3.1.

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Fig 3.1: Standard Bore and Optional Bore Dimensions

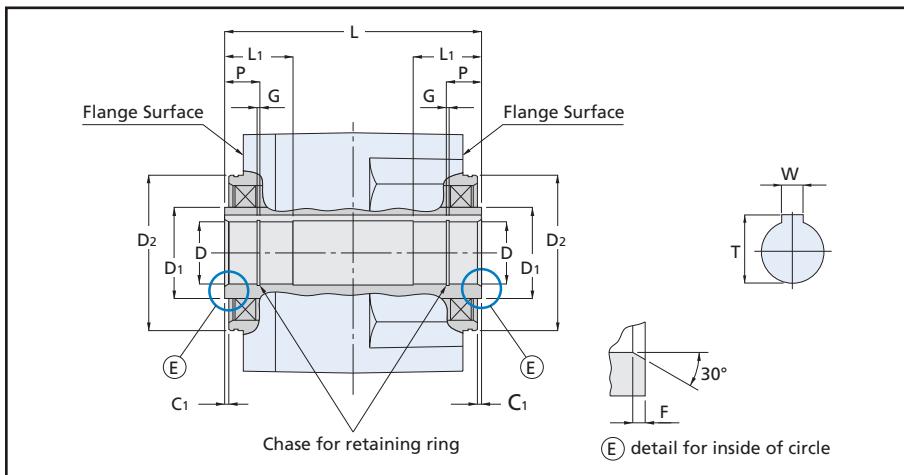


Fig 3.1 : Standard Bore and Optional Bore Dimensions

Frame	Standard or Option	Special Code (Note)	D	W	T	G	D1 in (mm)	D2 in (mm)	L in (mm)	L1 in (mm)	P in (mm)	C1 in (mm)	F in (mm)
F3S20	Standard		0.7500 in +0.0013/+0.0005	0.1875 in	0.838 in	0.039 in	1.1417 (29)	2.0866 in +0.0/-0.0012 (53 h7)	3.78 (96)	0.94 (24)	0.51 (13)	0.08 (2)	0.08 (2)
	Option	OJ	20 mm +0.033/+0.012	6 mm	22.8 mm	1.15 mm							
F3S25	Standard		1.0000 in +0.0013/+0.0005	0.2500 in	1.114 in	0.046 in	1.5354 (39)	2.5984 in +0.0/-0.0012 (66 h7)	4.65 (118)	1.06 (27)	0.55 (14)	0.08 (2)	0.08 (2)
	Option	F2	0.7500 in +0.0013/+0.0005	0.1875 in	0.838 in	0.039 in							
	Option	OJ	25 mm +0.033/+0.012	8 mm	28.3 mm	1.35 mm							
F3S30	Standard		1.2500 in +0.0013/+0.0005	0.2500 in	1.366 in	0.056 in	1.7323 (44)	2.9528 in +0.0/-0.0012 (75 h7)	4.88 (124)	1.3 (33)	0.67 (17)	0.08 (2)	0.08 (2)
	Option	F3	1.0000 in +0.0013/+0.0005	0.2500 in	1.114 in	0.046 in							
	Option	OJ	30 mm +0.033/+0.012	8 mm	33.3 mm	1.35 mm							
F3S35	Standard		1.2500 in +0.0013/+0.0005	0.2500 in	1.366 in	0.056 in	1.9291 (49)	3.3465 in +0.0/-0.0014 (85 h7)	5.59 (142)	1.5 (38)	0.79 (20)	0.08 (2)	0.08 (2)
	Option	F3	1.0000 in +0.0013/+0.0005	0.2500 in	1.114 in	0.046 in							
	Option	F5	1.3750 in +0.0015/+0.0007	0.3125 in	1.520 in	0.056 in							
	Option	FA	1.4375 in +0.0015/+0.0007	0.3750 in	1.606 in	0.056 in							
	Option	OJ	35 mm +0.039/+0.019	10 mm	38.3 mm	1.75 mm							
F3S45	Standard		1.3750 in +0.0015/+0.0007	0.3125 in	1.520 in	0.056 in	2.5197 (64)	3.9370 in +0.0/-0.0014 (100 h7)	6.61 (168)	1.97 (50)	1.02 (26)	0.08 (2)	0.08 (2)
	Option	F6	1.5000 in +0.0015/+0.0007	0.3750 in	1.669 in	0.056 in							
	Option	FB	1.6875 in +0.0015/+0.0007	0.3750 in	1.858 in	0.068 in							
	Option	OJ	45 mm +0.039/+0.019	14 mm	48.8 mm	1.95 mm							
F3S50	Standard		1.5000 in +0.0015/+0.0007	0.3750 in	1.669 in	0.056 in	2.9134 (74)	4.3307 in +0.0/-0.0014 (110 h7)	6.77 (172)	2.17 (55)	1.14 (29)	0.08 (2)	0.08 (2)
	Option	FC	1.9375 in +0.0015/+0.0007	0.5000 in	2.161 in	0.068 in							
	Option	OJ	50 mm +0.039/+0.019	14 mm	53.8 mm	2.20 mm							
F3S55	Standard		2.0000 in +0.0015/+0.0007	0.5000 in	2.224 in	0.068 in	3.1102 (79)	4.7244 in +0.0/-0.0014 (120 h7)	8.66 (220)	2.4 (61)	1.26 (32)	0.08 (2)	0.08 (2)
	Option	FC	1.9375 in +0.0015/+0.0007	0.5000 in	2.161 in	0.068 in							
	Option	OJ	55 mm +0.046/+0.021	16 mm	59.3 mm	2.20 mm							

Fig 3.2 : Metric Tolerances (mm)

Dimension	Bore : H7 (Ref D2)
Over 18~30 mm	+0.000/-0.021
Over 30~50 mm	+0.000/-0.030
Over 50~80 mm	+0.000/-0.035

F3S Type Hollow Shaft • Flange Mounted

When an F3S unit is flange mounted and used as the bearing support on one side of the driven load alignment should be precise to avoid burnout of the motor and/or damage to the bearings caused by misalignment.

- The F3 Series has a pilot D2 for guiding the attachment as shown in Fig. 3.1. The dimension tolerance for the bore φA is "h7". (Pilot D2 is inserted in φA)
- Four fixing bolts should be used as shown in Fig. 3.1 to assure a secure mount.

Fig 3.3: Flange Mounting

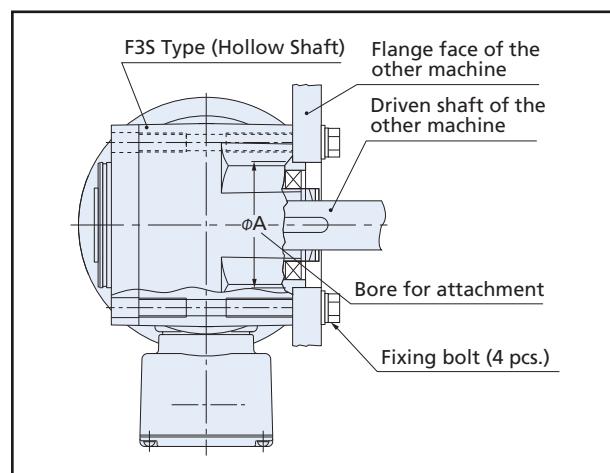
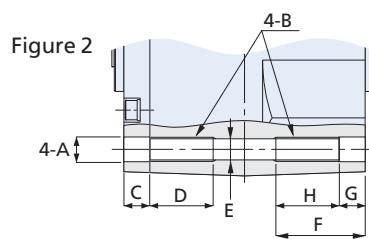
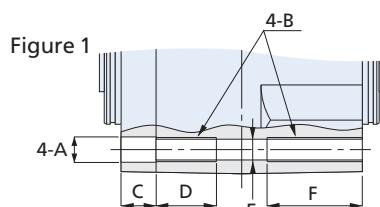
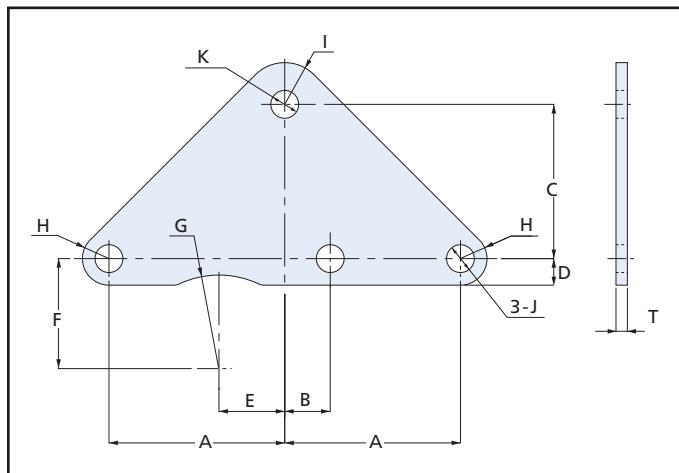


Fig 3.4: Mounting Hole Detail



Frame	Ratio	Hp	Figure	A	B	C	D	E	F	G	H
20	5:1~60:1	1/8 Hp				12			37		
25	5:1~60:1	1/4 Hp	Fig.3.4: Figure 1	10.5	M10xP1.5	14.5	25	8.6	39.5	n/a	n/a
	80:1~240:1	1/8 Hp				14.5			39.4		
30	5:1~60:1	1/2 Hp				15.5			40.5		
	80:1~240:1	1/4 Hp				15.5			45.5		
	300:1~375:1	1/8 Hp				15.8			45.5		
	5:1~60:1	1 Hp				18			48		
35	80:1~240:1	1/2 Hp		12.5	M12xP1.75	18	30	10.6	58	n/a	n/a
	300:1~375:1	1/4 Hp				18			58		
	450:1~750:1	1/8 Hp				18			58		
	5:1~60:1	2 Hp				23			63		
45	5:1~30:1	3 Hp		16.5	M16xP2	23	40	14	63	n/a	n/a
	80:1~240:1	1 Hp				18			58		
	300:1~375:1	1/2 Hp				18			58		
	450:1~750:1	1/4 Hp				18			58		
	900:1~1200:1	1/8 Hp				23			73		
	5:1~60:1	2 Hp				23					
50	40:1~60:1	3 Hp	Fig.3.4: Figure 2	16.6	M16xP2	19	40	14	59	19	40
55	80:1~240:1	2 Hp		20.5	M20xP2.5	21.5	50	17.5	71.5	21.5	50
	80:1~120:1	3 Hp									
	300:1	1 Hp									
	450:1~600:1	1/2 Hp									
	900:1~1200:1	1/4 Hp									
	1500:1	1/8 Hp									

Fig 3.5: Optional Torque Arm



Frame	Part Number	Hp	Reduction Ratio	A	B	C	D	E	F	G	H	I	J	K	T	Wt (lb)
F3S20	TAF3S-20-2	1/8 Hp	5:1~60:1	53.5	23.5	52	10.5	n/a	n/a	10.5	11	11	9	3.2	0.1	
F3S25	TAF3S-25-2	1/4 Hp	5:1~60:1	60	27	61	10.5	16.5	43.5	37	10.5	15	11	9	3.2	0.2
	TAF3S-25-3	1/8 Hp	80:1~240:1	69.5	17.5	61	10.5	26	43.5	37	10.5	6.5	11	11	4.5	0.2
F3S30	TAF3S-30-2	1/2 Hp	5:1~60:1	69.5	26.5	70	10.5	21.5	48	41.5	10.5	15	11	11	4.5	0.3
	TAF3S-30-3	1/8 Hp	300:1~375:1	78	14	70	12	32	46	41.5	12	16.5	13.5	13.5	6	0.4
		1/4 Hp	80:1~240:1													
F3S35	TAF3S-35-2	1 Hp	5:1~60:1	80.5	31.5	94	12	24.5	56	46.5	12	18	13.5	13.5	6	0.6
	TAF3S-35-3	1/8 Hp	450:1~750:1	97	11	94	15	43	54	46.5	15	22.5	17.5	17.5	9	1.2
		1/4 Hp	300:1~375:1													
		1/2 Hp	80:1~240:1													
F3S45	TAF3S-45-2	2 Hp	5:1~60:1													
	TAF3S-45-3	3 Hp	5:1~30:1	13.5	42.5	110	15	n/a	n/a	n/a	16	20	17.5	17.5	9	1.4
		1/8 Hp	900:1~1200:1													
		1/4 Hp	450:1~750:1													
		1/2 Hp	300:1~375:1													
		1 Hp	80:1~240:1													
F3S50	TAF3S-50-2	3 Hp	40:1~60:1	136	44	140	15	n/a	n/a	n/a	15	20	17.5	17.5	9	2.1
F3S55	TAF3S-55-3	1/8 Hp	1500:1	146	70	160	18.5	n/a	n/a	n/a	18.5	28.5	20.5	20.5	12	3.6
		1/4 Hp	900:1~1200:1													
		1/2 Hp	450:1~600:1													
		1 Hp	300:1													
		2 Hp	80:1~240:1													
		3 Hp	80:1~120:1													

Material: SS400, Surface treatment: uni-chrome, Color: white

Tightening Torque

A torque arms is subjected to a rotation reaction torque. They must use materials and fasteners strong enough to endure extended normal operation as well as a starting/ braking and/or potential shock loading. Our standard parts are sized appropriately given the mating gearmotor or reducer.

When installing a reducer with a torque arm, tighten the bolt using a helical spring lock washer and plain washer. Proper tightening torques, are shown in the table.

Fig 3.2: Tightening Torque

Part Number	Bolt Size		Tightening Torque	
	Metric	Inch	N-m (kgf-m)	in-lb
TAF3S-20-2	M8	5/16-18	13 (1.3)	115
TAF3S-25-2	M8	5/16-18	13 (1.3)	115
TAF3S-25-3	M10	3/8-16	25 (2.6)	220
TAF3S-30-2	M10	3/8-16	25 (2.6)	220
TAF3S-30-3	M12	7/16-14	44 (4.5)	390
TAF3S-35-2	M12	7/16-14	44 (4.5)	390
TAF3S-35-3	M16	5/8-11	108 (11)	955
TAF3S-45-2	M16	5/8-11	108 (11)	955
TAF3S-45-3	M20	3/4-10	294 (30)	2600
TAF3S-50-2	M20	3/4-10	294 (30)	2600
TAF3S-55-3	M20	3/4-10	294 (30)	2600

Brother Rt-Angle Hollow Bore Mid Series Gearmotors & Reducers BORE OPTION DETAILS

Fig 3.7: How to Apply the Torque Arm Fixing Element

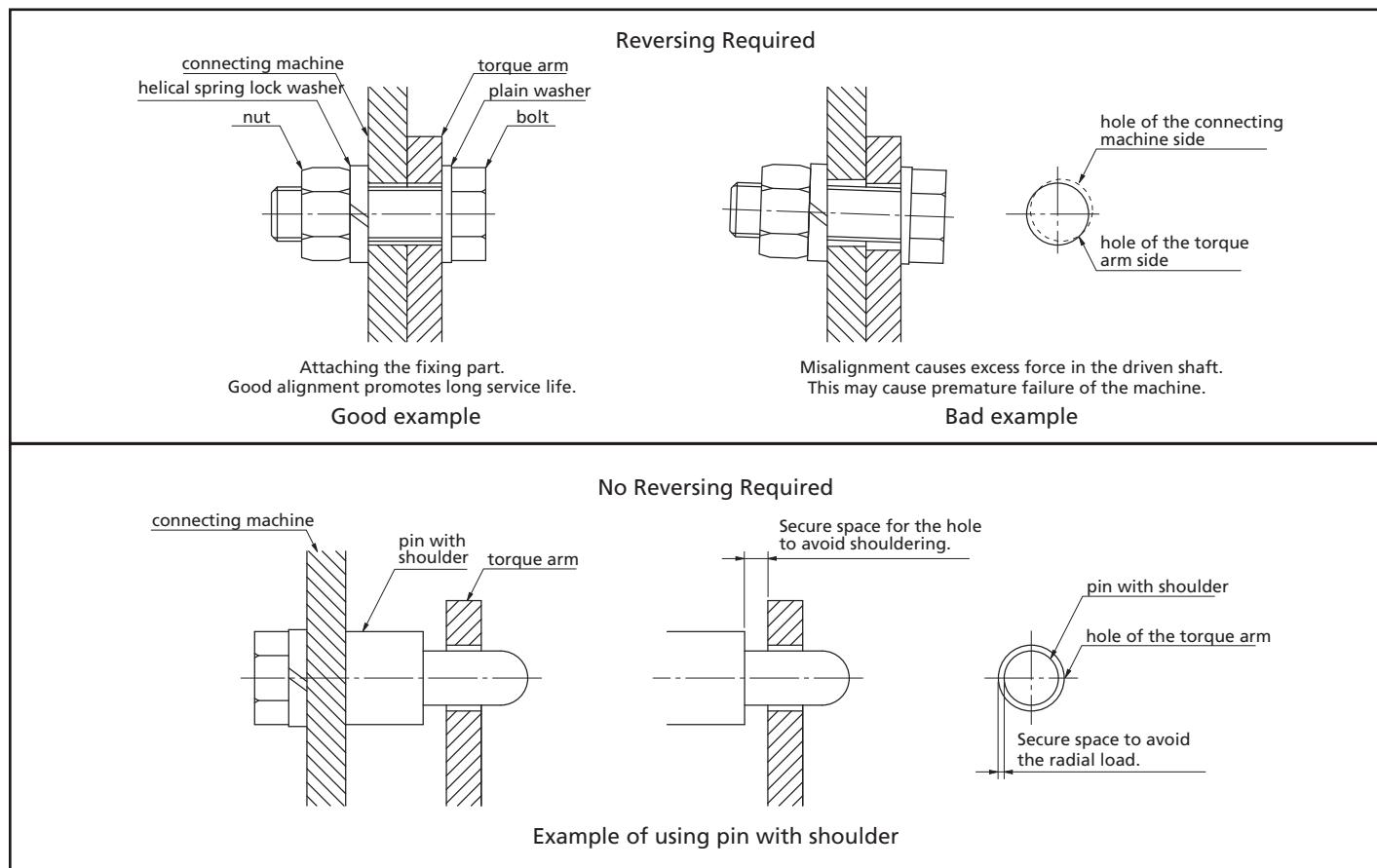
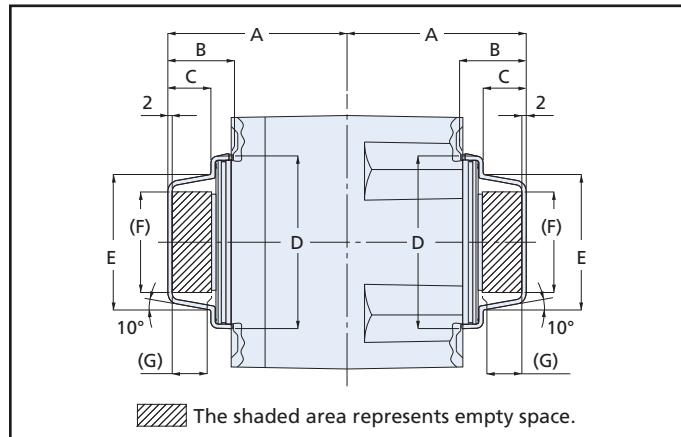


Fig 3.8: Safety Cap Dimensions



F3 S Safety Cap Dimensions

Frame	A	B	C	D	E	F	G
F3S20	64	25.5	15.7	57	40	26	14
F3S25	79	29.5	19.7	70	53	37.5	18
F3S30	82	19.5	19.7	79	62	46.5	18
F3S35	95	33.5	23.7	89	72	55	22
F3S45	108	33.5	23.7	104	87	70	22
F3S50	120	43	41	141	127.5	104	32
F3S55	143	43	41	141	127.5	104	32

Brother Rt-Angle Hollow Bore Mid Series Gearmotors & Reducers BORE OPTION DETAILS

Fig 3.9: Inserting the Shaft

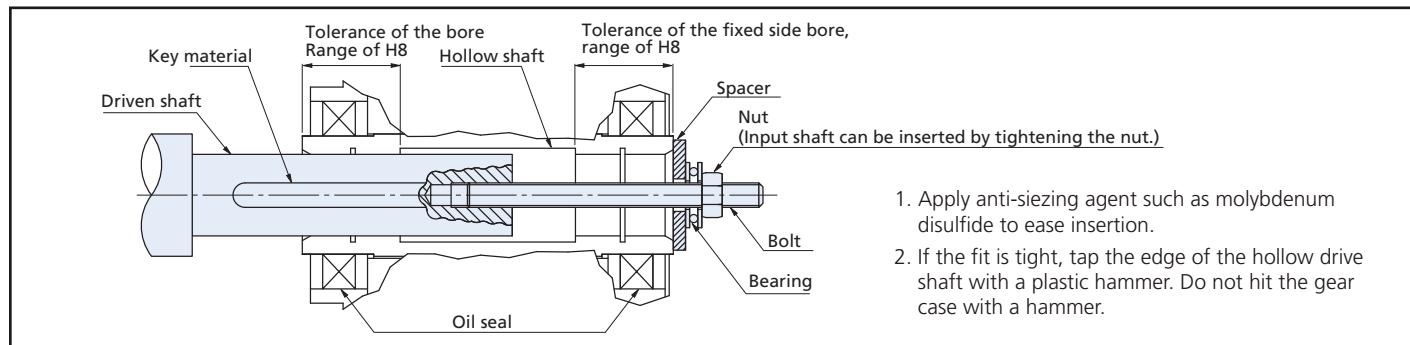
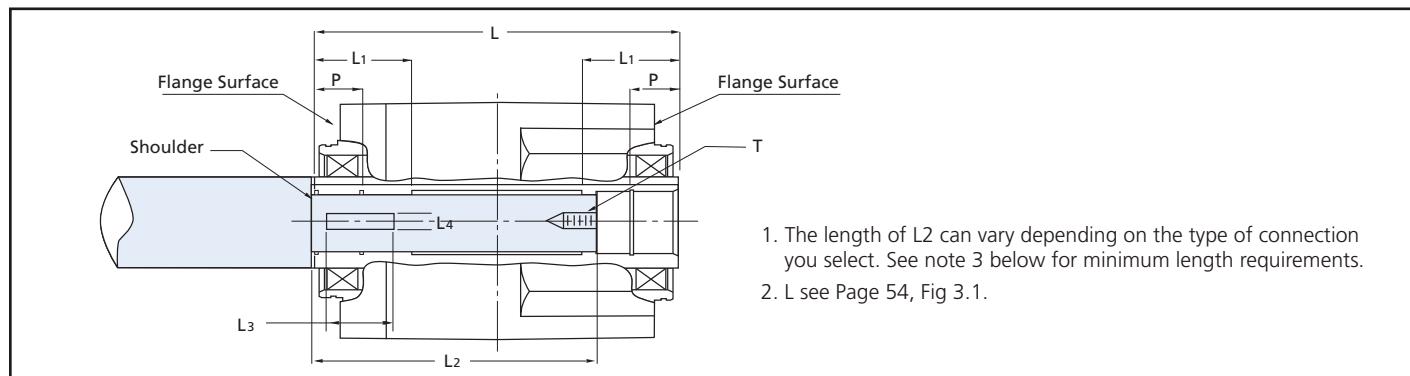


Fig 3.10: Recommended Dimensions of Shaft from the Shoulder



Note: The shaft is supplied by the OEM or User.

Bore Diameter (Inch)	Shaft (Inch Dimension)						
O.D. (in)	L1 (in)	L2 (in)	L3 (in)	L4 (in)	Key (in)	Tap T	
F3-20 0.7500	0.7500 in +0.0/-0.0008	0.945	3.125	1.500	0.1875	0.1875	1/4-20X0.50
F3-25 1.0000	1.0000 in +0.0/-0.0008	1.063	3.938	2.000	0.2500	0.2500	1/4-20X0.50
F3-30 1.2500	1.2500 in +0.0/-0.0008	1.063	4.000	3.375	0.2500	0.2500	5/16-18X0.63
F3-35 1.4375	1.4375 in +0.0/-0.0010	1.496	4.500	2.938	0.3750	0.3750	3/8-16X0.75
F3-45 1.6875	1.6875 in +0.0/-0.0010	1.969	5.375	3.375	0.3750	0.3750	3/8-16X0.75
F3-50 1.9375	1.9375 in +0.0/-0.0010	2.165	5.375	3.938	0.5000	0.5000	7/16-14X1.0
F3-55 2.0000	1.9375 in +0.0/-0.0010	1.063	7.125	4.000	0.5000	0.5000	7/16-14X1.0

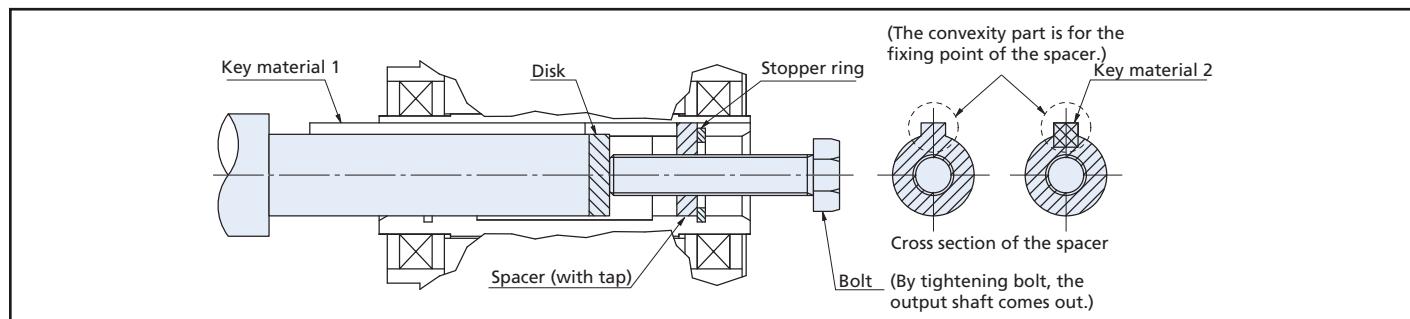
Bore Diameter (Inch)	Shaft (Inch Dimension)						
O.D. (in)	L1 (in)	L2 (in)	L3 (in)	L4 (in)	Key (in)	Tap T	
F3-20 20	20 h ₇	0.945	80	30	6	6	M6X12
F3-25 25	25 h ₇	1.063	100	37.5	8	8	M6X12
F3-30 30	30 h ₇	1.063	102	45	8	8	M8X16
F3-35 35	35 h ₇	1.496	117	52.5	10	10	M10X20
F3-45 45	45 h ₇	1.969	137	67.5	14	14	M10X20
F3-50 50	50 h ₇	2.165	138	75	14	14	M12X24
F3-55 55	55 h ₇	1.063	182	82.5	16	16	M12X24

Tolerances are for low impact or uniform loading. For high impact loading or high radial loading, use tighter tolerances.

Designing your Own Shaft

- The usable key length should be greater than 1.5X the diameter of the driven shaft.
- The Key should be engaged with at least half of the length L1. See Fig 3.1 for the dimension L.
- The minimum length of shaft engaged inside the bore is approximately $(L - L1) + ((L1-P)/2)$. See Fig 3.1 for details.

Fig 3.11: How to Remove the Shaft



* The spacer, disk, belt, stopper ring are not supplied by Brother.

Brother Rt-Angle Hollow Bore Mid Series Gearmotors & Reducers BORE OPTION DETAILS

Fig 3.12A Securing the Shaft with a Shoulder

Fixing by Spacer and Stopper Ring

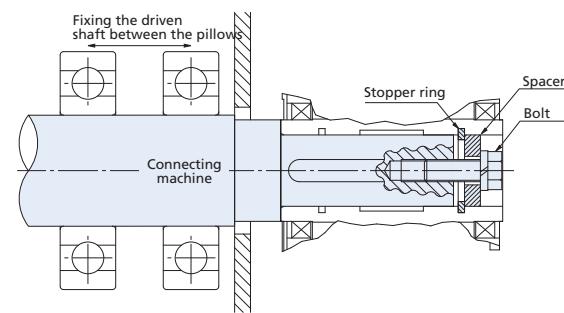


Fig 3.12B Securing the Shaft with a Shoulder

Fixing by End Plate

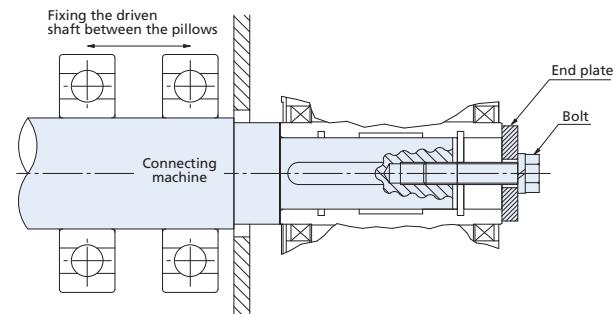


Fig 3.13A Securing the Shaft without a Shoulder

Fixing by Spacer and Stopper Ring

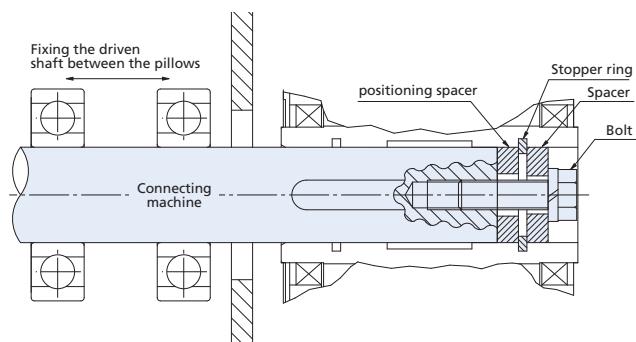


Fig 3.13B Securing the Shaft without a Shoulder

Fixing by End Plate

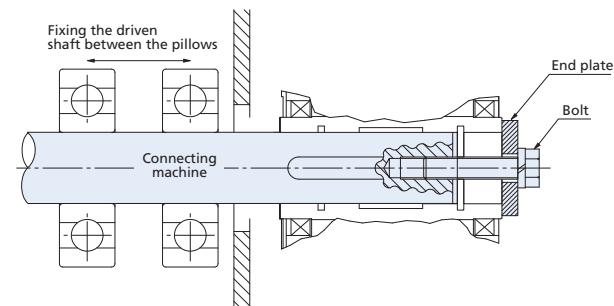


Fig 3.14A: Fixing Element Parts; Inch

Bore (mm)	Bolt		O.D. (in)	I.D. (in)	T (in)
	Internal	External			
0.7500	1/4-20X0.75	1/4-20X1.25	0.73	0.28	0.125
1.0000	1/4-20X0.75	1/4-20X1.25	0.98	0.28	0.125
1.2500	5/16-18X0.75	5/16-18X1.5	1.23	0.35	0.188
1.4375	3/8-16X1.25	3/8-16X1.75	1.42	0.43	0.188
1.6875	3/8-16X1.25	3/8-16X2	1.67	0.43	0.250
1.9375	7/16-14X1.25	7/16-14X2.5	1.92	0.51	0.250
2.0000	7/16-14X1.25	7/16-14X2.5	1.98	0.51	0.250

Fig 3.14B: Fixing Element Parts; Metric

Bore (mm)	Bolt		O.D. (in)	I.D. (in)	T (in)
	Internal	External			
20	M6X16	M6X30	19.5	7	3
25	M6X16	M6X30	24.5	7	4
30	M8X20	M8X40	29.5	9	5
35	M10X25	M10X40	34.5	11	5
45	M10X25	M10X50	44.5	11	5
50	M12X30	M12X60	49.5	13	6
55	M12X30	M12X60	54.5	13	6

Why Use A Hypoid/Helical Hollow Bore

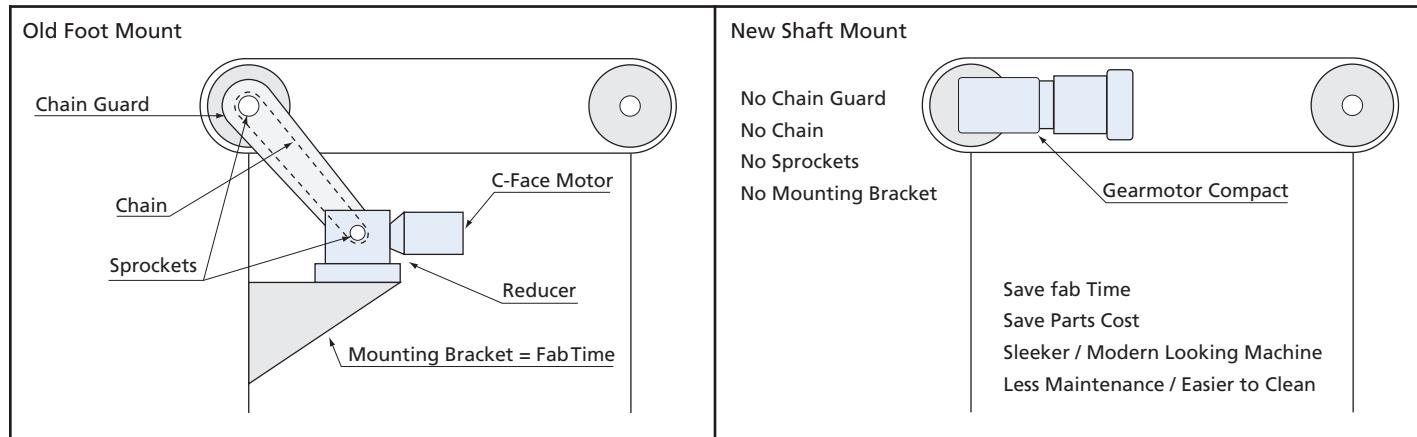
Flange Mounted

Positive Aspects

- Direct attachment to the machine is possible.
- Space is saved.
- Few parts are required.
- Base mounts, chains, sprockets, and chain guarding are not required.
- Easy to sanitize in food service environment (IP-65 Type).

Negative Aspects

- Alignment of the reducer bearings with the machine bearing is required.
- (4) bolts are needed to securing the reducer flange to the mounting surface.
- Changing the reducer may be more difficult.



Torque Arm Mounted

Positive Aspects

- Easy alignment with the connecting machine.
- Only one fixing point is needed to transmit the torque.
- Changing the reducer is simpler.
- Easy to sanitize in food service environment (IP-65 Type).

Negative Aspects

- Torque arm is needed.
- Space for attaching torque arm is needed.

Compared to a Worm

Positive Aspects

- Service Life is greater than 2X longer = superior cost of ownership.
- HRH/H is more energy efficient = lower operating cost.
- HRH/H is lighter and more compact = easier to mount.
- HRH/H is symmetric = mounting is simple and flexible.
- HRH/H operating temperature is lower = longer life.
- No breather hole is required = easier to mount, no external ingress point.
- Mounting is 100% flexible, any angle any direction = easier to apply.

Negative Aspects

- HRH/H is not self locking. If backdrive is not acceptable, a brake is required.

**BROTHER INTERNATIONAL CORPORATION
GEARMOTOR/OEM DIVISION****General**

These standard Terms and Conditions of Sale shall be incorporated into any contract between Purchaser and Brother International Corporation (hereafter Brother) and shall apply to all purchase orders issued by Purchaser. Unless specifically provided herein or in a separate written agreement duly executed by Brother, the quotation and this form constitute the entire agreement between Brother and Purchaser and no other terms or conditions oral or written shall be of any effect. All orders, whether placed pursuant to a quotation or not, are accepted only upon express condition that purchaser agrees to the Terms and Conditions as specified herein.

Price and Delivery Terms

Price and delivery terms are F.O.B. Brothers nearest U.S. facility and do not include sales, use, excise, or any other taxes. Our responsibility ceases when delivery is made to the transportation company and any claims for loss or damage in transit must be handled by the Purchaser with the carrier.

Packing

No charge is made for standard boxing for domestic shipments. Purchaser will be quoted and charged separately for export or special packing requirements.

Payment Terms

To Purchasers with credit standing satisfactory to Brother, terms of payment are cash in full, net 30 days. If at any time Brother deems that by reason of financial condition of the Purchaser or otherwise, the continuance of production or shipments is not justified, Brother may revoke its extension of credit, enforce any security interest(s) created hereby on all goods furnished by Brother to the Purchaser and otherwise secure itself as to Purchasers performance of its obligation.

Cancellation

Changes, suspension or cancellation of any order by Purchaser may be made only upon written approval of an authorized officer of Brother.

Warranty

All Brother gearmotor product are warranted against defects in materials and workmanship for a period of 2 years from the date of manufacture. This constitutes Brother's only warranty in connection with this sale, and is in lieu of all other warranties expressed or implied, written or oral. There are no implied warranties of merchantability or fitness for a particular purpose that apply to this sale. If performance guarantees are requested, they should be requested in writing. Full consideration will be given to such requests when complete details of the proposed application are included.

Limitation of Remedy

Brother will repair or replace, at brother's option, F.O.B. Brother's factory, freight prepaid, any Brother gearmotor proved defective in materials or workmanship if immediate written notice of claim is made to Brother by Purchaser within 2 years from the date of

manufacture. It is agreed that such repair or replacement is the exclusive remedy available from Brother. Under no circumstances shall Brother be liable to anyone for any special, incidental or consequential damages, whether the result of negligence or otherwise.

Warranty Exclusions

The Warranty of Brother gearmotor products does not cover and Brother makes no warranty with respect to:

1. Failures not reported in writing to Brother within the warranty period of 2 years after the date of manufacture.
2. Failures or damages due to miss-application, abuse, improper installation or abnormal conditions of temperature, humidity, dirt or corrosive matter.
3. Failures due to operation, either intentional or otherwise, above rated capacities or in an otherwise improper manner.
4. Product which has in any way been tampered with or altered by anyone other than an authorized representative of Brother.
5. Expenses incurred by the Purchaser in an attempt to repair or rework an allegedly defective product.
6. Product damaged in shipment or otherwise without the fault of Brother.

Returns

No product will be accepted for return unless authorized in writing with a returned merchandise authorization (RMA) number assigned. Any returned goods must be returned with transportation charges prepaid.

Regulatory Laws and/or Standards

It is the Purchaser's obligation to install and operate all Brother gearmotor products in conformance with all applicable national or local laws and safety codes.

Patents

Brother represents that its gearmotors are designed and manufactured such that they do not infringe on any United States Patent(s), and that Brother will, at its expense, defend any claim charging such infringement and will save Purchaser harmless from any adverse judgments resulting there from. Purchaser agrees to give Brother, prompt written notice of any claim of infringement and to turn over to Brother the complete control of any litigation involving such claims including the right to settle such claims. This indemnity does not apply to Products which are incorporated by the Purchaser into Products which are changed to infringe a Patent or to Product which is used by Purchaser in performance of a method or process which is charged to infringe a Patent.

Law

These Standard terms and Conditions of Sale shall be interpreted in accordance with the Laws of the State of New Jersey.

Severability

If any of the terms and Conditions shown here are determined to be invalid, illegal, or unenforceable the remainder of these Terms and Conditions shall remain in full force and effect.

brother

at your side

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Rev 1.10.17